Minkowski space has $\mathbb{R}^{\lambda}_{m_{k}} = 0$ so it will be true in any representation of flat space. For example in spherical coordinates: $ds^{\perp} = ds^{\perp} + \gamma^{2} \left(d \overline{\partial}^{\perp} + \cos \overline{\partial} d \varphi^{2} \right) - Jt^{2}$ dst= dxtdx qpu (p=t,r,o,q) $\begin{array}{ccc}
 & & & \lambda \\
 & & \mu \nu \neq 0 \\
 & & forces
\end{array}$ because of the pseudo
 forces but $R^{+} = 6$ because it is a tensor Is the opposite also true? If $R^{\lambda}_{\mu\nu k} = 0$ does this mean that the space is (locally) equivalent to Minkowski space? Actually, if $R^{\lambda}_{\mu\nu\kappa} = 0$ and the signature of the metric is the one of Minkowski, this is in fact true.

Let's start in an arbitrary point X.

These matrices can be enhanced to fields via parallel transport (remember $R^{\lambda}_{\mu\nu} = 0$)

$$\nabla_k d^k (x) = \partial_k l^{\prime \prime} + \Gamma^{\prime \prime} k v d^{\prime} z = 0$$

(notice that alpha is not a GR index, it just enumerates the different vectors that achieve the Minkowski metric)

Then one has:

 $\mathcal{O}_{k}\left(\begin{array}{c}g^{\mu}d^{\mu}d^{\nu}\\g^{\mu}\end{array}\right)=0$

Ab scalous in GR

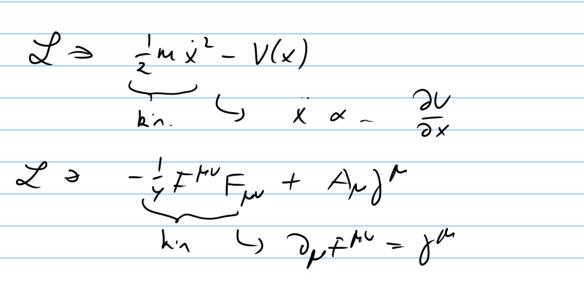
=) Jr. d^Md^V = Map everywlere in the heighborhood

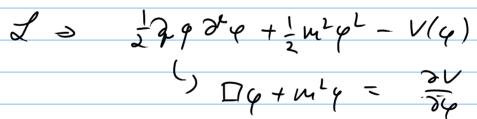
beause Dd =0 Dg =0



In order to describe the dynamics of the metric, we need a 'kinetic term' for the metric.

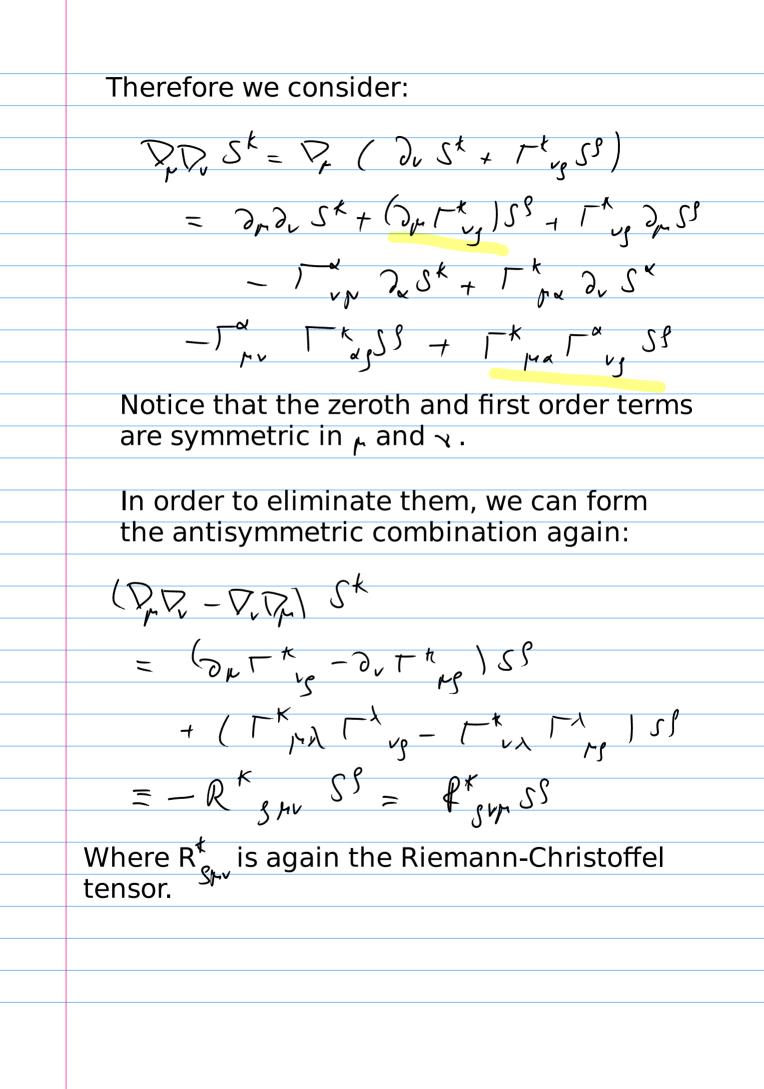
Usually, kinetic terms contain second derivatives or two simple derivatives, e.g.





