

ML for particle physics in the precision era

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The goal of particle physics

→ Answer the big fundamental questions!

Nature of EWSB

Dark matter

Neutrino masses

Baryon asymmetry

.....

Naturalness

Can ML find answer these questions for us? **No!**

Can it help us with it? **Yes!**

The challenge ahead

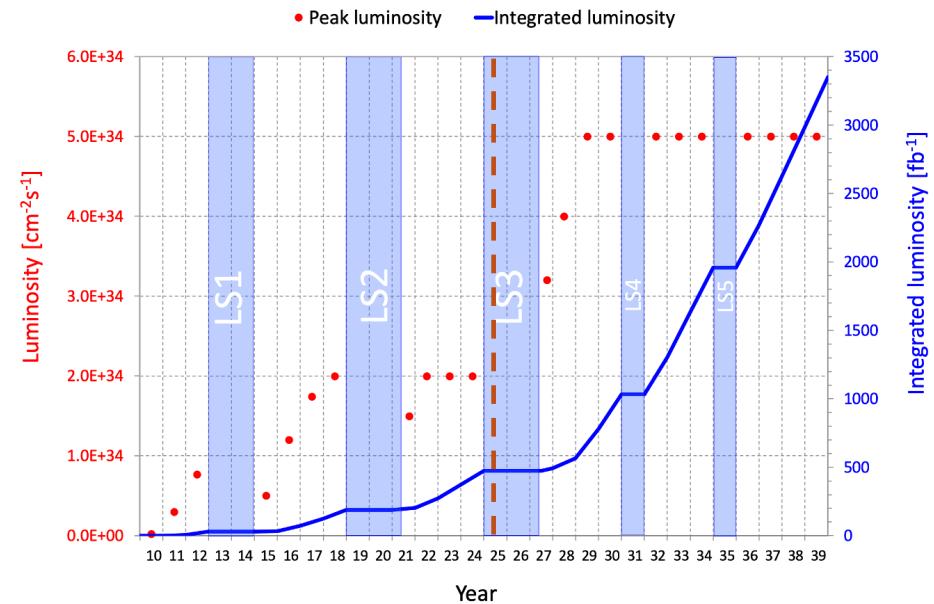
- general trend: larger-and-larger experiments collecting more-and-more data
- e.g. LHC: already enormous dataset will be further enlarged by a factor ~ 10
- costs for future experiments increasing



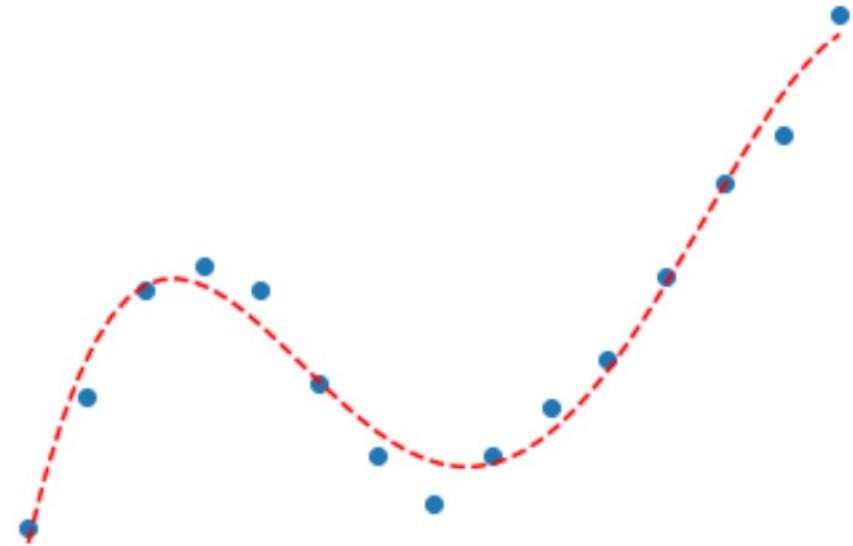
Fully exploit the available data!



- new analysis methods
- theory precision \simeq experimental precision
- in particular: high-precision MC simulation

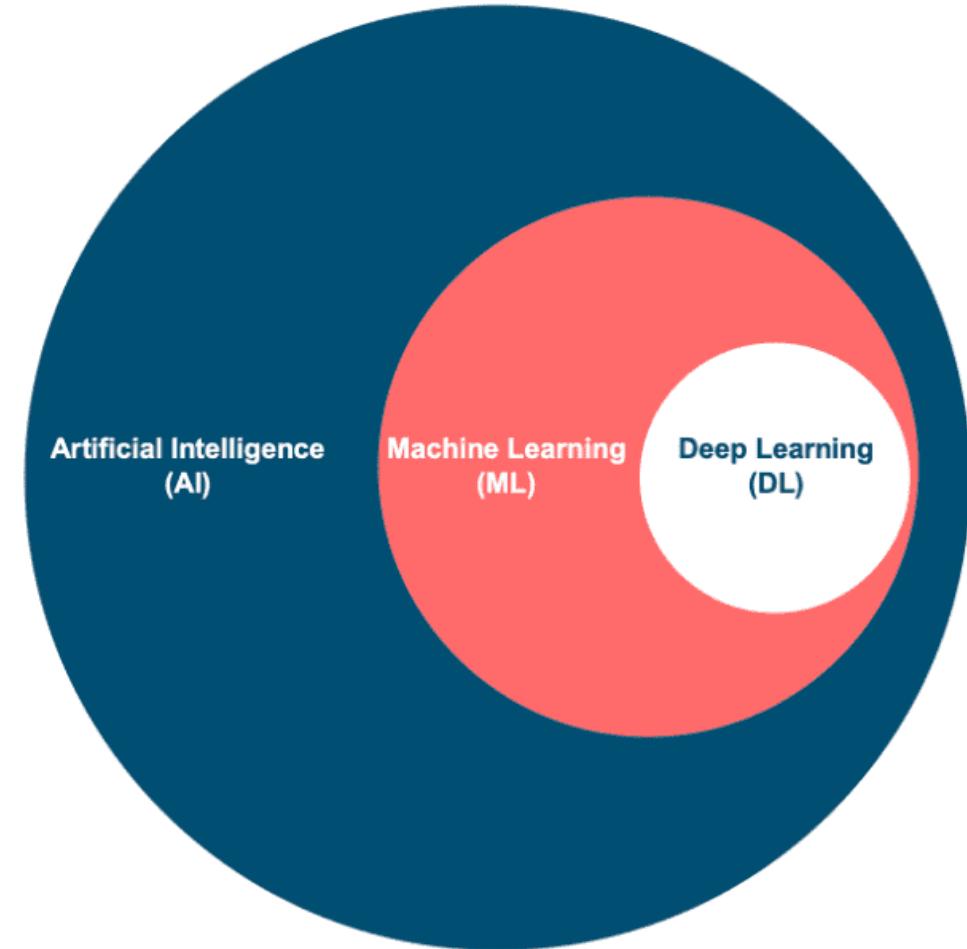


ML in a nutshell

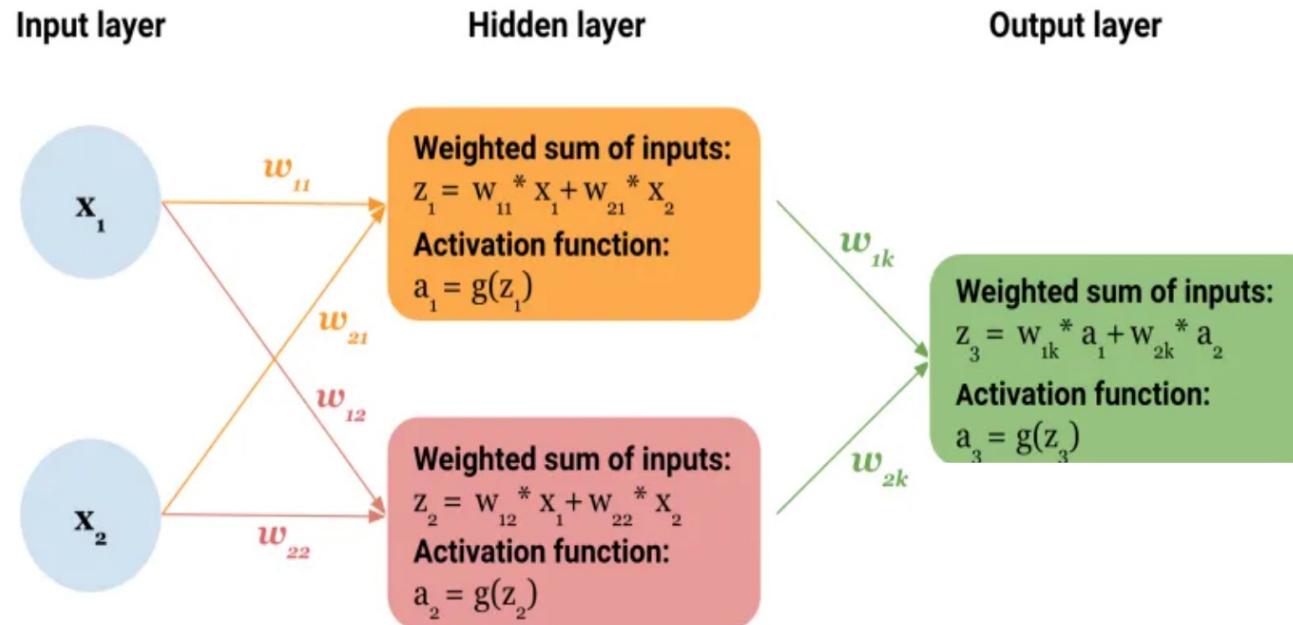


Terminology

- **Artificial Intelligence (AI)**
 - machines performing complex tasks
 - e.g. Feynman diagram generators, ...
- **Machine Learning (ML)**
 - subfield of AI where machines learn from data
 - e.g. linear regression, BDTs, ...
- **Deep Learning (DL)**
 - subfield of ML using deep neural networks



