

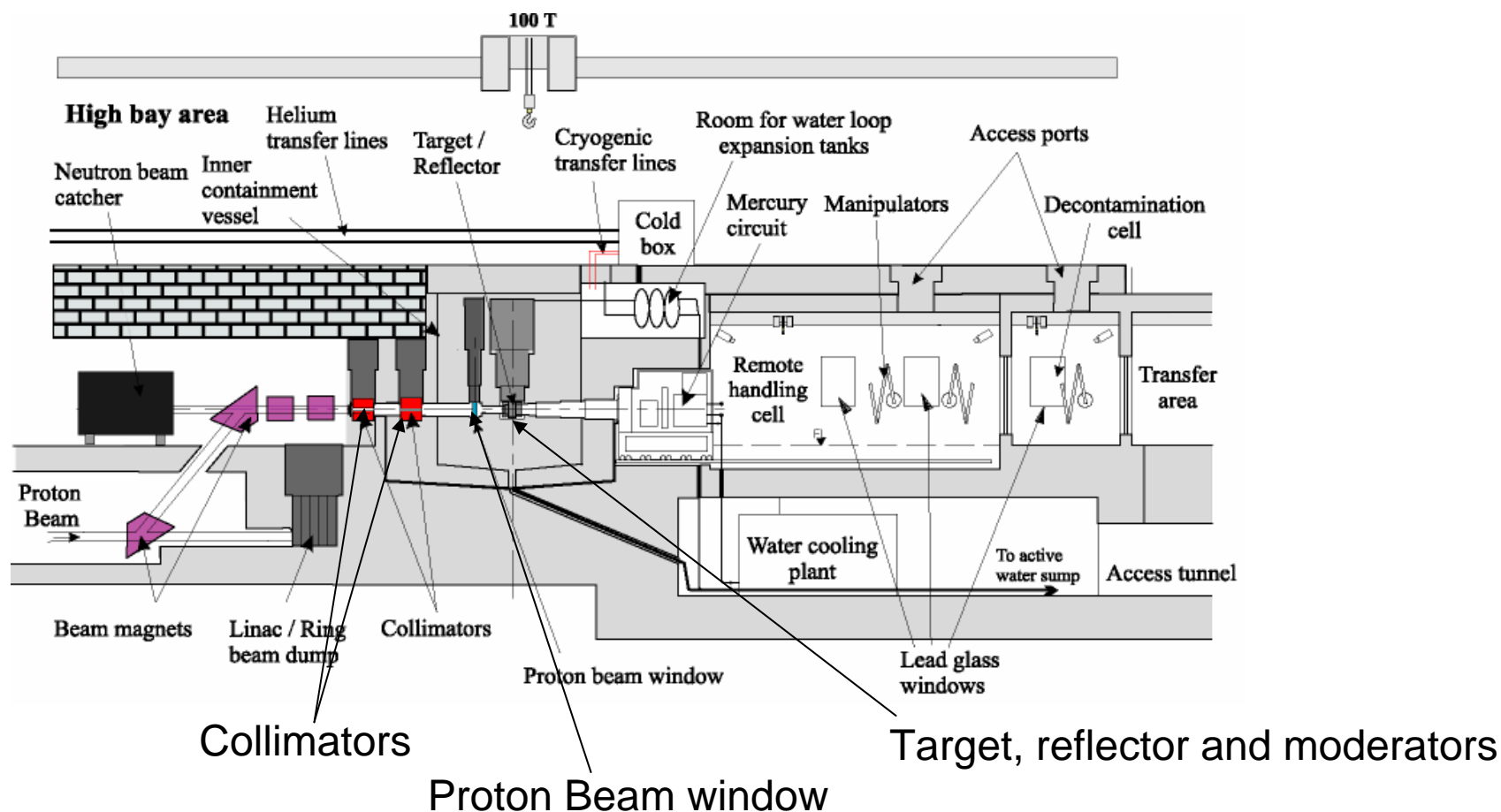


# Experience of Remote Handling of a Proton Beam Target

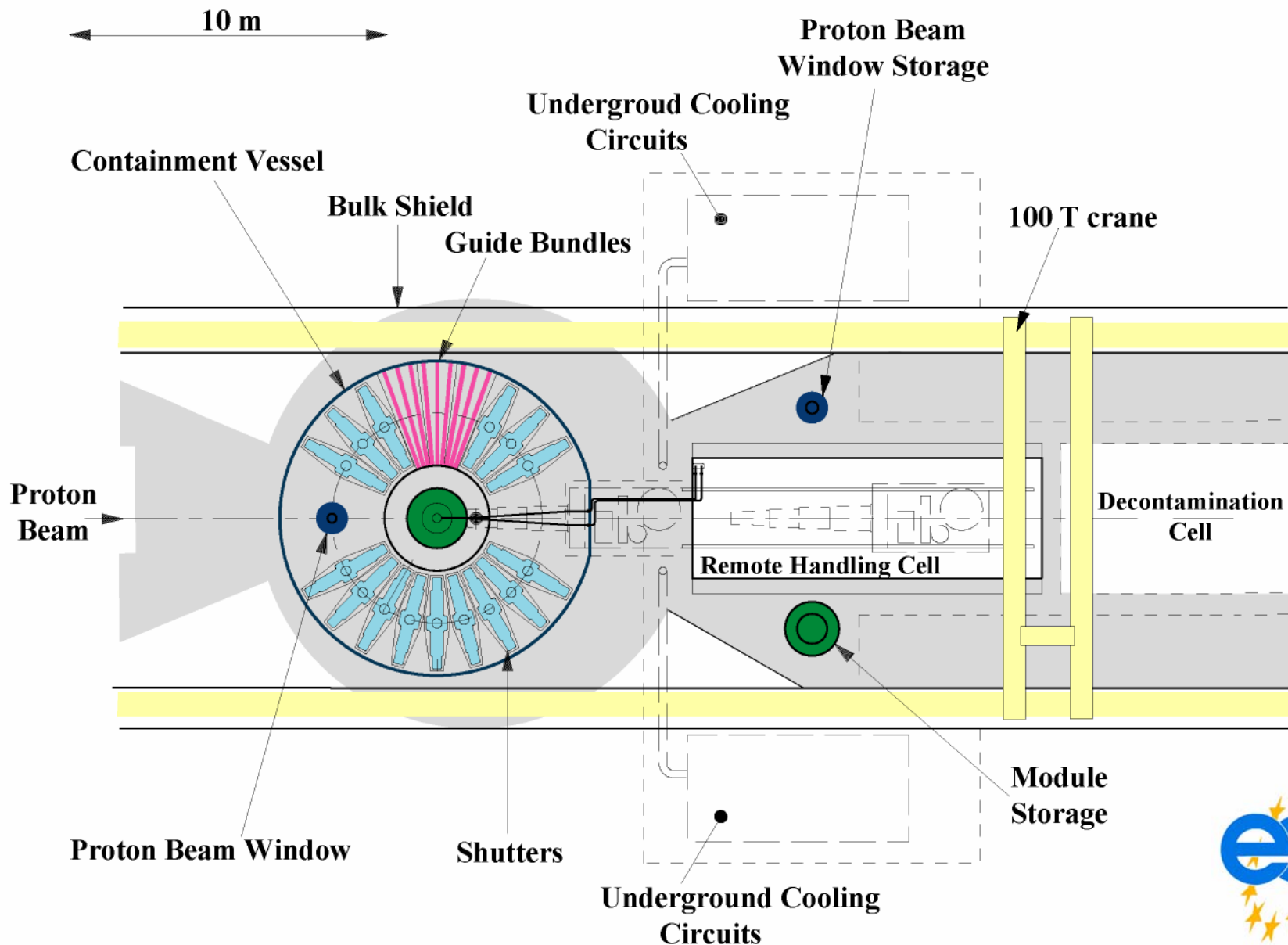
Tim Broome, ISIS Facility

- Remote handling requirements for a spallation neutron source
- Guiding principles
- Handling concepts at existing sources and sources under construction
- Simple solutions
- Complex solutions
- Some technical details
- Summary