Hence we would like to construct a term involving second derivatives of the metric in a covariant way:

 $\nabla \Rightarrow 7.4 \Gamma \Gamma = g \frac{\partial g}{\partial f}$ $O(\Gamma^2)$, $O(\partial\Gamma) \propto \frac{\partial^2 g}{\partial r^2}$, $(\frac{\partial g}{\partial r})$



Comments:

Notice that since $R^{h}_{\nu\lambda\kappa}$ is a tensor, it cannot be made to vanish by a coordinate transformation.

$$g_{\mu\nu}(y) = g_{0} \mu\nu(y) + (y - x^{\lambda}) \partial_{\lambda} g_{0}(x) +$$

2(yk - 1/1/ - x) 2, 2, gliput -

In every point, g0 can be made the Minkowski metric and g0 can be transformed away, but the second derivatives can only put partially in a more convenient form, because these are the degrees of freedom that enter the Riemann tensor, and it cannot be be removed fully (if the space is non-flat).

Notice that the construction of R via the commutator of the covariant derivative does not resort to parallel transport, S^{λ} is just any vector/field.

Generalizations:

So we have seen that

This can be generalized for the commutator acting on different tensor structures:

$$(\mathcal{D}_{\mu}\nabla_{\nu}-\mathcal{D}_{\mu}\nabla_{\mu}) e = 0$$

For a covariant vector one finds:

$$(\overline{P_{A}P_{V}} - \overline{P_{V}P_{V}})S_{\lambda} = +R^{S}_{\lambda \mu \nu}S_{S}$$

A similar formula holds for any tensor, e.g.

$$(D_{\mu}O_{\nu} - D_{\nu}D_{\mu})T^{\lambda}_{\kappa} = -R^{\lambda}_{sm}T^{s}_{\kappa}$$
$$+ R^{s}_{\kappa\mu\nu}T^{\lambda}_{\rho}$$

Symmetries:

In order to study the symmetries under exchange of indices one has to construct the fully covariant form:

R_{xkm} = gre R^gkm

The fully covariant form can be evaluated to be:

The following properties are then more evident:

A) symmetry:
$$R_{\chi_{\mu}\nu\kappa} = R_{\nu\kappa\lambda_{\mu}}$$

(12 -1 34)

B) antisymmetry:
$$R_{\lambda\mu\nu\kappa} = -R_{\lambda\lambda\nu\kappa} = -R_{\lambda\mu\kappa\nu}$$

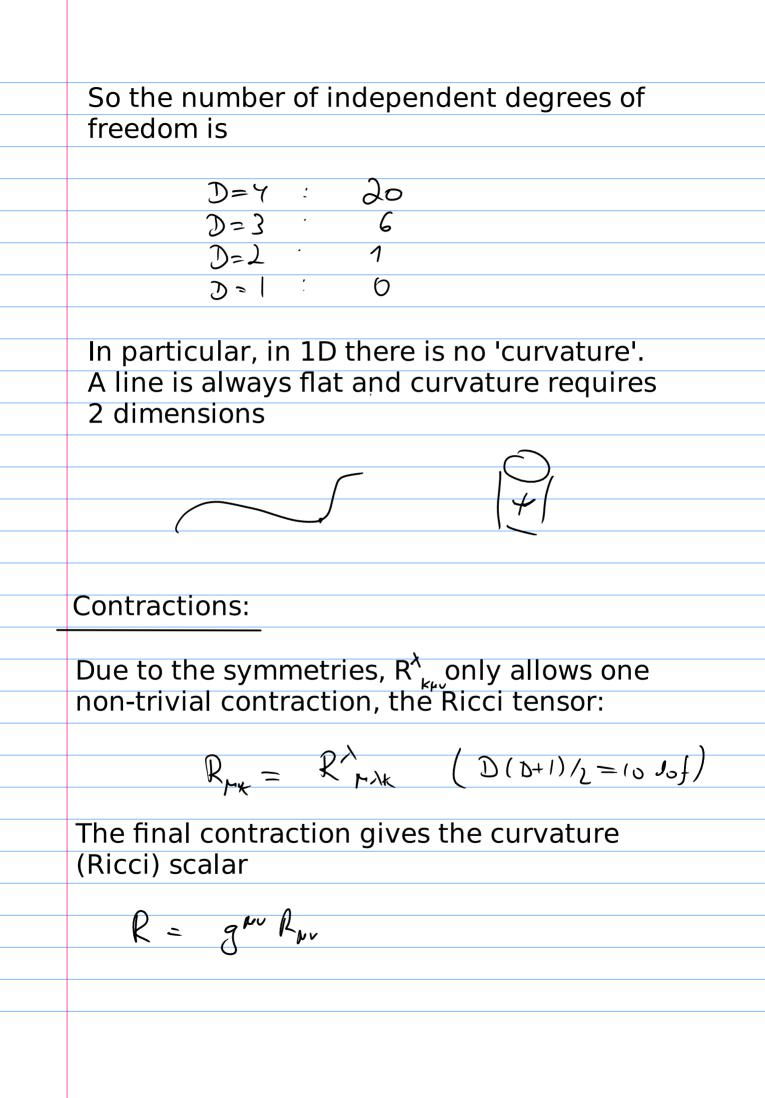
(s) $(+)$; $(-) \leftrightarrow (2)$
= + $R_{\mu\lambda\kappa\nu}$

C) cyclicity:

(234)

In general this tensor would have $D^4 \approx 256$ arbitrary entries.

If all the symmetries are imposed, one ends up with



Counting the degrees of freedom suggests that in 2D, the Riemann tensor might be expressed in terms of the Ricci scalar! (both have 1 d.o.f.)

RAKEN = - (gxpg+v-gxg+p)R