Neural networks

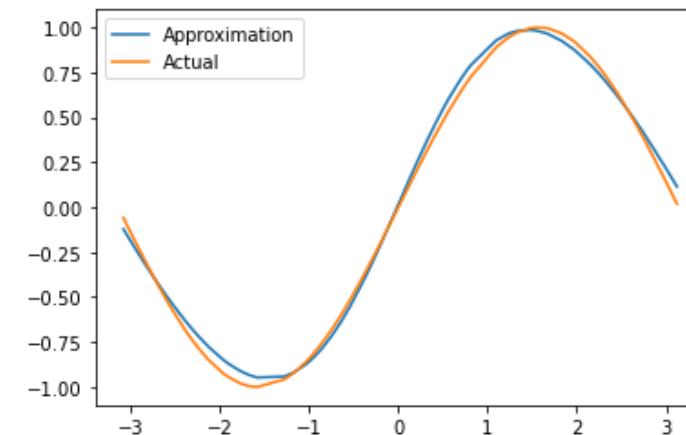
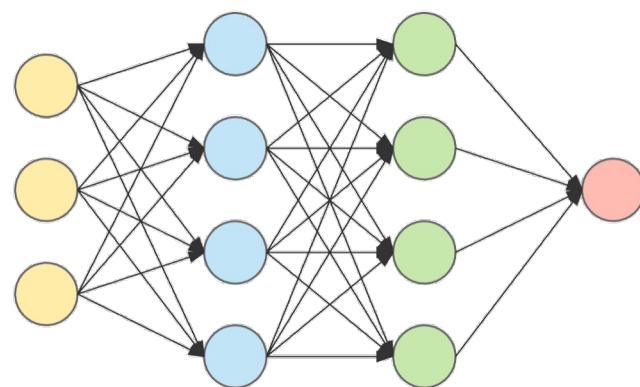


- activation introduces non-linearity (e.g. $g(x) = \max(0, x)$)
- adjust weights by minimizing loss

The Universal Approximation Theorem

Theorem (informal):

“A feedforward neural network with enough neurons can approximate any continuous function with arbitrary accuracy.”



Limitations in practice:

- 1) amount of **training data**, 2) **size** of NN, and 3) **compute** spent for training

Types of ML (selection)

Tasks

- regression (e.g. calorimeter calibration)
- classification (e.g. jet tagging)
- generation (e.g. event generation)

Learning types

- supervised (e.g. amplitude regression)
- unsupervised (e.g. data clustering)
- semi-supervised (e.g. anomaly detection)

ML workflow

1. define the problem
2. collect and preprocess the dataset
3. define your ML model
4. training
5. evaluation

ML workflow

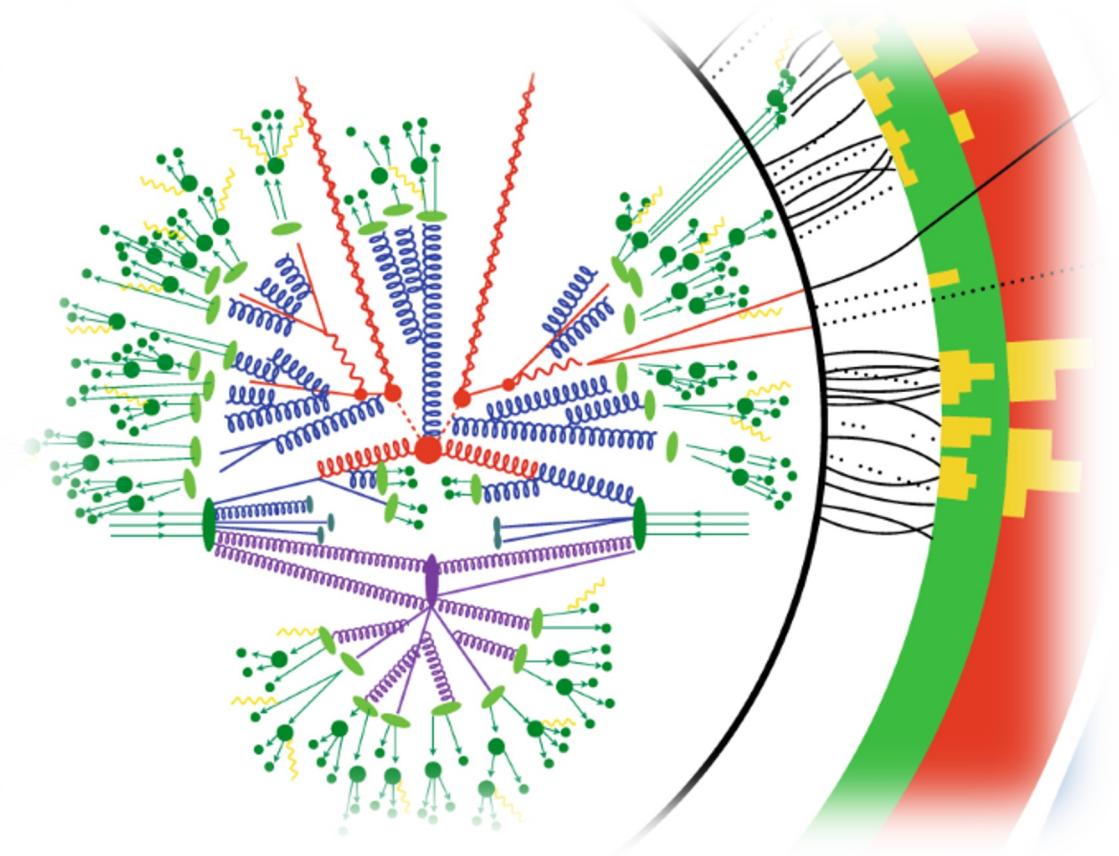
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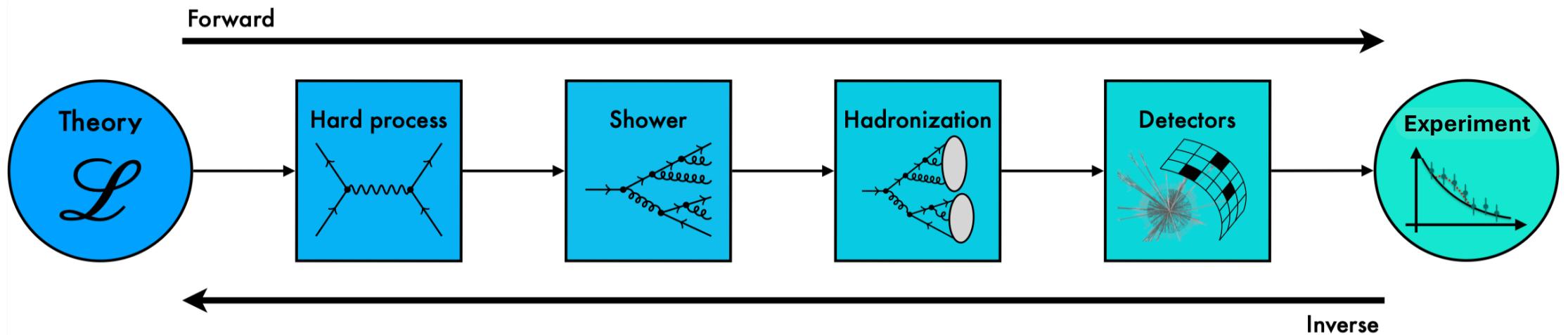
- ML strategy — *multiple ways to approach problem*
- loss — *what objective do I want to optimize?*
- architecture — *what is the best structure for my NN?*
- encode physics knowledge — *symmetries, ...*

ML for particle physics

[Iulia Georgescu, 2021]



The particle physics workflow



ML can help with each of these steps by increasing

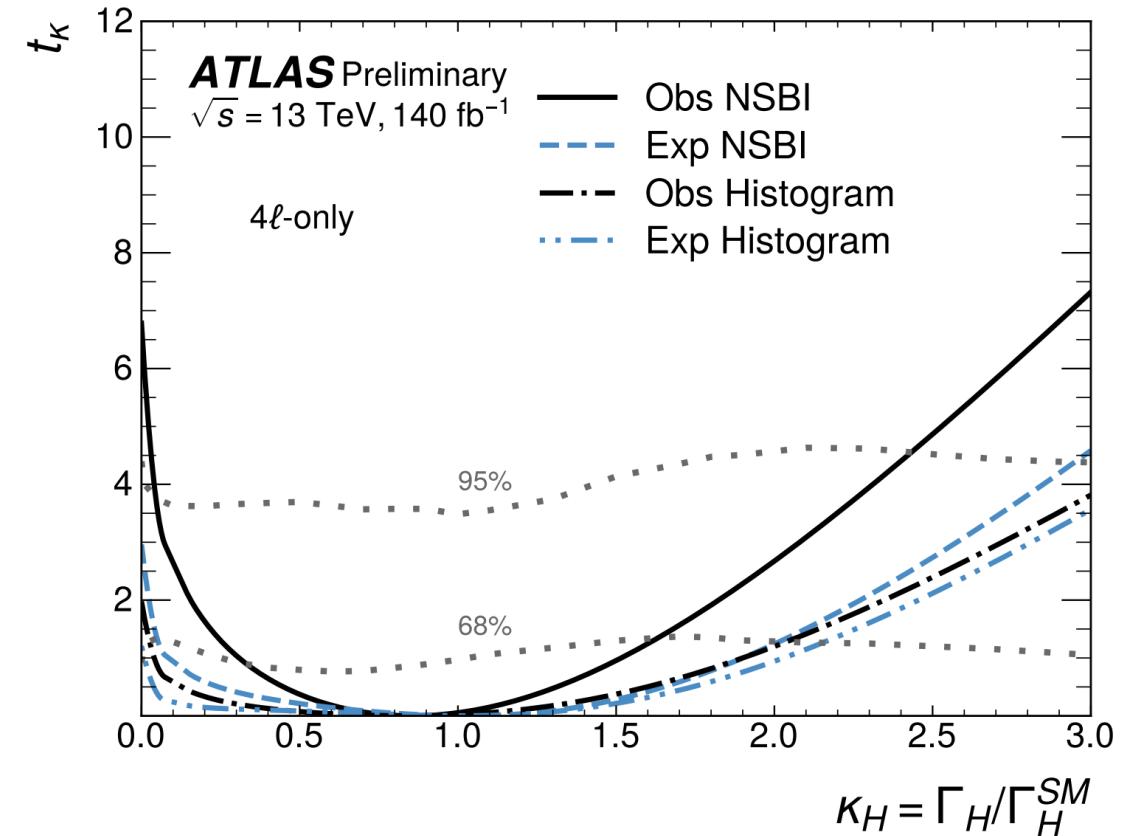
- accuracy/performance
- speed

Motivating example: simulation-based inference

- simulation-based inference (SBI) allows to exploit full kinematic information
- significant improvement in comparison to histogram approach