- Complex assemblies with many components requiring regular replacement



# CCLRC Remote Handling at Spallation Sources

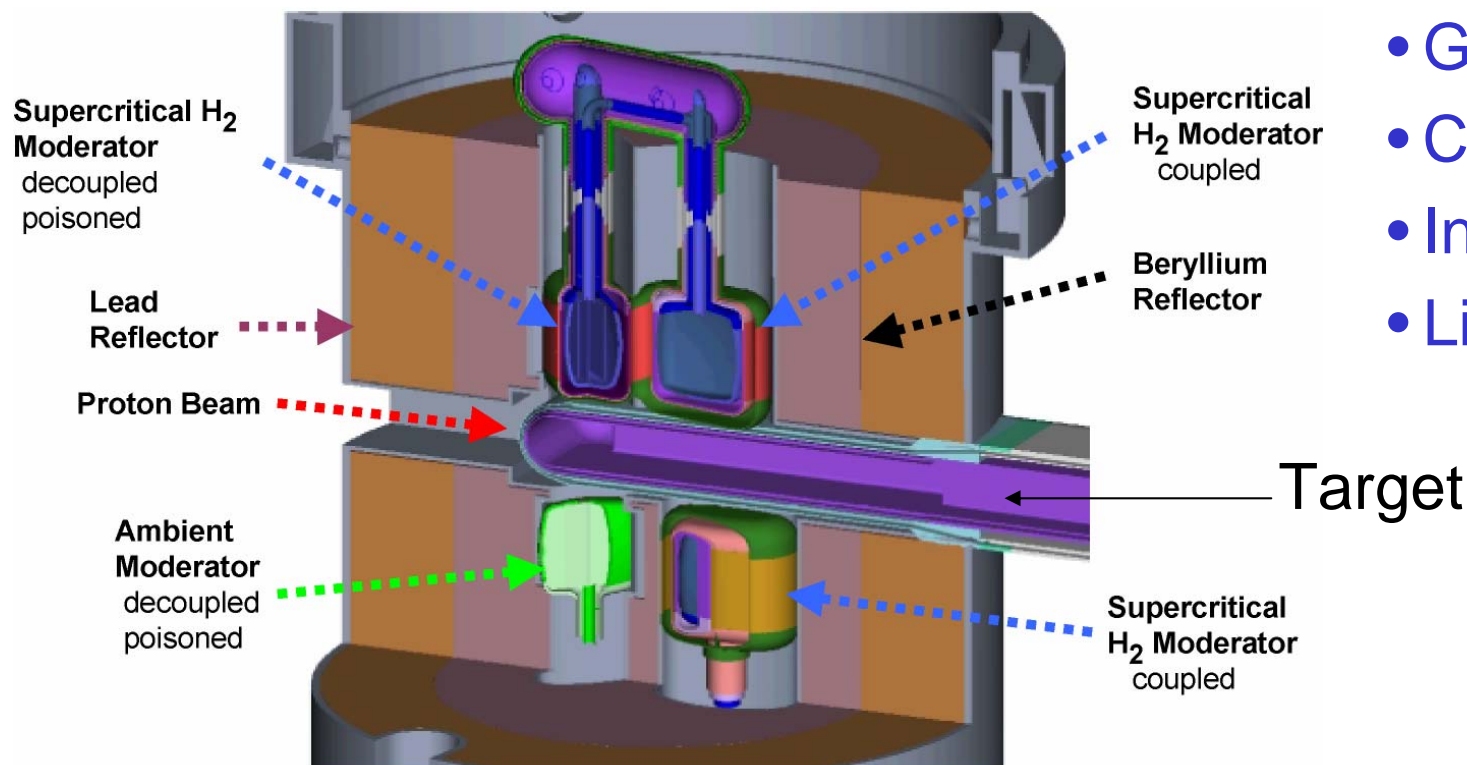




- Complex assemblies with many components requiring regular replacement

## Services Include:

- Water
- Gases
- Cryogenics
- Instrumentation
- Liquid metals



- All components that have a **limited lifetime** must be exchangeable within a **reasonable time**. (Within natural scheduled shutdown periods.)
- All components that can be designed for facility life must still be exchangeable as long as chance of failure theoretically exists; longer shut down time is acceptable.
- Allow either complex repair inside the target station or limit handling to exchange of pre-manufactured modules.
- Non-exchangeable components should be limited to carefully justified cases.
- These considerations will determine the overall design of the handling facilities

Handling **requirements** on every component have to be considered on a **case-by-case basis**. Issues to be considered during the conceptual and detailed design of a component as well as its direct environment are:

- Expected **lifetime** of the component and therefore frequency of handling.
- Expected **activation** of the component to be handled and its environment.
- Expected **contamination** of the component to be handled and its environment. Size and weight of component to be handled.
- **Complexity** of geometric arrangement of the component and its environment.
- **Handling areas**.

In most cases the **basic driver is the expected lifetime** or end of life mode of the addressed component.

- Proton Beam Power

- LANSCE 100 kW solid target  
Vertical handling
- ISIS (RAL) 160 kW solid target  
Horizontal handling
- SINQ (PSI) 1000 kW solid target  
Vertical handling
- SNS (ORNL) 2000 kW mercury target  
Horizontal Handling
- JSNS (JAERI) 1000 kW mercury target  
Horizontal Handling

## Typical Heat loads

Mean power density  
100-200 kW/l

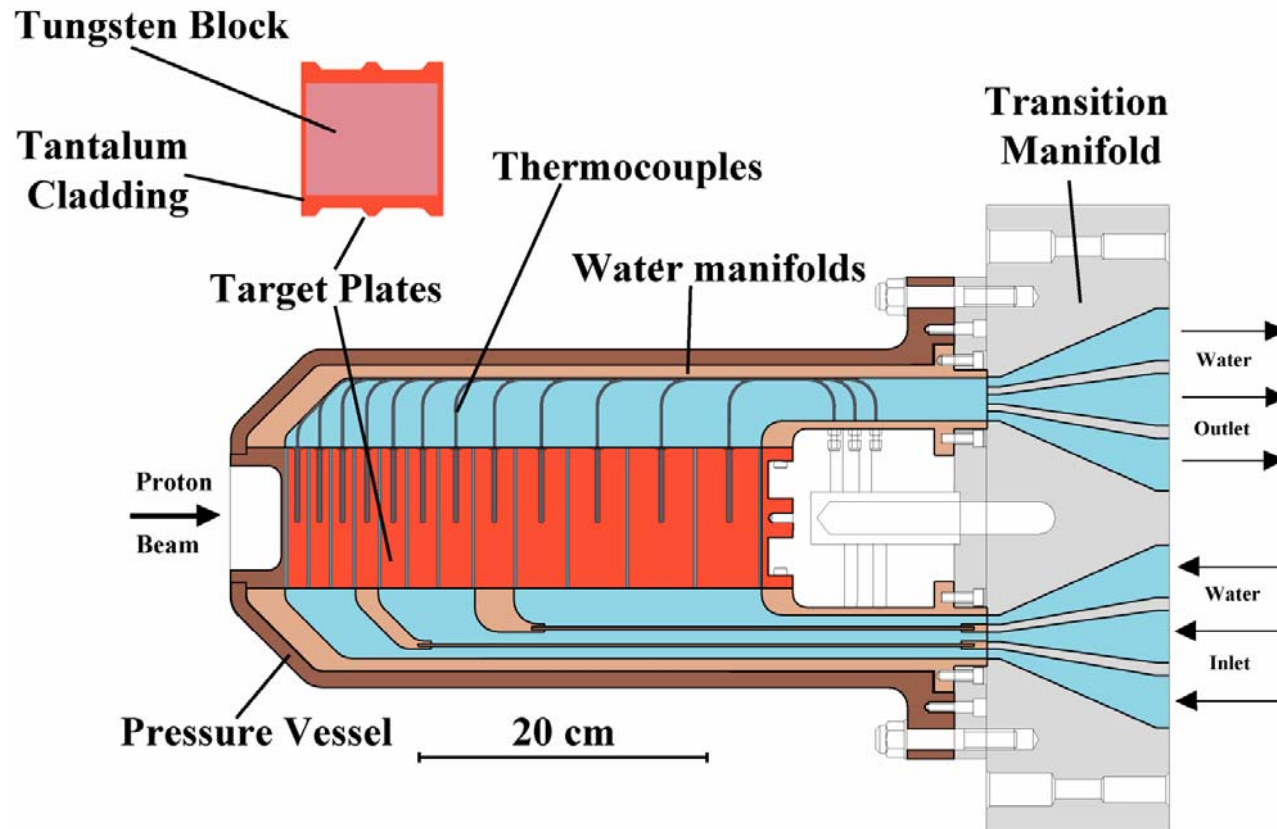
Peak Power density  
0.5-2 MW/l

(Small when compared  
to the positron target.)

