

Wirkungen $\longleftrightarrow$ Feldern

$$\vec{R} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

Mass m

$$m \ddot{\vec{R}} = \vec{F}(\vec{R}, t) \rightarrow \vec{R}(t)$$

$$\vec{F} = q \cdot \vec{E}(\vec{R}, t) + q \cdot \vec{v} \times \vec{B}(\vec{R}, t)$$

q -el. Ladung

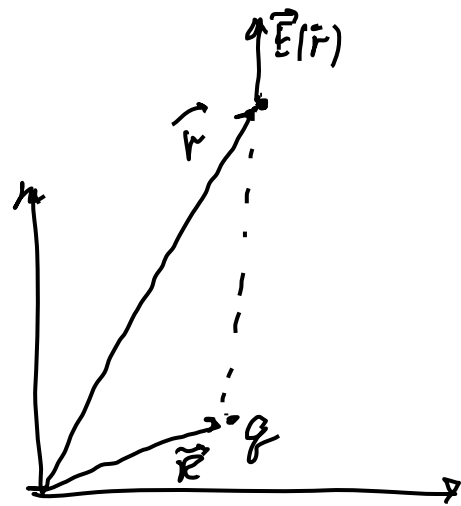
$$\begin{aligned} \vec{E}(\vec{R}, t) \\ \vec{B}(\vec{R}, t) \end{aligned}$$

$$\vec{E} = \begin{pmatrix} E_x(\vec{r}, t) \\ E_y(\vec{r}, t) \\ E_z(\vec{r}, t) \end{pmatrix}$$

$$E_x = E_x(\vec{r}, t) = E_x(x, y, z, t)$$

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon} \cdot \frac{q(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

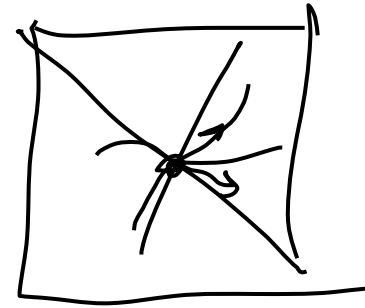
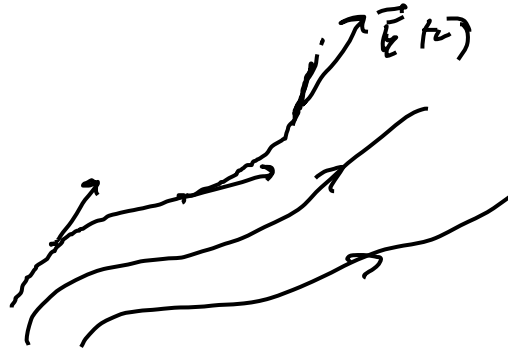
$$\begin{cases} \nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \\ \nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \end{cases}$$



Vektorfelder

$$\vec{E}(\vec{r}) = \{ E_i(\vec{r}) \}, \quad i = x, y, z$$

$$E_i(x, y, z)$$



Partielle Ableitung

$$f(x, y, z)$$

$$\frac{\partial f}{\partial x} = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x, y, z) - f(x, y, z)}{\Delta x}$$

$$\frac{\partial}{\partial x}(xyz) = yz, \quad \frac{\partial}{\partial y}(xyz) = xz$$

$$f(x, y, z) : \quad \frac{\partial f}{\partial x}, \quad \frac{\partial f}{\partial y}, \quad \frac{\partial f}{\partial z}.$$

$$\nabla = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix}$$

$$\begin{cases} \nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \\ \nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \end{cases}$$

$$\nabla f(x, y, z) = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} f(x, y, z) = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ \frac{\partial f}{\partial z} \end{pmatrix}$$

$$f = x y z : \quad \nabla f = \begin{pmatrix} y z \\ x z \\ x y \end{pmatrix}$$

$$KM : \quad \vec{F}(\vec{r}) = -\nabla V(\vec{r}) = -\text{grad } V(\vec{r})$$

Skalarprodukt

$$\vec{a} = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix}$$

$$(\vec{a} \cdot \vec{b}) = a_x b_x + a_y b_y + a_z b_z = \sum_{i=1}^3 a_i b_i = (\vec{b} \cdot \vec{a})$$

$$\vec{a} = \nabla, \quad \vec{b} = \vec{E}(\vec{r})$$

$$\nabla \cdot \vec{E} = \nabla_x E_x + \nabla_y E_y + \nabla_z E_z = \partial_x E_x + \partial_y E_y + \partial_z E_z = \rho(x, y, z) - \text{Skalar}$$

$$\vec{E} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \quad \nabla \cdot \vec{E} = \partial_x x + \partial_y y + \partial_z z = 3.$$

$$\boxed{\nabla \cdot \vec{E} = \text{div } \vec{E}(\vec{r})}$$

$$\nabla \cdot \vec{E} \neq \vec{E} \cdot \nabla$$

$$\vec{E} \cdot \nabla = E_x \partial_x + E_y \partial_y + E_z \partial_z$$

vektorenprodukt

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{e}_x & \hat{e}_y & \hat{e}_z \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix} = \hat{e}_x (a_y b_z - a_z b_y) +$$

$$\hat{e}_y (a_z b_x - a_x b_z) + \hat{e}_z (a_x b_y - a_y b_x)$$

$$\hat{e}_x = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad \hat{e}_y = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad \hat{e}_z = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Levi-Civita-Tensor ϵ_{ijk} , $i = \overline{1,3}$ $j = \overline{1,3}$ $k = \overline{1,3}$

$$\epsilon_{123} = 1$$

$$\epsilon_{ijk} = \epsilon_{kij} = \epsilon_{jki} \Rightarrow \epsilon_{123} = \epsilon_{312} = \epsilon_{231} = 1$$

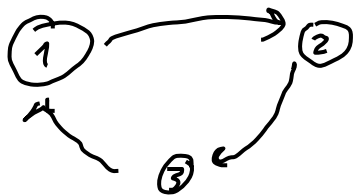
$$\epsilon_{ijk} = -\epsilon_{jik}$$

$$\epsilon_{123} = -\epsilon_{213}$$

$$\epsilon_{213} = -1 =$$

$$= \epsilon_{321} = \epsilon_{132}$$

$$\epsilon_{iik} = 0 : \epsilon_{112} = \epsilon_{122} = \dots = 0$$



zyklisch