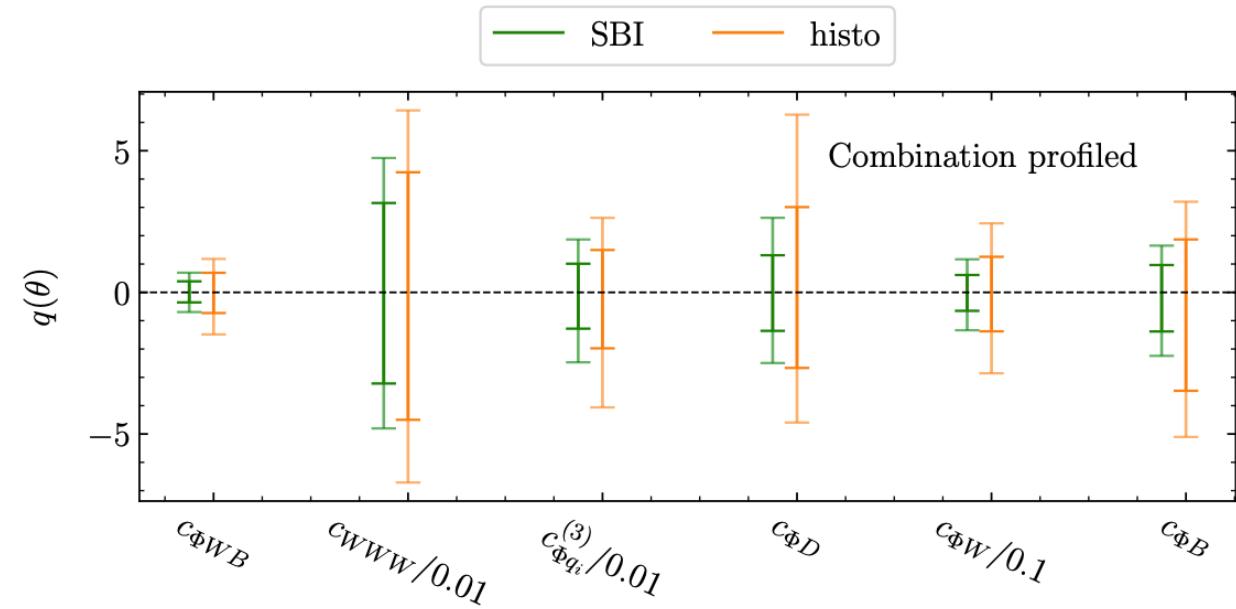
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- 1st experimental analysis: measure off-shell signal strength in $H \rightarrow ZZ$ channel
[ATLAS-CONF-2024-016]



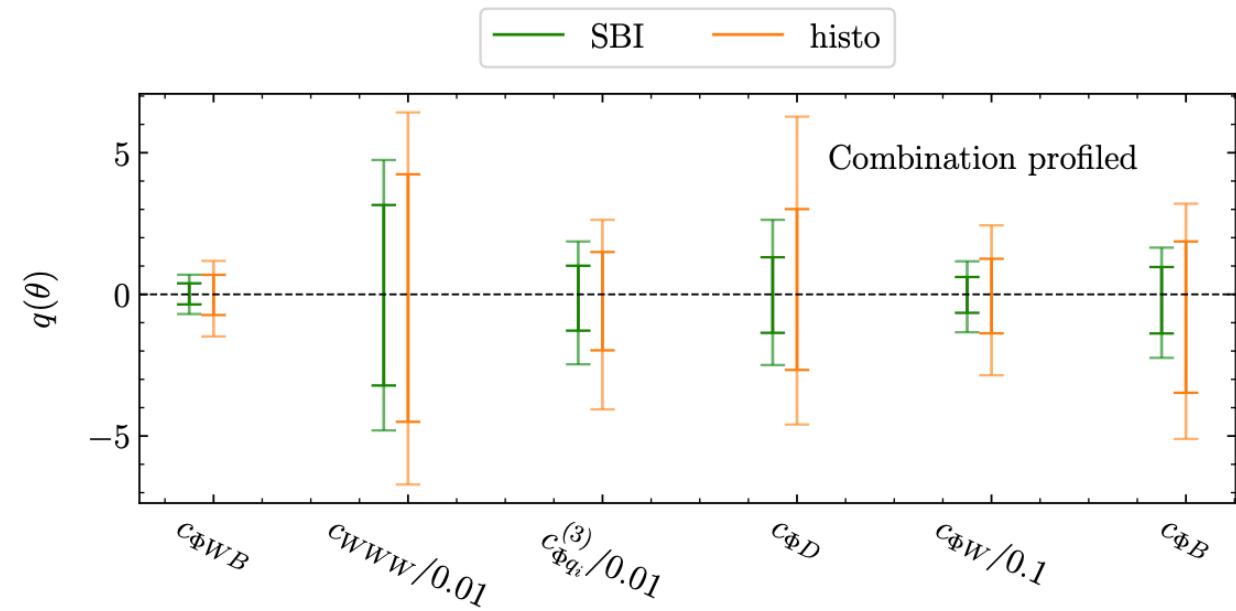
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[ATLAS-CONF-2024-016]
- also persists in global analyses
[HB,Plehn,Schmal,2509.05409]



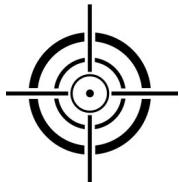
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→ What is needed to apply ML successfully?