- Full remote Handling is essential

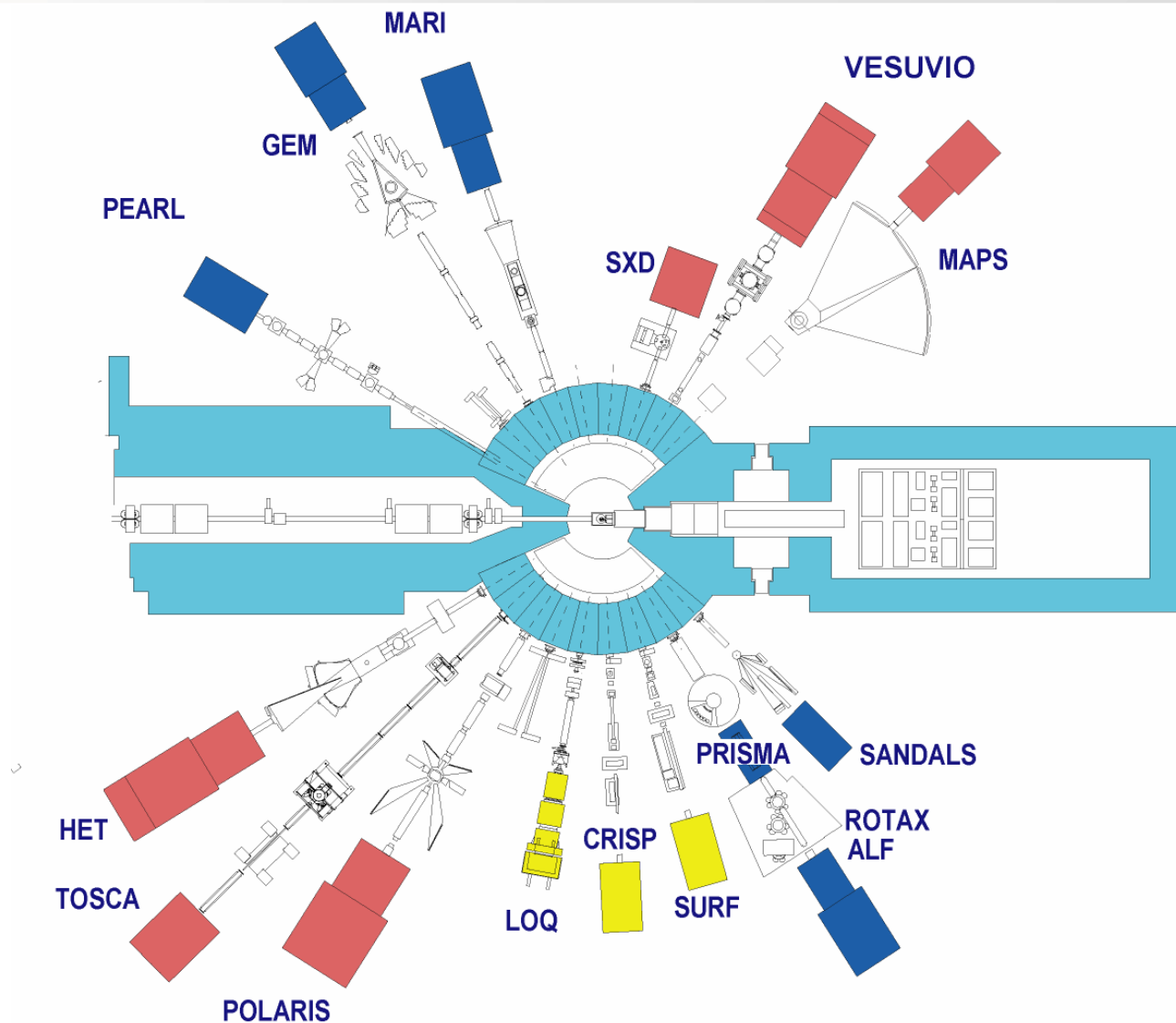


# CCLRC Spallation Source Targets



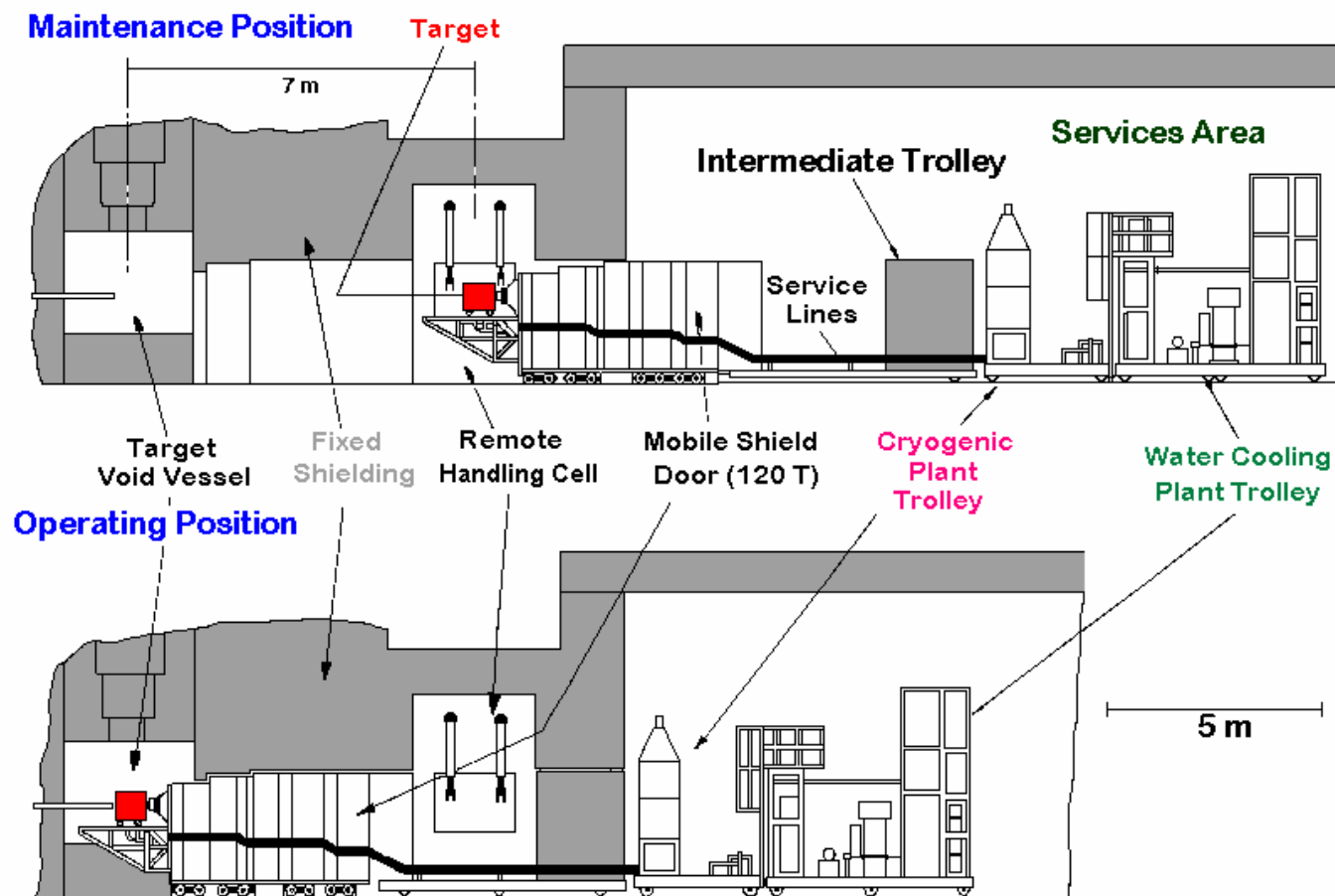
The ISIS Neutron Production Target

# Alternative Concepts (1) - Horizontal



The ISIS Target Station

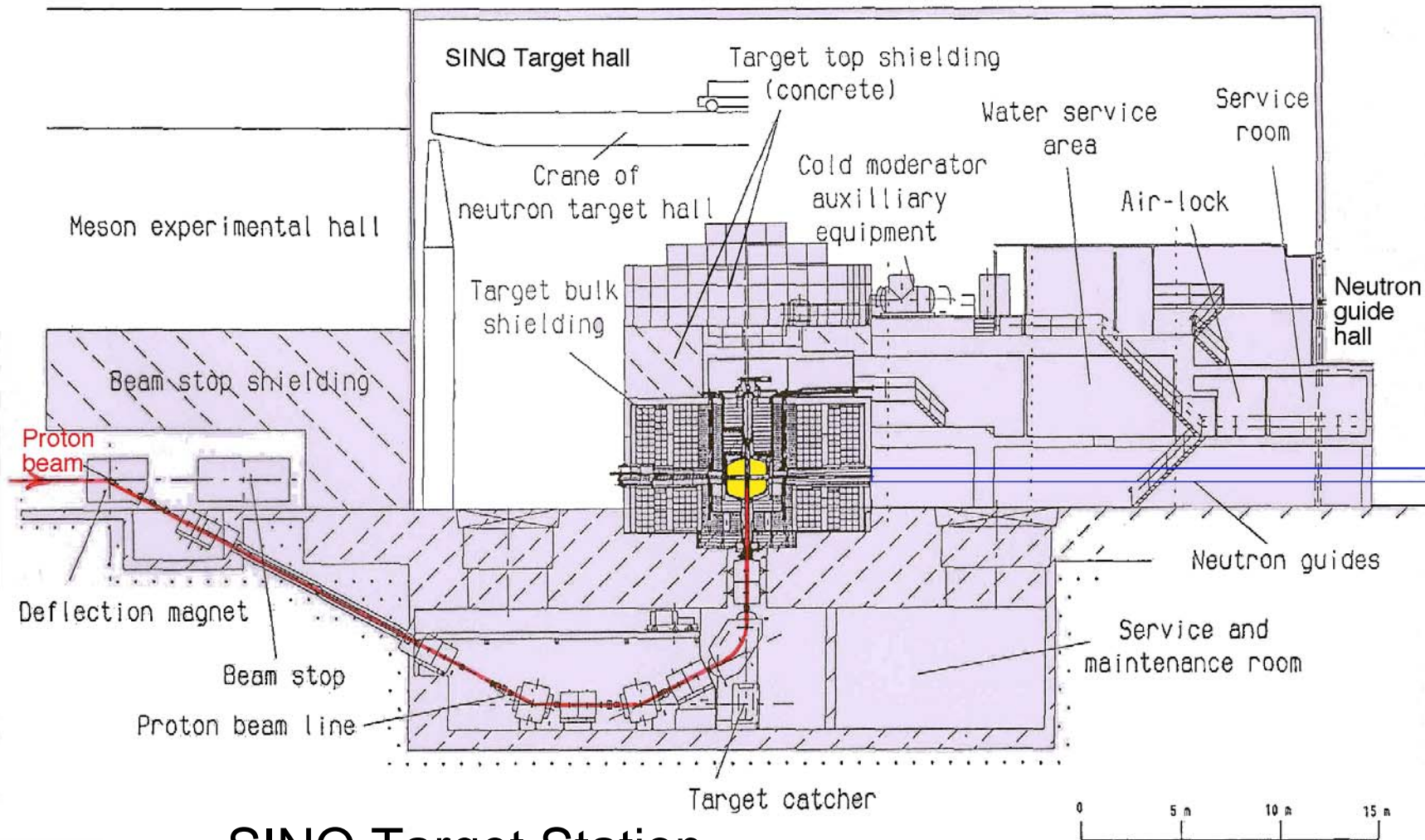
# Alternative Concepts (1) - Horizontal



Services remain connected, target moved to an integral remote handling cell for replacement.



# CCLRC Alternative Concepts (2) - Vertical



SINQ Target Station

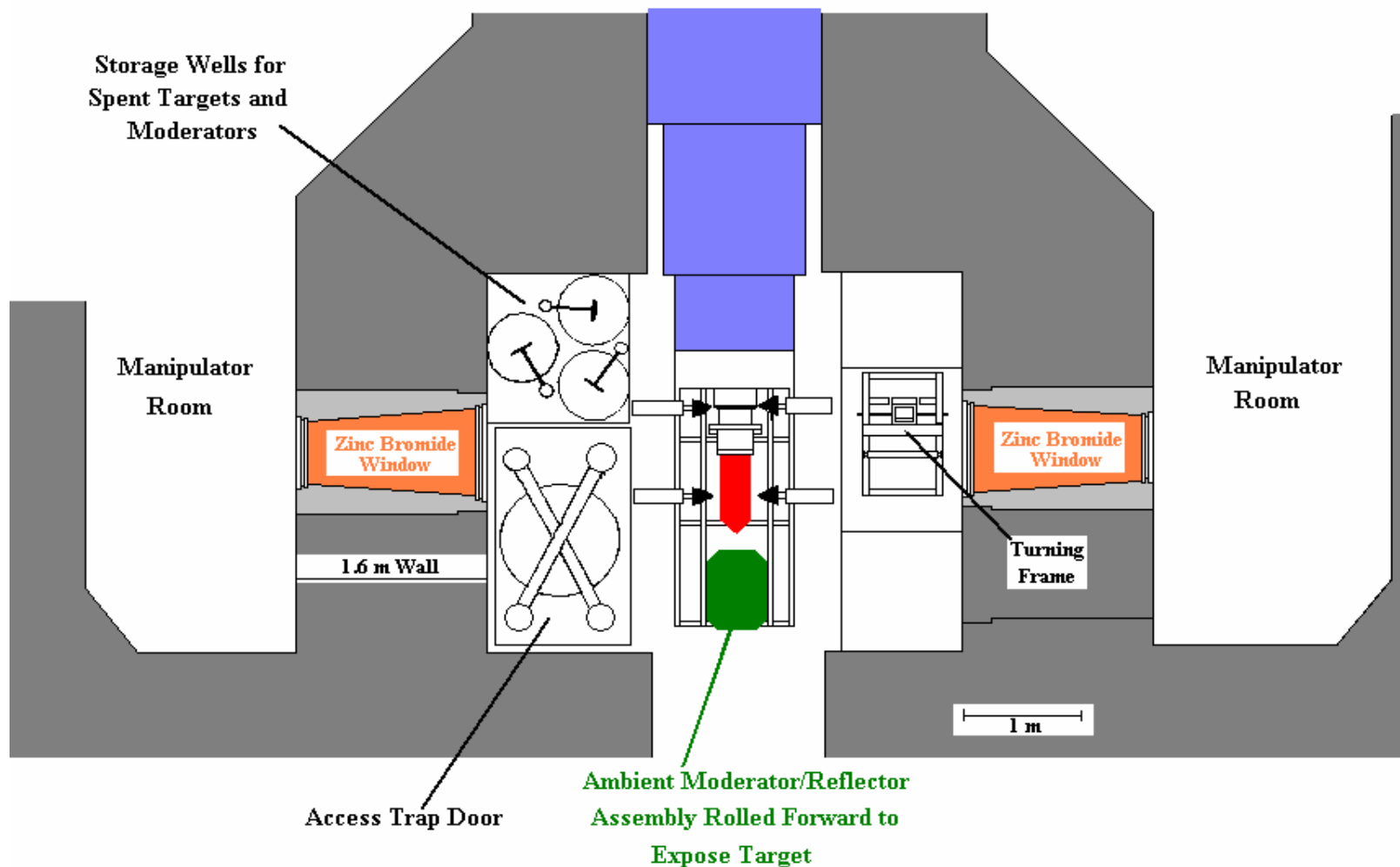


# CCLRC Alternative Concepts (2) - Vertical

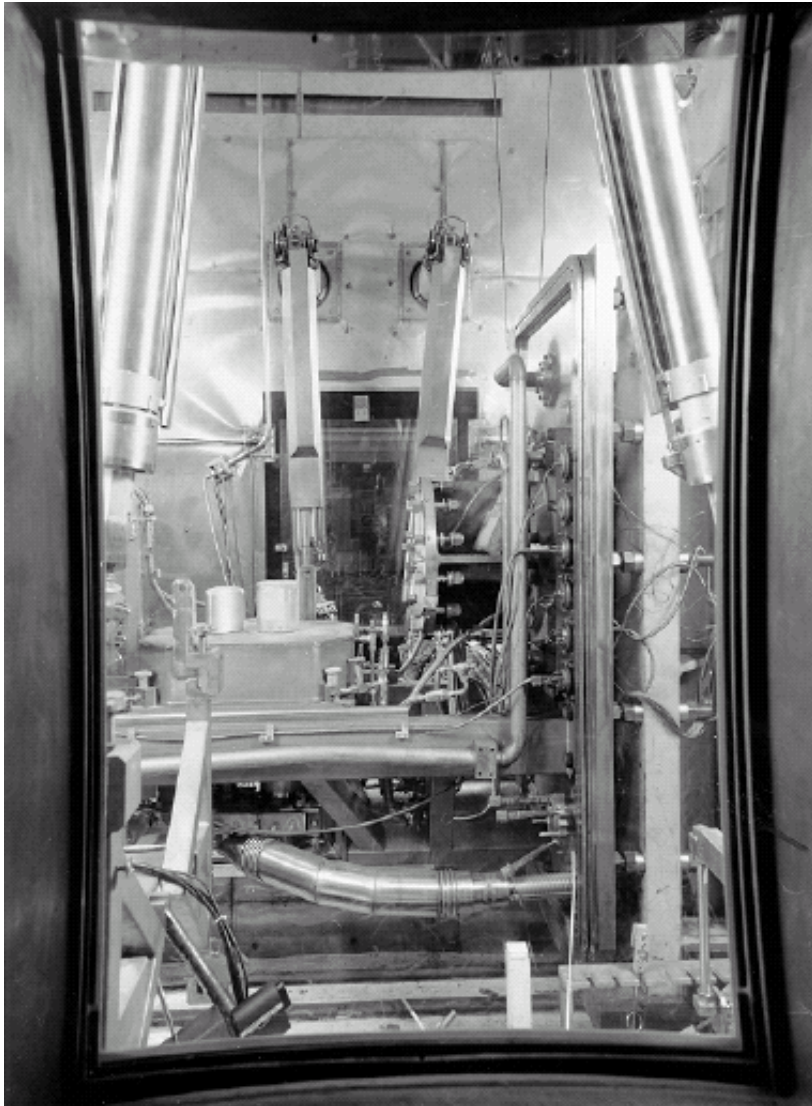


Services disconnected and target removed to a storage facility. Later can be worked on in a separate remote handling facility

# CCLRC Simple Handling Equipment (ISIS)



# CCLRC Simple Handling Equipment (ISIS)



- 2 Pairs master - slave manipulators
- 2 viewing windows supplemented by 8 cameras
  - 6 fixed with pan, tilt and zoom
  - 2 mobile (held by manipulator) with mobile lights
- All operations can be recorded on video tape
- Only simple tools used - standard spanners with grips for manipulator hands (Almost NO power tools are used)
- Underground tunnel for access and removal of radioactive components using a transport flask



# CCLRC Complex Handling Equipment (JSNS)

**Neutron beam shutters**

**Mercury circulation system**

(Supplying mercury to the target vessel at the maximum flow rates of  $0.8\text{m}^3/\text{min}$ , and is fixed on the target trolley)

**Biological shielding**

**In-cell crane and power manipulator**

(To exchange the target vessel, mercury circulation components etc.)