ML for particle physics



accuracy



speed

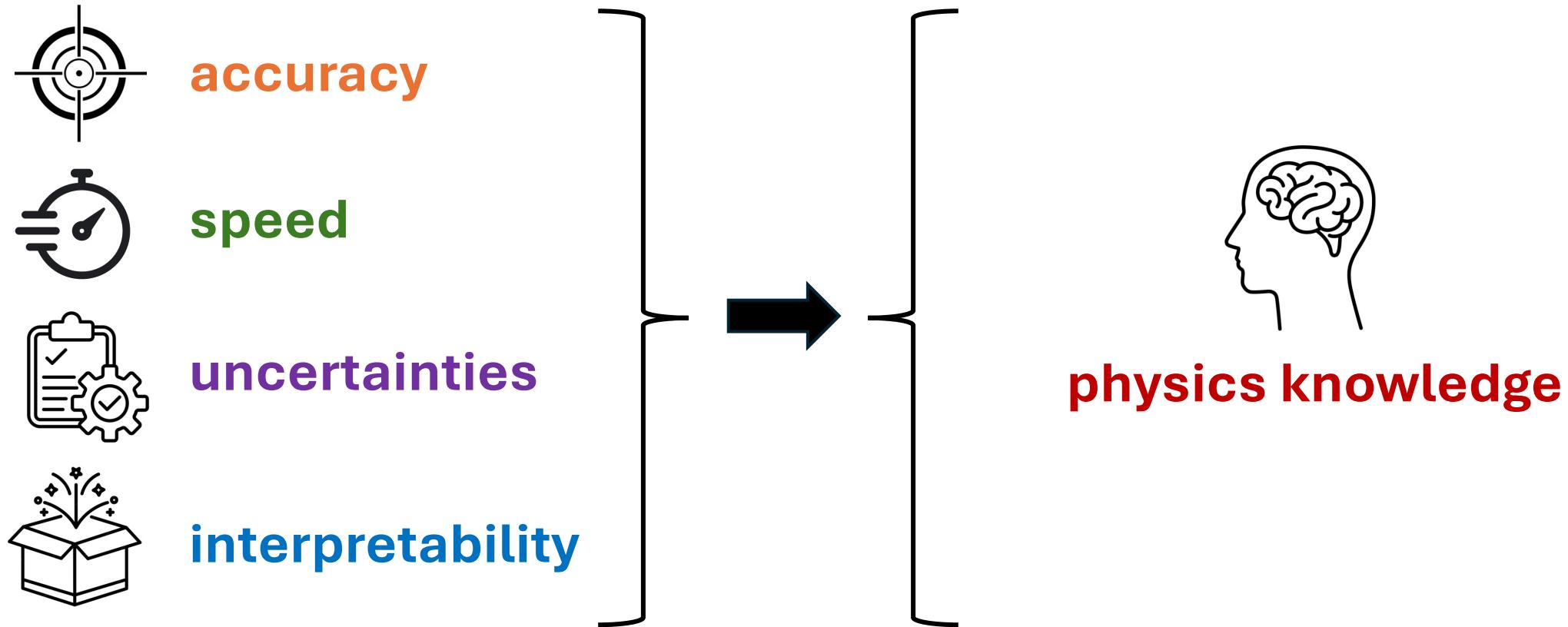


uncertainties

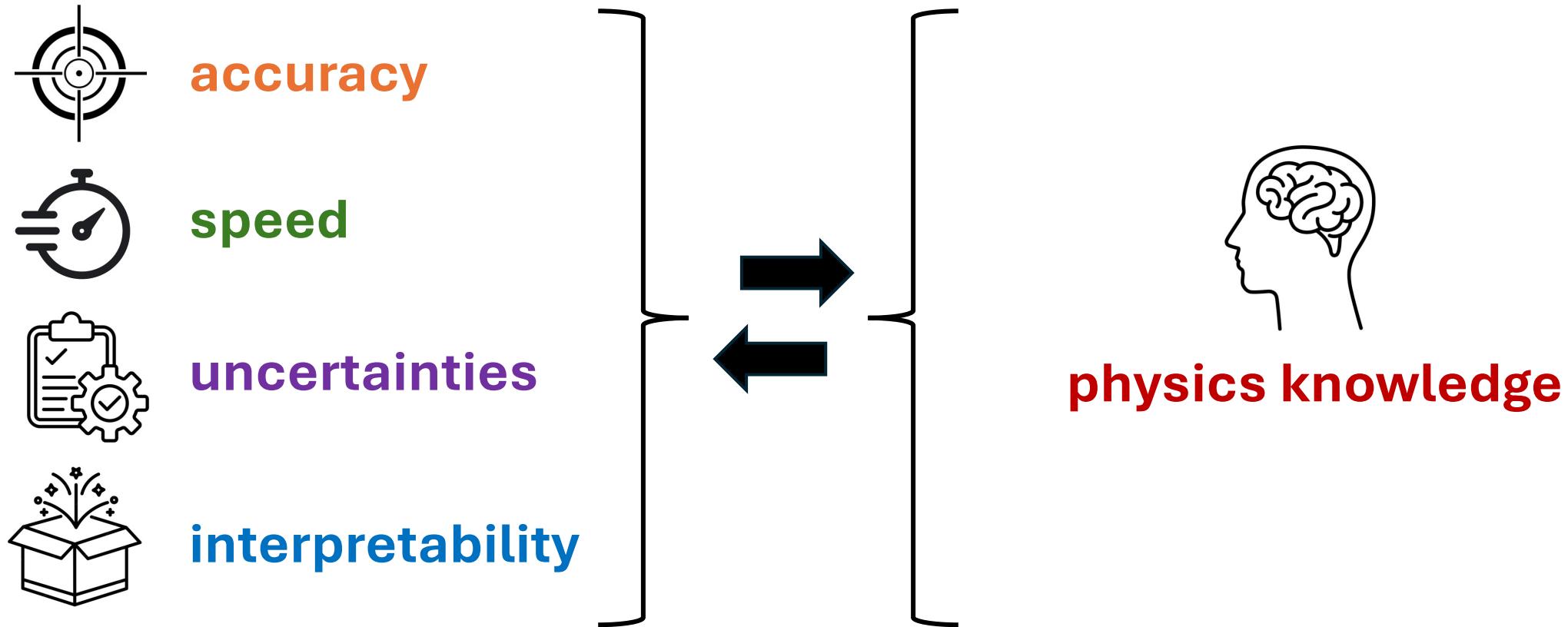


interpretability

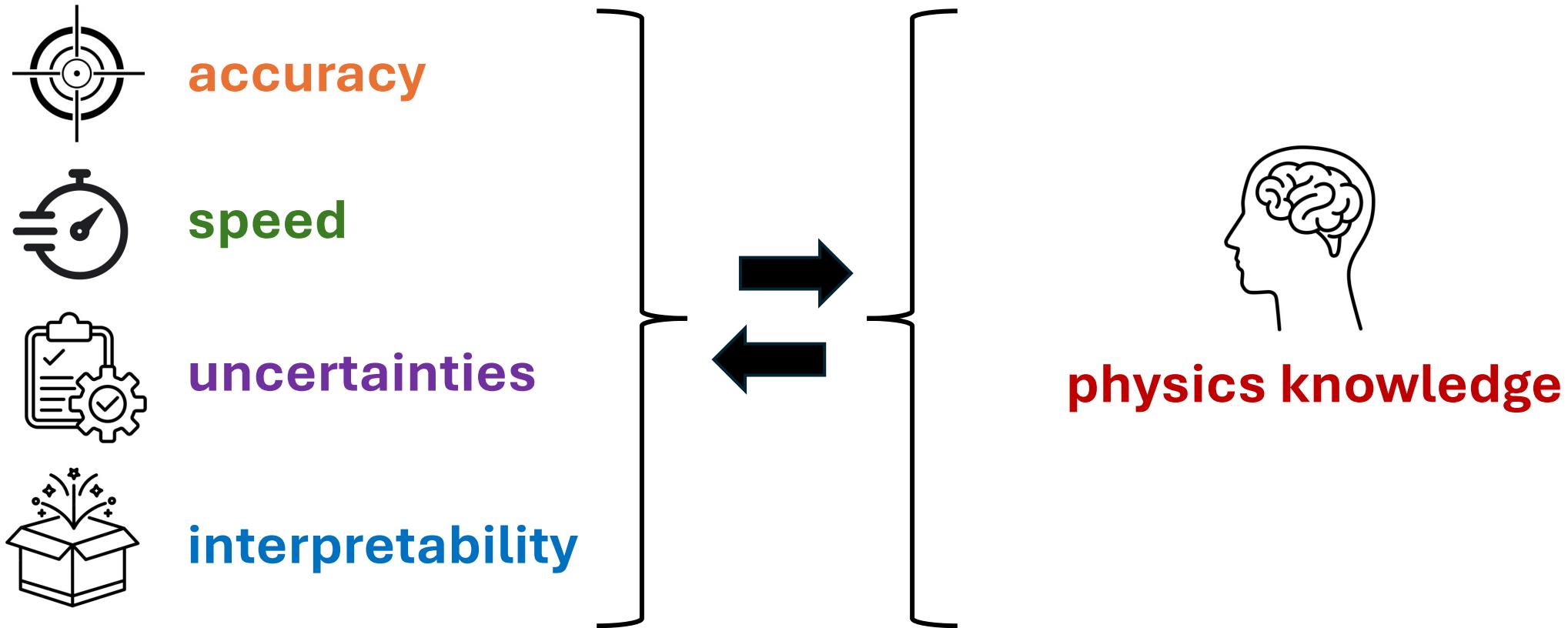
ML for particle physics



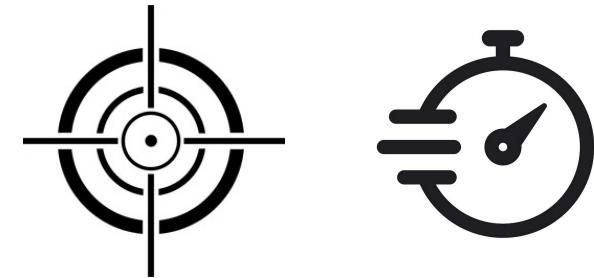
ML for particle physics



ML for particle physics

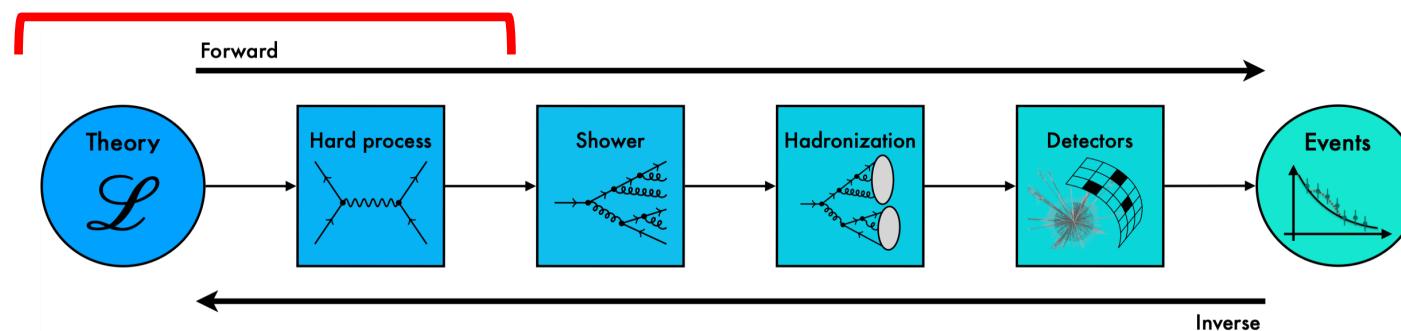


→ Key to all these aspects: finding good representations of the data



Accuracy & speed

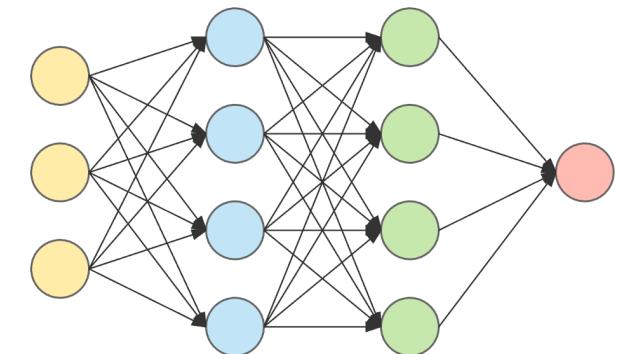
fast higher-order amplitude surrogates



Amplitude surrogates

- evaluating analytic expressions for amplitudes $|\mathcal{M}|^2$ can be very expensive due to
 - higher-order corrections
 - large final-state multiplicities

$$|\mathcal{M}|^2 \approx$$

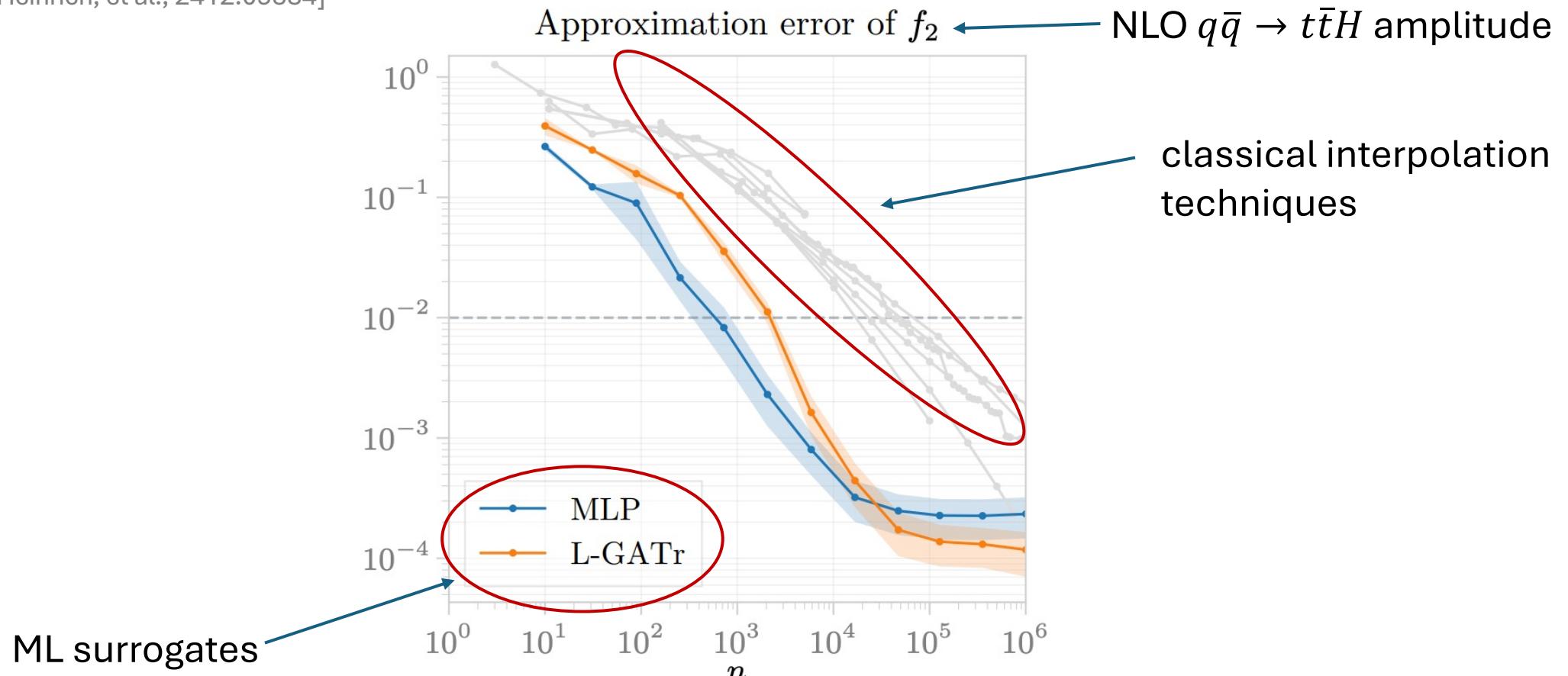


- idea:
 - generate small training sample using full analytic expression
 - train a NN to approximate $|\mathcal{M}|^2$
 - generate events using NN surrogate → fast to evaluate

→ fast high-precision event generation

Comparison to classical interpolation

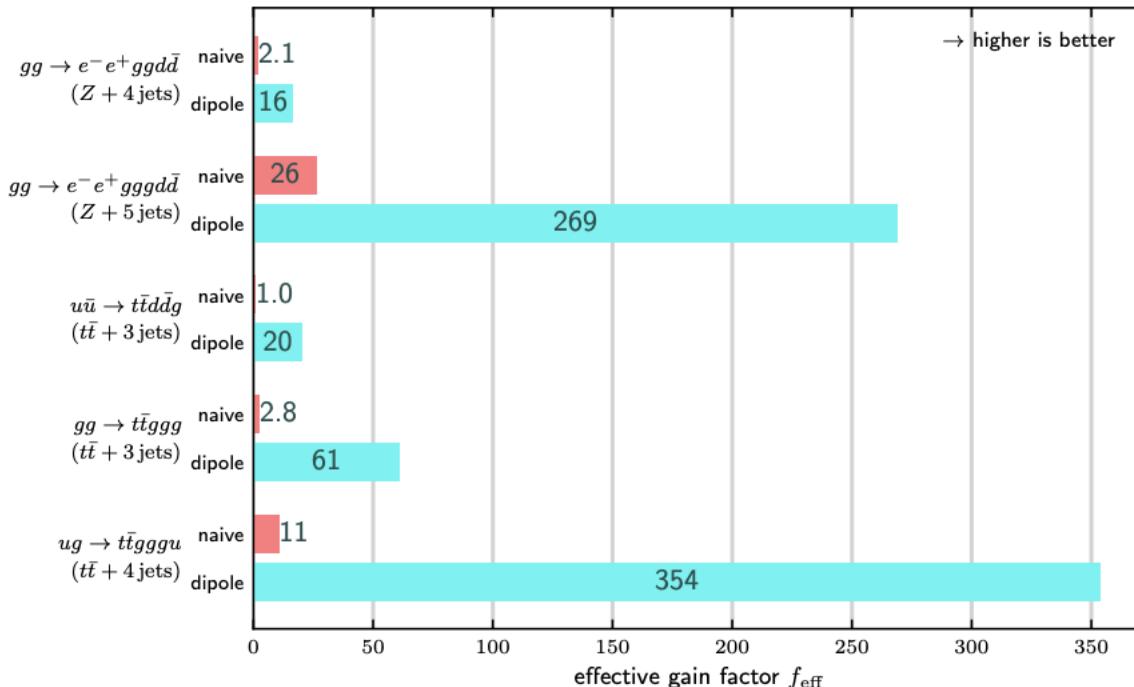
[Bresó, Heinrich, et al., 2412.09534]



→ ML surrogates outperform classical interpolation techniques

Speed comparison

[Janßen et al., 2301.13562]



$$f_{\text{eff}} = \frac{T_{\text{standard}}}{T_{\text{surrogate}}}$$

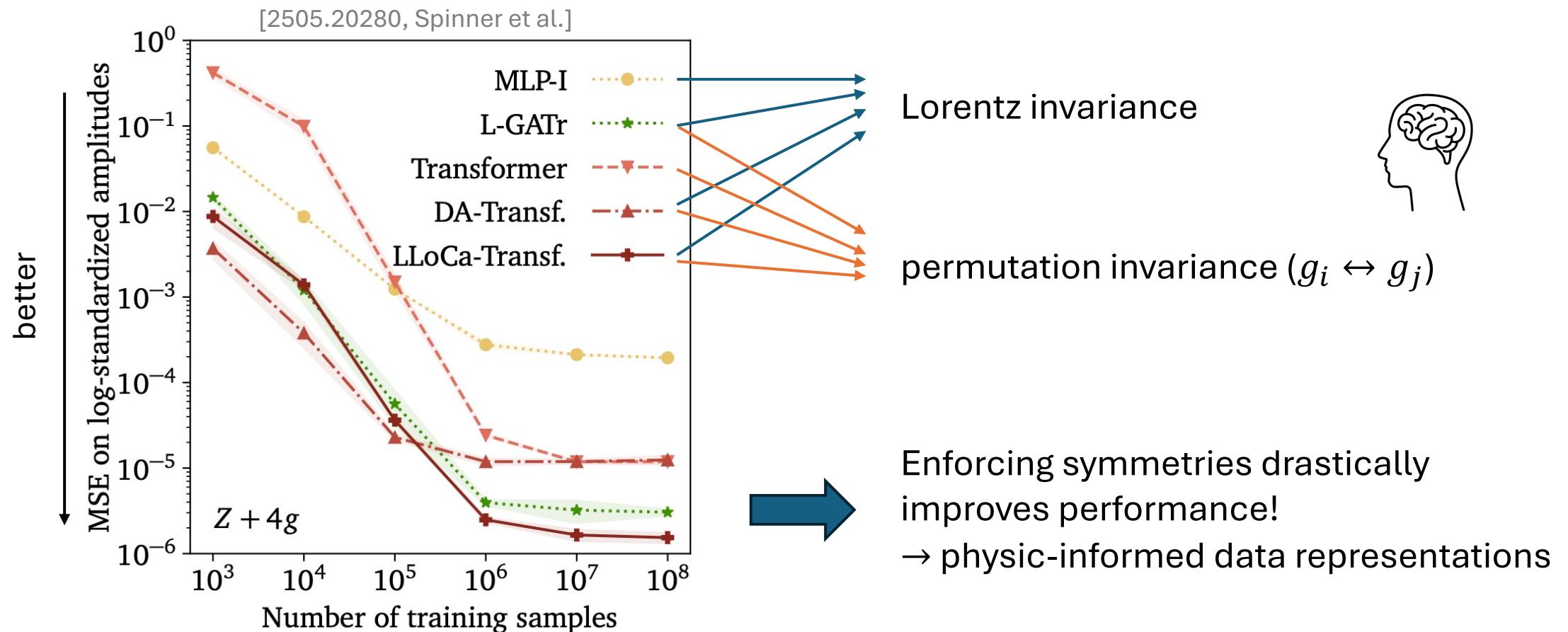
dipole vs naïve:
encode singularity structure of amplitudes



Large speed-ups possible!

Process	SHERPA default			with dipole-model surrogate				
	$t_{\text{ME}}[\text{ms}]$	$t_{\text{PS}}[\text{ms}]$	ϵ_{full}	$t_{\text{surr}}[\text{ms}]$	x_{max}	$\epsilon_{1\text{st,surr}}$	$\epsilon_{2\text{nd,surr}}$	f_{eff}
$gg \rightarrow e^- e^+ gg d\bar{d}$	54	0.40	1.411 %	0.14	2.6	1.418 %	39 %	16
$gg \rightarrow e^- e^+ ggg d\bar{d}$	16 216	5.70	0.076 %	0.20	3.6	0.085 %	29 %	269

Exploiting known symmetries



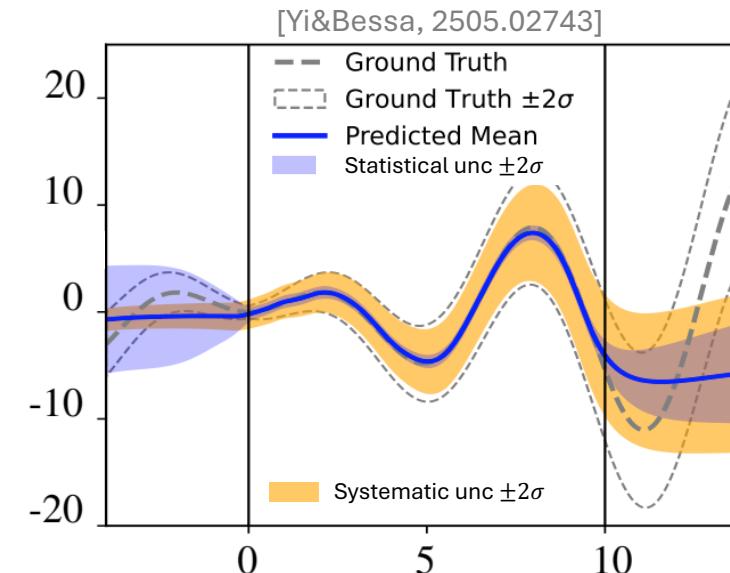
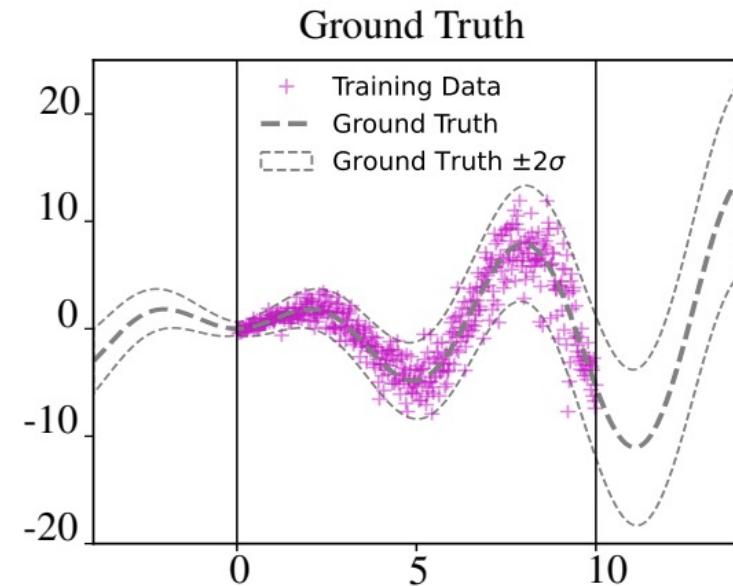


Uncertainties

"All models are wrong, but some — those that know when they can be trusted — are useful!"