$\phi 13\text{m}$   
 $\times 12\text{m}$

**Neutron beam line**

**Helium vessel**

**Master-slave manipulators**

**Target maintenance room**

**Target storage cask**

**Proton beam line**

**Mercury Target**

(fixed on the target trolley)

**Target trolley**

(moves horizontally to maintenance room)

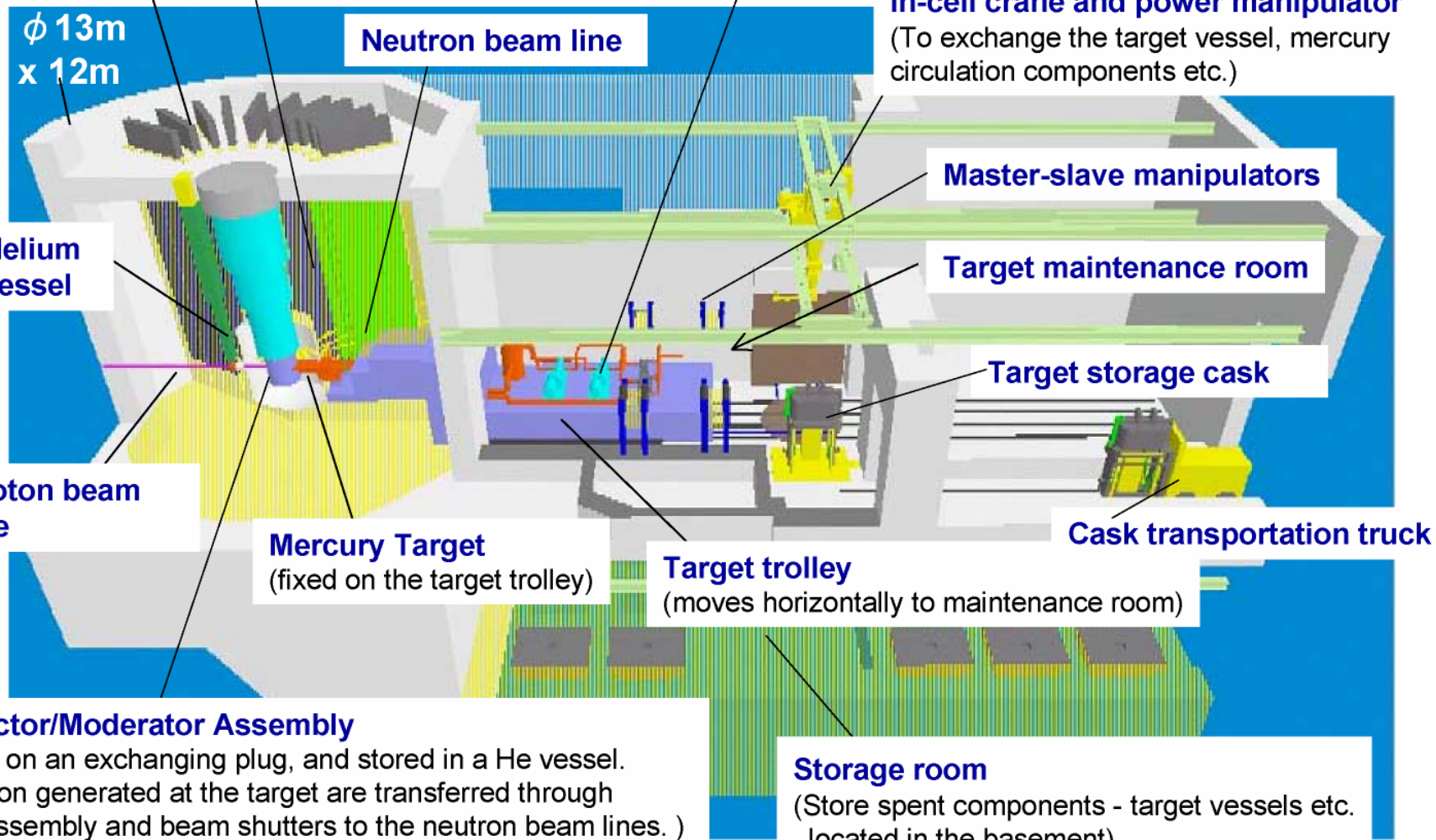
**Cask transportation truck**

**Reflector/Moderator Assembly**

(Fixed on an exchanging plug, and stored in a He vessel. Neutron generated at the target are transferred through this assembly and beam shutters to the neutron beam lines.)

**Storage room**

(Store spent components - target vessels etc. located in the basement)



# CCLRC Complex Handling Equipment (JSNS)



Complex Robots and fixtures, power tools



Large integral Remote Handling Cell, many windows, complex storage facility

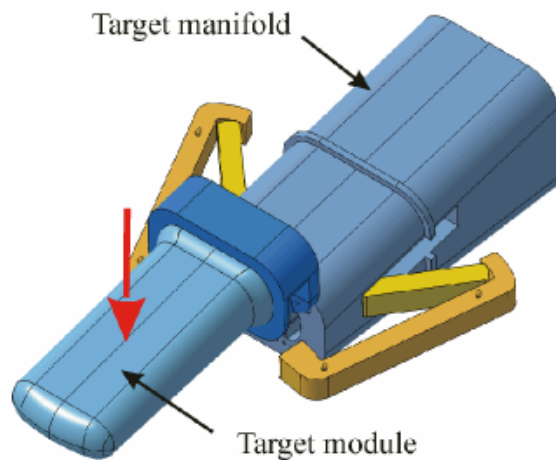


# CCLRC General Comments

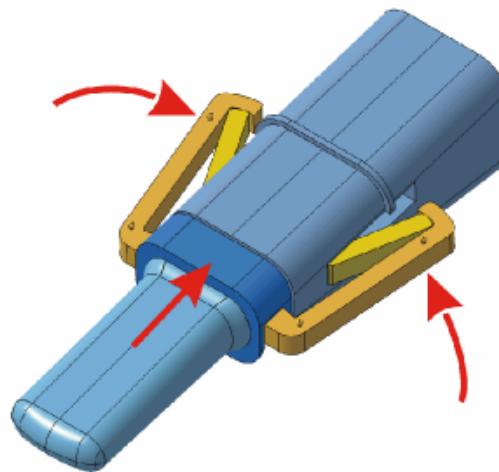
- Despite careful Quality Control most equipment can be expected to suffer failure in operation.
- Procedures to recover from any failure are essential.
- A full scale mock-up for developing tooling and procedures and training operators is essential.
- A policy defining under what conditions staff may enter a remote handling cell is essential.
- Control of contamination must be built in to the basic design of all remote handling.
- Do not ignore services - cooling plant may also require remote handling (e.g. liquid metal targets).

- For component replacement reliable, easily handled connections are essential but there are several difficulties
- To make reliable joints (with metal seals) can require application of precise torque on the flanges or joints
  - Most methods of applying a known torque to a nut requires the friction between the threads to be controlled
  - Irradiation effects and the problems of applying lubricants remotely result in poor condition of the threads
- The seal design has to be tolerant of poorly known and uneven closure forces
- Leak testing and detection is very hard and time-consuming
- Minimise connections

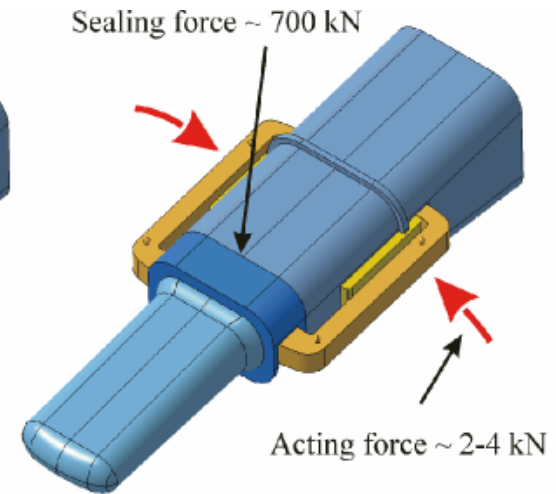
# CCLRC Sealing Technologies (ESS Target)



1. Insert target module from above

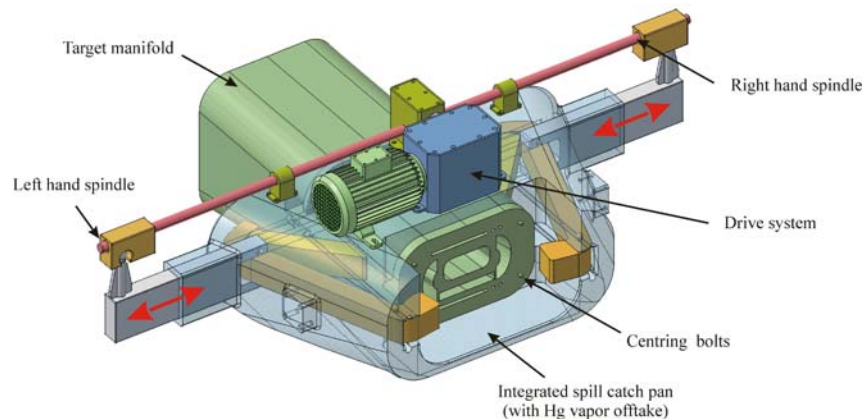


2. Move target module towards manifold

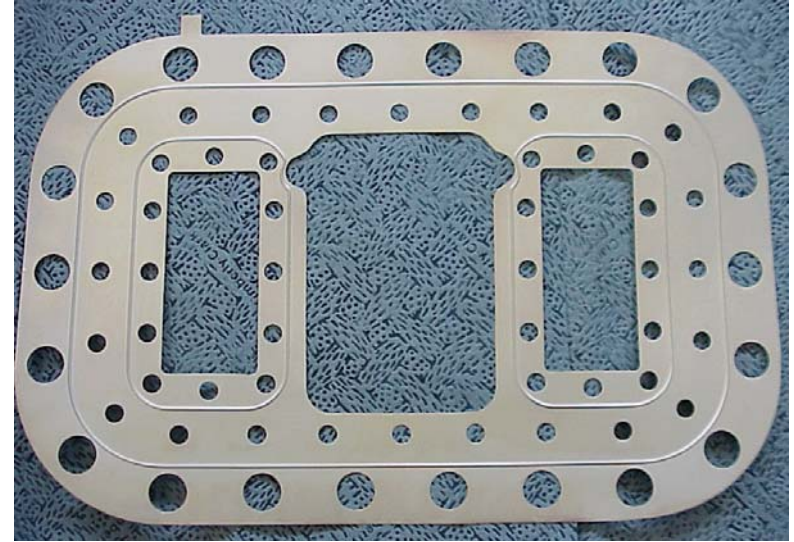


3. Close clamps to tighten seals

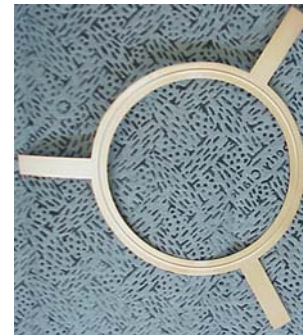
Avoids Bolted Flanges



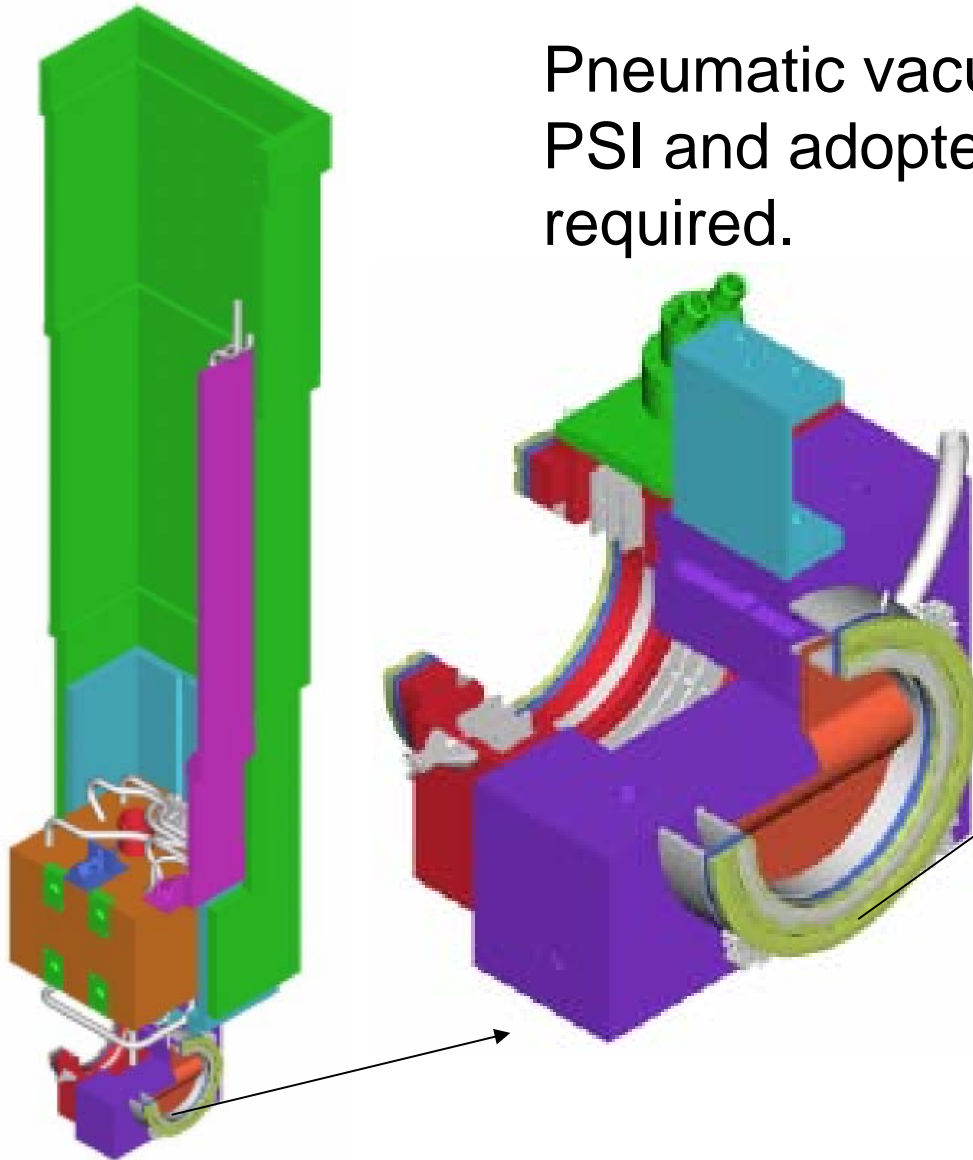




- Corroseal – silver plated stainless steel.
- Versatile shape to allow manifolds for many connections
- Tolerant of uneven torque



Pneumatic vacuum seals – Developed at PSI and adopted at SNS. No bolts required.