George Box (adapted)

Regression with uncertainties



- statistical uncertainty $\hat{=}$ lack of training data
- systematic uncertainty $\hat{=}$ noise in the data, lack in model expressivity



Can we the NNs encode a representation of their own uncertainties?

Probabilistic learning

Learn amplitude statistically

$$p(A|x) = \int d\theta p(\theta|D_{\text{train}}) p(A|x, \theta) \approx \int d\theta q(\theta) p(A|x, \theta)$$

NN parameters

Then, we can calculate the mean prediction and uncertainties as

$$A_{\text{NN}}(x) = \int dA A p(A|x) = \int d\theta q(\theta) \bar{A}(x, \theta) \quad \text{with} \quad \bar{A}(x, \theta) = \int dA A p(A|x, \theta)$$

$$\sigma_{\text{ syst }}^2(x) = \int d\theta q(\theta) [\bar{A}^2(x, \theta) - \bar{A}(x, \theta)^2] \quad \longrightarrow \quad \text{vanishes for perfect data: } p(A|\theta) \rightarrow \delta(A - A_0)$$

$$\sigma_{\text{ stat }}^2(x) = \int d\theta q(\theta) [\bar{A}(x, \theta) - A_{\text{NN}}(x)]^2 \quad \longrightarrow \quad \text{vanishes for perfect training: } q(\theta) \rightarrow \delta(\theta - \theta_0)$$

Modelling the systematic uncertainty

- log-likelihood loss:

$$\mathcal{L} = - \sum_{x_i, A_i \in D_{\text{train}}} \log p(A_{\text{true}}(x_i) | x_i, \theta)$$

true amplitudes
phase-space point

- assume Gaussian likelihood: $p(A|x) = \mathcal{N}(\bar{A}(x), \sigma_{\text{syst}}^2(x))$

- NN learns both: $\bar{A}(x)$ and $\sigma_{\text{syst}}(x)$

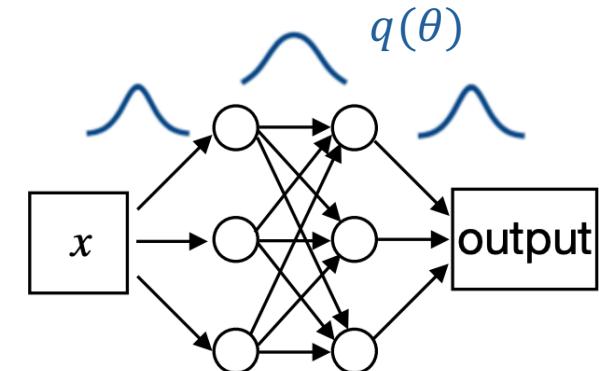
$$\Rightarrow \text{heteroskedastic loss: } \mathcal{L} = \sum_i \left[\frac{(\bar{A}(x_i) - A_{\text{true}}(x_i))^2}{2\sigma_{\text{syst}}^2(x_i)} + \log(\sigma_{\text{syst}}(x_i)) \right]$$

- if needed: replace by Gaussian mixture model

Modelling the statistical uncertainty

- variational approximation: $p(\theta|D_{\text{train}}) \simeq q(\theta)$
- promote each NN parameter to Gaussian distribution
- train by minimizing KL divergence:

$$\begin{aligned} \text{KL}[q(\theta), p(\theta|D_{\text{train}})] &= \int d\theta q(\theta) \log \frac{q(\theta)}{p(\theta|D_{\text{train}})} \\ \text{Bayes' theorem} \quad \longrightarrow &= \int d\theta q(\theta) \log \frac{q(\theta)p(D_{\text{train}})}{p(\theta)p(D_{\text{train}}|\theta)} \\ &= \text{KL}[q(\theta), p(\theta)] - \underbrace{\int d\theta q(\theta) \log p(D_{\text{train}}|\theta)}_{\text{prior}} + \dots - \underbrace{\int d\theta q(\theta) \log p(D_{\text{train}}|\theta)}_{\text{log likelihood}} + \dots \end{aligned}$$



Alternative: repulsive ensembles

- can describe NN training via ODE or continuity equation:

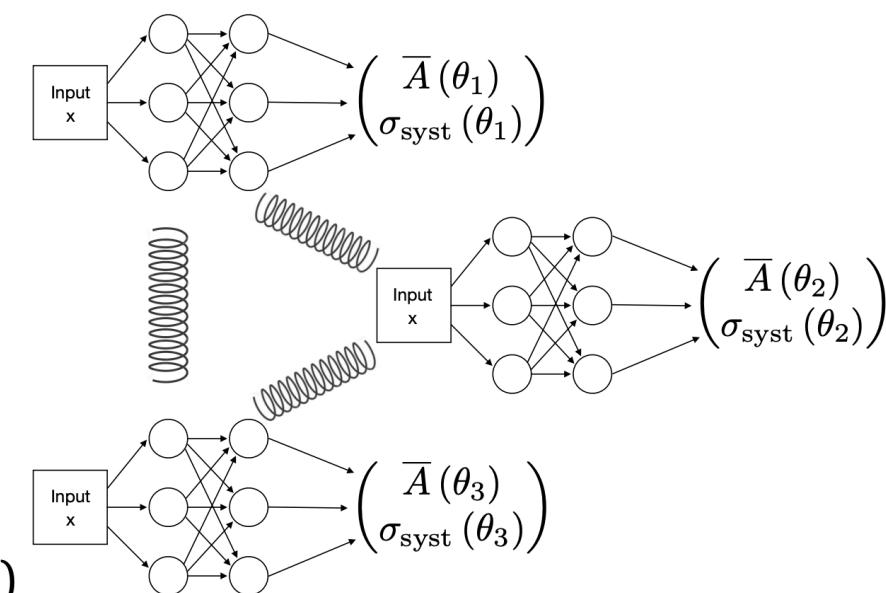
$$\frac{d\theta}{dt} = v(\theta, t) \quad \text{or} \quad \frac{\partial \rho(\theta, t)}{\partial t} = -\nabla_\theta [v(\theta, t)\rho(\theta, t)]$$

- choose $v(\theta, t) = -\nabla_\theta \log \frac{\rho(\theta, t)}{\pi(\theta)}$ → solution: $\rho(\theta) = \pi(\theta) \equiv p(\theta | D_{\text{train}})$

- estimate density via NN ensemble: $\rho(\theta^t) \approx \frac{1}{n} \sum_{i=1}^n k(\theta^t, \theta_i^t)$
- NN parameter update rule

$$\frac{d\theta}{dt} = -\nabla_\theta \left[\log \left(\frac{1}{n} \sum_i k(\theta, \theta_i) \right) - \log p(\theta | x) \right]$$

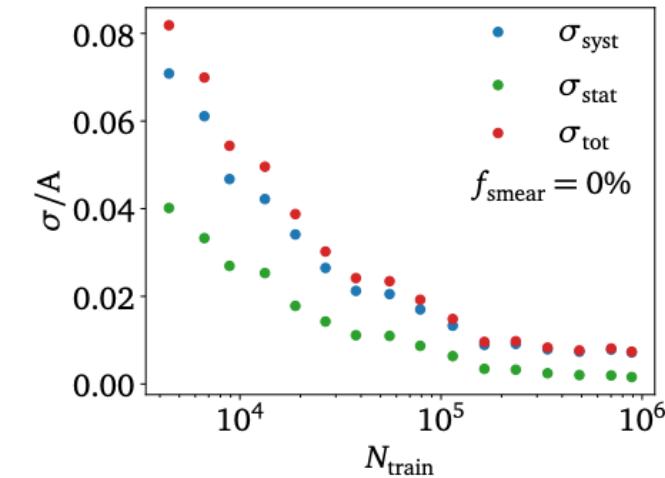
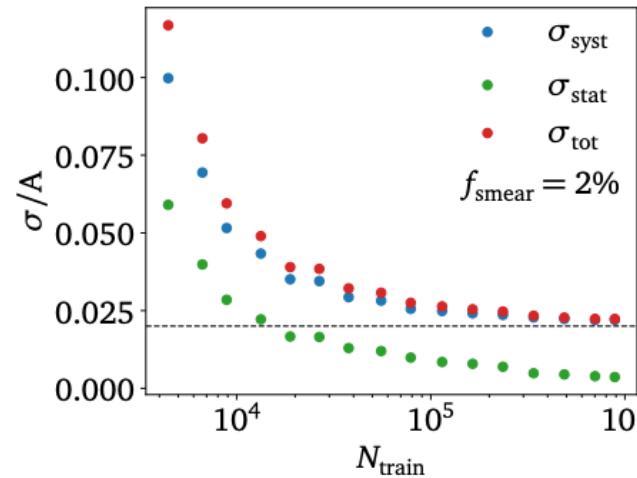
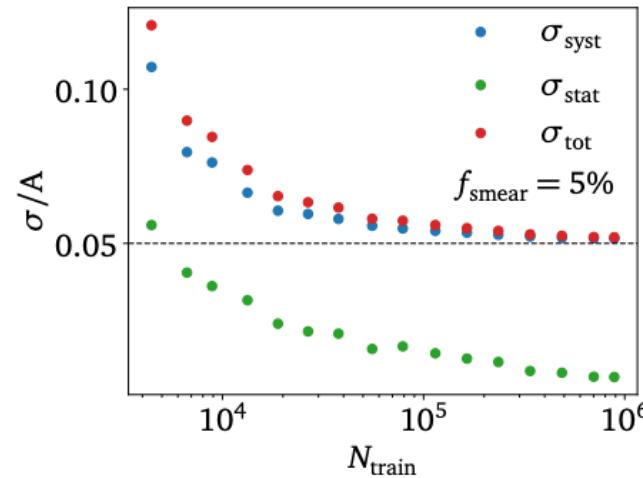
→ NN ensemble with repulsive force ensuring $\theta \sim p(\theta | D_{\text{train}})$