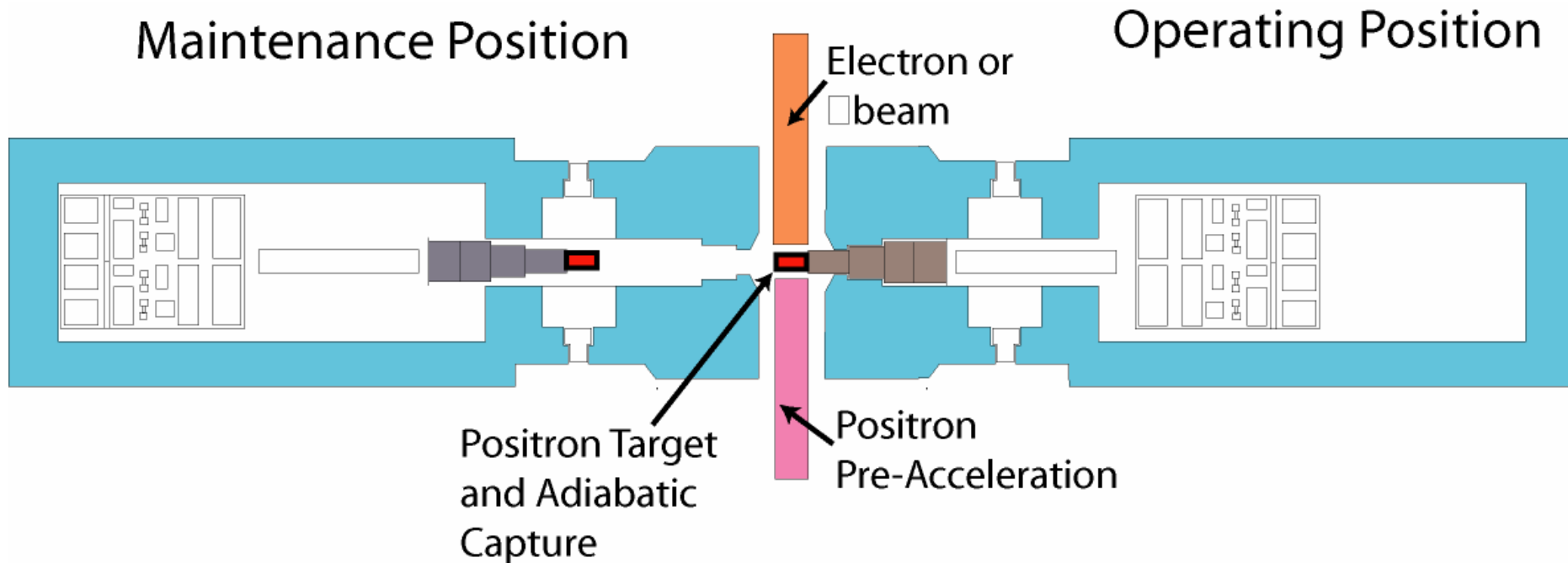




# CCLRC General Observations

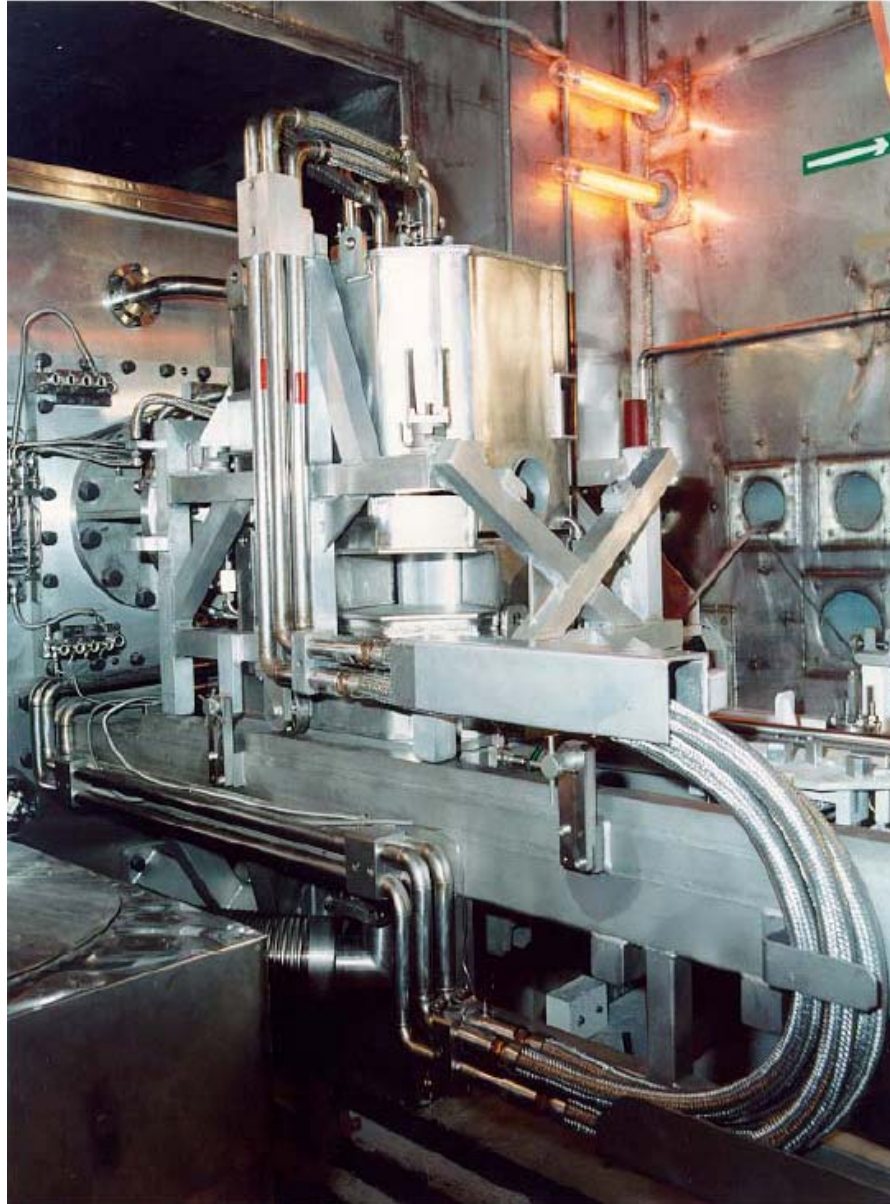
- Remote Handling requirements will dominate the layout of the target area.
- Remote handling of components must be included in the design of the components from the outset.
- The main choice is between replacement of modules or replacement of components
- This choice will depend on:
  - Frequency of replacement, availability of Hot Cell facilities and cost and complexity of service connections
- Do not install any system without a solution to the remote handling requirements
- Remember Instrumentation

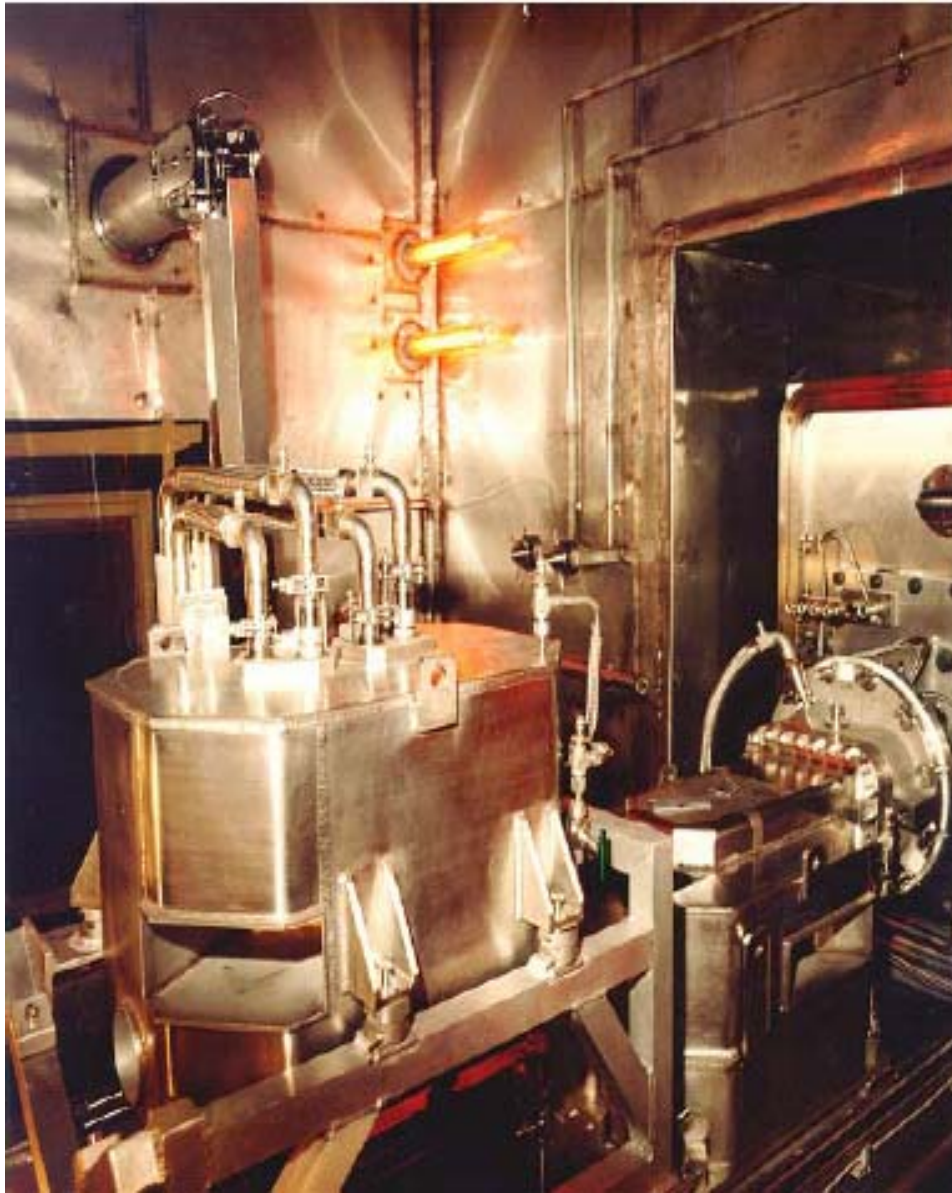
# CCLRC 2 – 4 Hour Positron target change