Behavior of uncertainties

[HB,Elmer,Favaro,...,2412.12069]

$$A_{\text{train}} \sim \mathcal{N}(A_{\text{true}}, \sigma_{\text{train}}^2)$$
$$\sigma_{\text{train}} = f_{\text{smear}} A_{\text{true}}$$



test: apply Gaussian noise to $gg \rightarrow \gamma\gamma g$ amplitudes

- statistical unc. decreases with more training data
- systematic unc. converges to level of applied noise

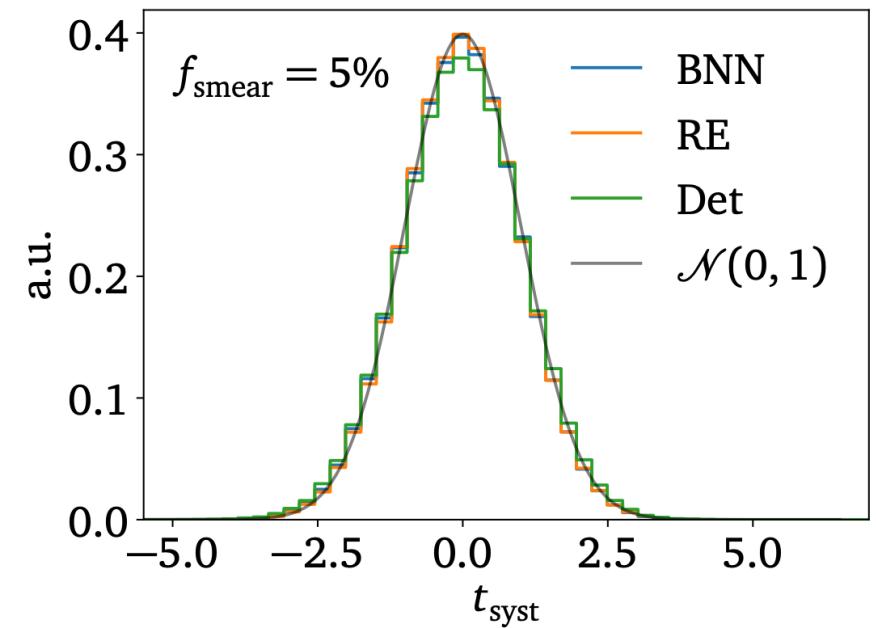
→ reliable uncertainty estimate

Are these uncertainties calibrated?

- statistical uncertainties play minor role for amplitude regression
- define systematic pull:

$$t_{\text{syst}} = \frac{\langle A \rangle(x) - A_{\text{train}}(x)}{\sigma_{\text{syst}}(x)}$$

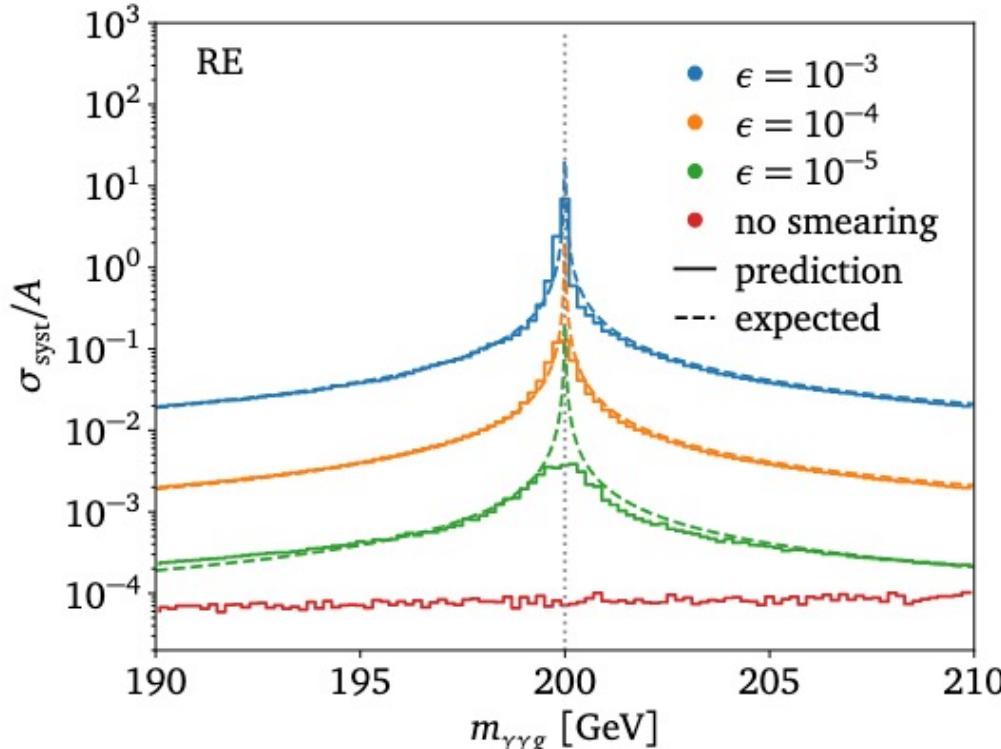
- if calibrated, t_{syst} distribution should follow $\mathcal{N}(0, 1)$



Almost perfectly calibration → reliable uncertainty estimate

Localized noise

[HB,Elmer,Plehn,Winterhalder, 2509.00155]



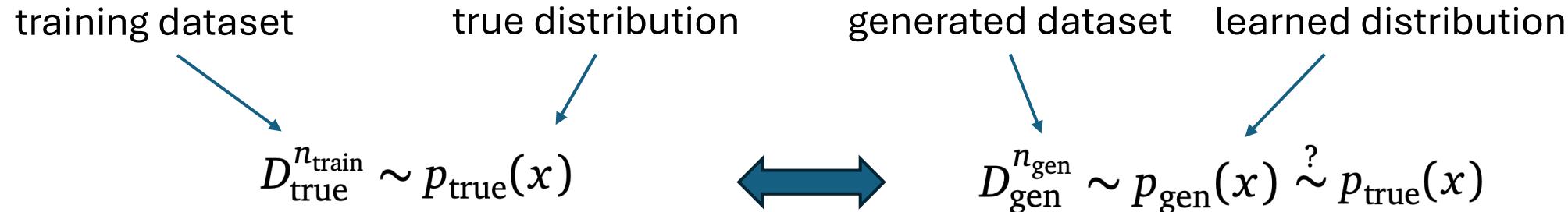
$$A_{\text{train}}(x) = \mathcal{N}\left(A_{\text{true}}(x), \frac{\epsilon m_{\text{thresh}}}{|m_{\gamma\gamma g}(x) - m_{\text{thresh}}|} A_{\text{true}}(x)\right)$$

- emulates numerical noise close to threshold
- well captured by systematic uncertainties
- NN effectively finds the mean prediction
- uncertainties still well calibrated

Same techniques also applicable to all kind of other regression problems!

Controlling generative ML

[HB,Diefenbacher,Elmer,..., 2509.08048]



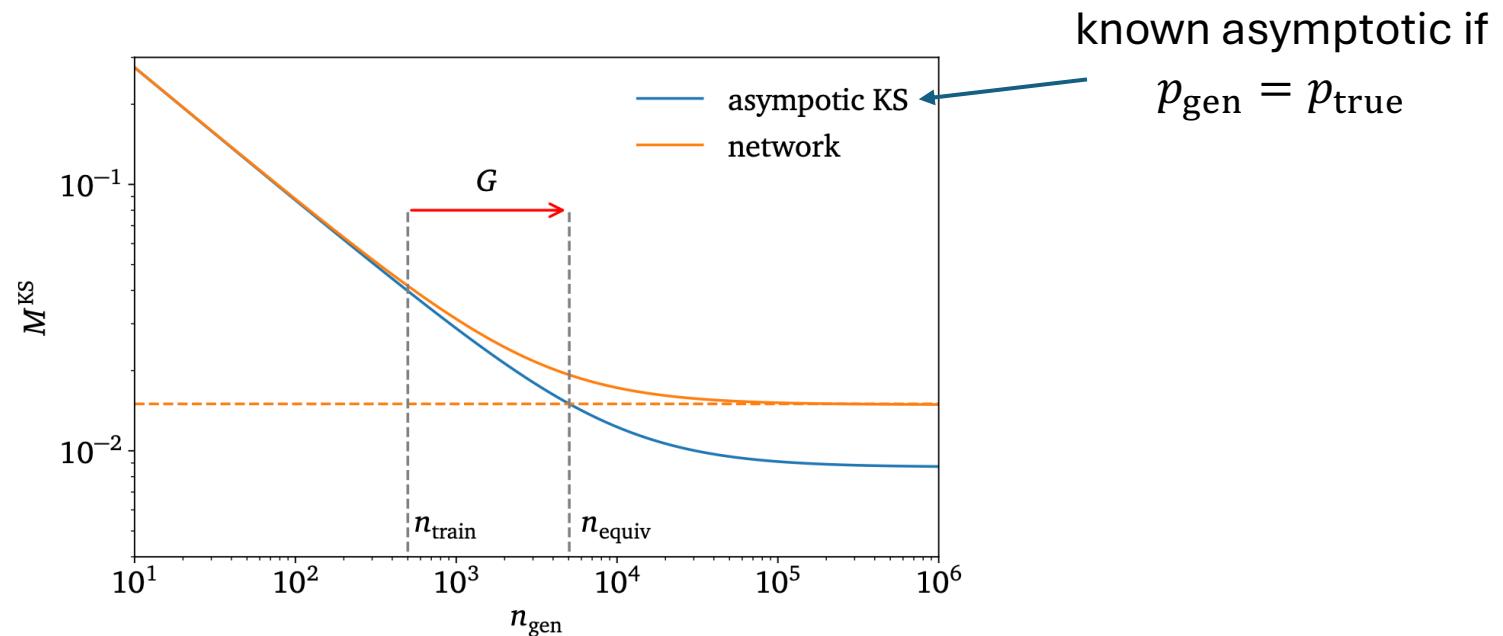
How can we quantify the performance of the generative NN?