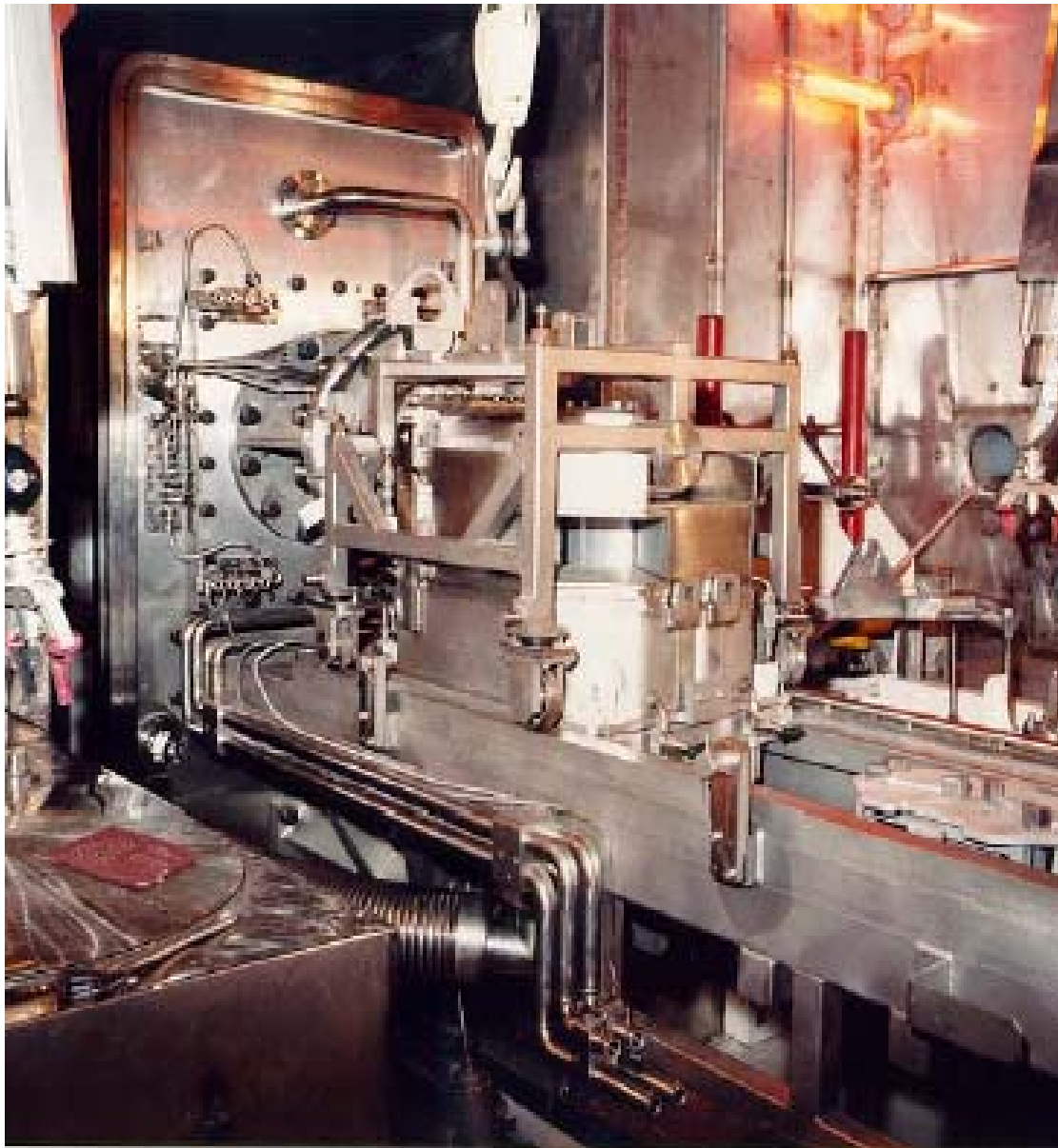


- The remote handling challenges for the positron target have many similarities with those of spallation targets
- There is lots of experience of detailed handling technology at spallation source – all available to the Linear Collider designers
- Remote handling for spallation targets has been most successful when handling requirements have been included at the conceptual design phase
- Ad hoc handling is likely to take a very long time

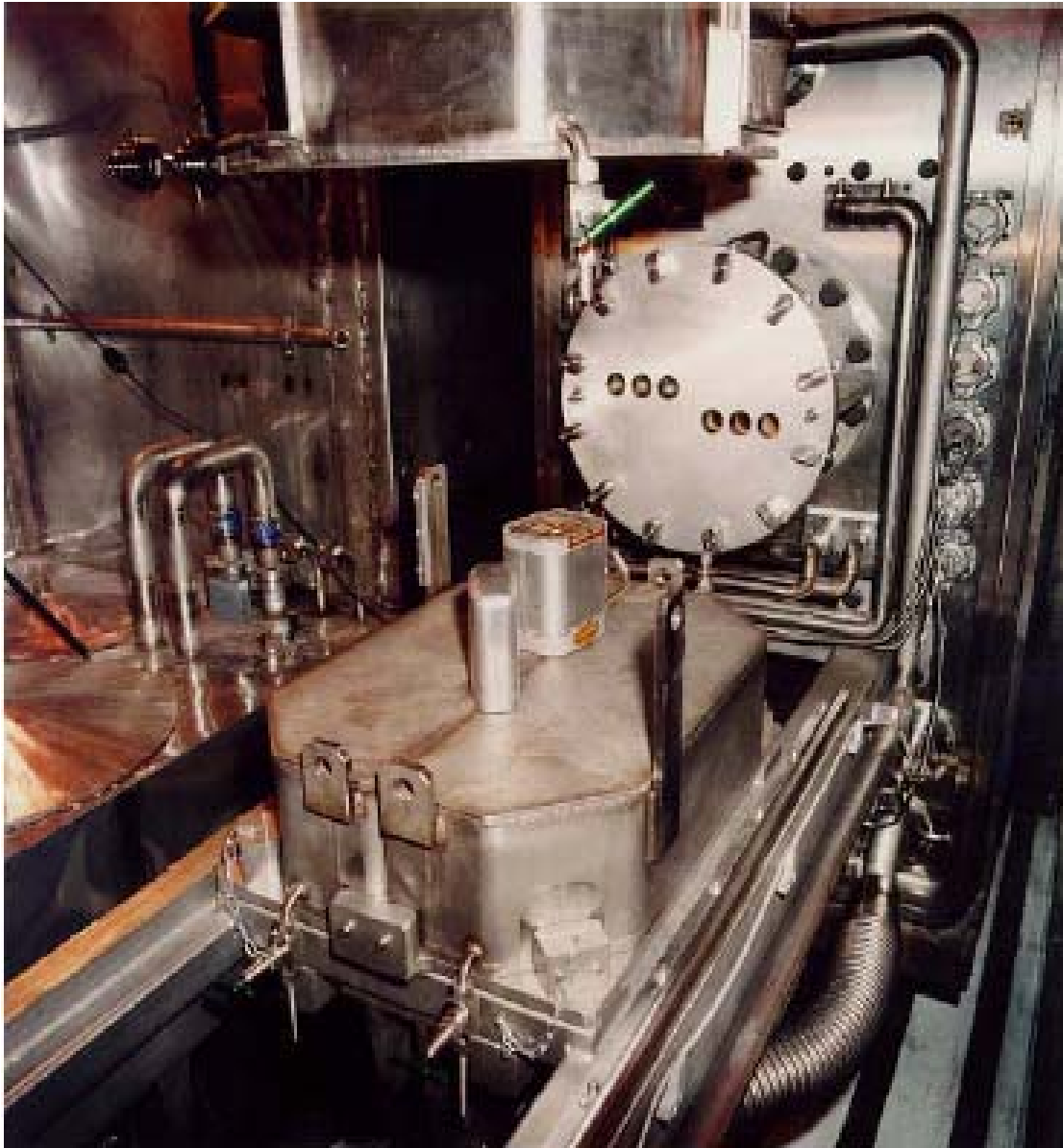














- **Horizontal removal of the Target, Reflector and Moderator system (with all the cooling plant)**
- **Replacement of individual components**
- **Target replacement takes 10 days beam off to beam on**
  - **3 days for cooldown and preparation of cell**
  - **4 days remote handling**
  - **1 day leak testing**
  - **2 days to return to operating conditions and cool down cryogenics**
- **Moderator replacement takes 14 days beam off to beam on**