→ determine n_{equiv} such that $M(D_{\text{true}}^{n_{\text{equiv}}}, p_{\text{true}}(x)) \equiv M(D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{true}}(x))$ with $D_{\text{true}}^{n_{\text{equiv}}} \sim p_{\text{true}}(x)$

comparison metric \rightarrow amplification factor $G = \frac{n_{\text{equiv}}}{n_{\text{train}}}$

Controlling generative ML

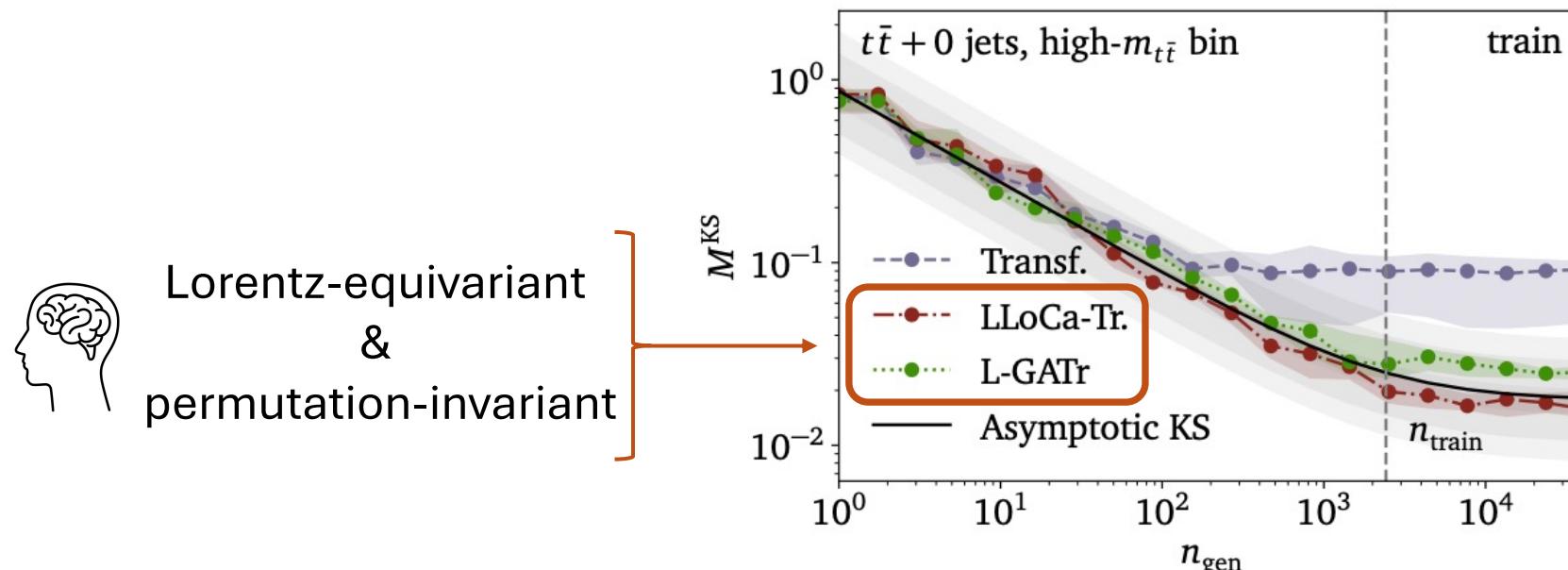
one option for M : Kolmogorov-Smirnov test comparing D_{train} and D_{gen}



→ systematic approach to assess quality of generative NNs

Controlling generative ML

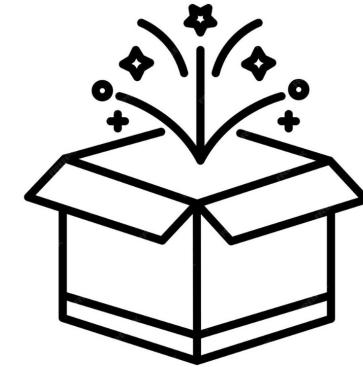
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→ systematic approach to assess quality of generative NNs

Interpretable ML

looking under the hood

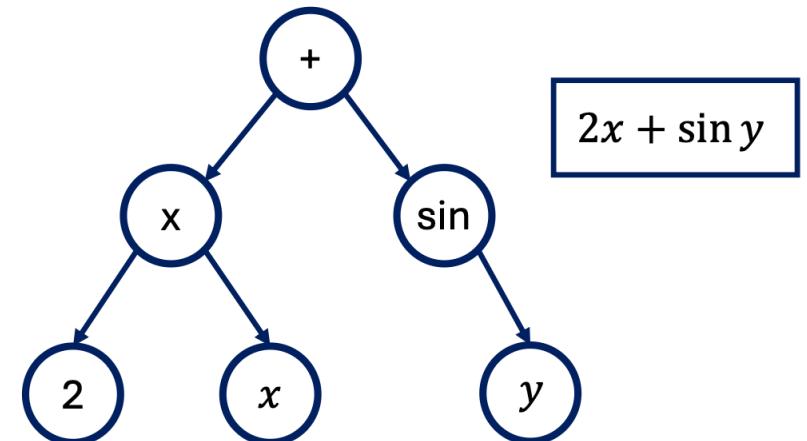


Back to the formula – symbolic regression

- many ways to make ML interpretable
- goal: find most relevant representation/observables describing the data

→ maximal interpretability: analytic equation!

- construct them dynamically using symbolic regression
[Schmidt&Lipson `09, Udrescu&Tegmark `19, Cranmer et al. `19, `20, `23]
- build upon genetic algorithm successively forming equation
- interplay between goodness-of-fit and complexity of equation



Example: Higgs CP test for VBF

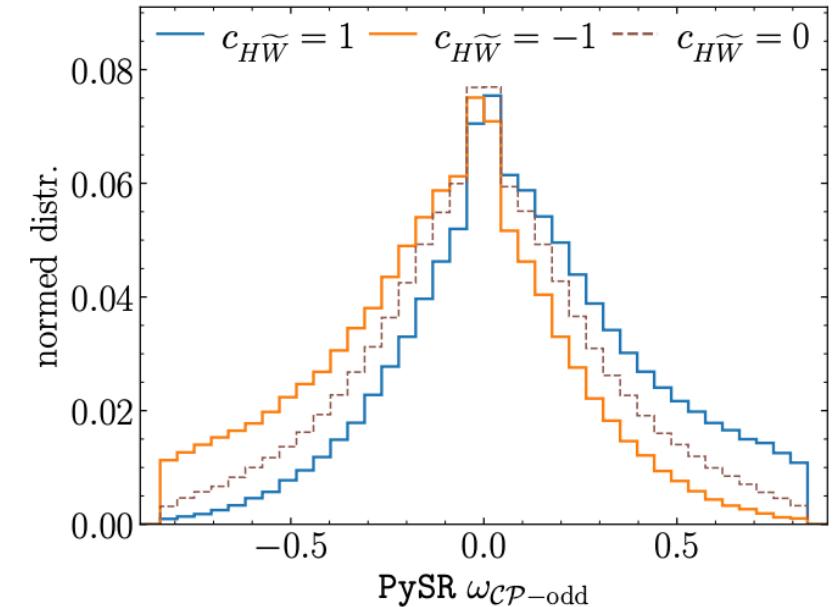
[HB,Menon,Fuchs,Plehn,2507.05858]

- consider dim-6 operator $\frac{c_{H\widetilde{W}}}{\Lambda^2} \Phi^\dagger \Phi \widetilde{W}_{\mu\nu}^a W^{a\mu\nu}$
- unambiguous CP test \rightarrow CP-odd observables
- construct optimal reco-level CP-odd obs. by training a classifier on $c_{H\widetilde{W}} = \pm 1$ samples
- analytic equation \rightarrow ensure learned observable is indeed CP-odd



$$d^{\text{PySR}} = \frac{1.8566 \sin \Delta\phi_{jj}}{\left| \frac{0.3080 x_{j_1} \log \Delta\eta_{jj} + \log \Delta\eta_{jj} \sinh(x_{j_2} - 2.5977) + 0.3080 \sinh x_h}{x_{j_1} \log \Delta\eta_{jj} + \sinh x_h} \right| + 0.6047}$$

with $x = p_T/m_h$



$ \sigma(c_{H\widetilde{W}} = 1 \text{ vs. SM}) $	
$p_{T,j_1} p_{T,j_2} \sin \Delta\phi_{jj}$	6.76
trained on $c_{H\widetilde{W}} = \pm 1$	
PySR	6.98
SymbolNet	7.07
BDT	6.71

Conclusions

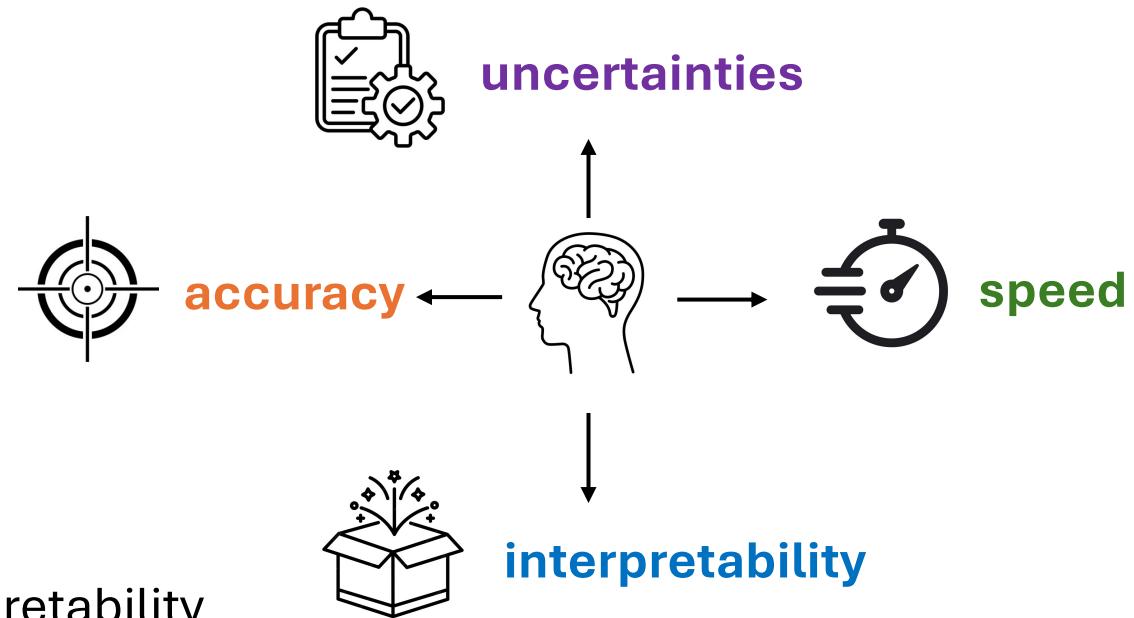


Conclusions

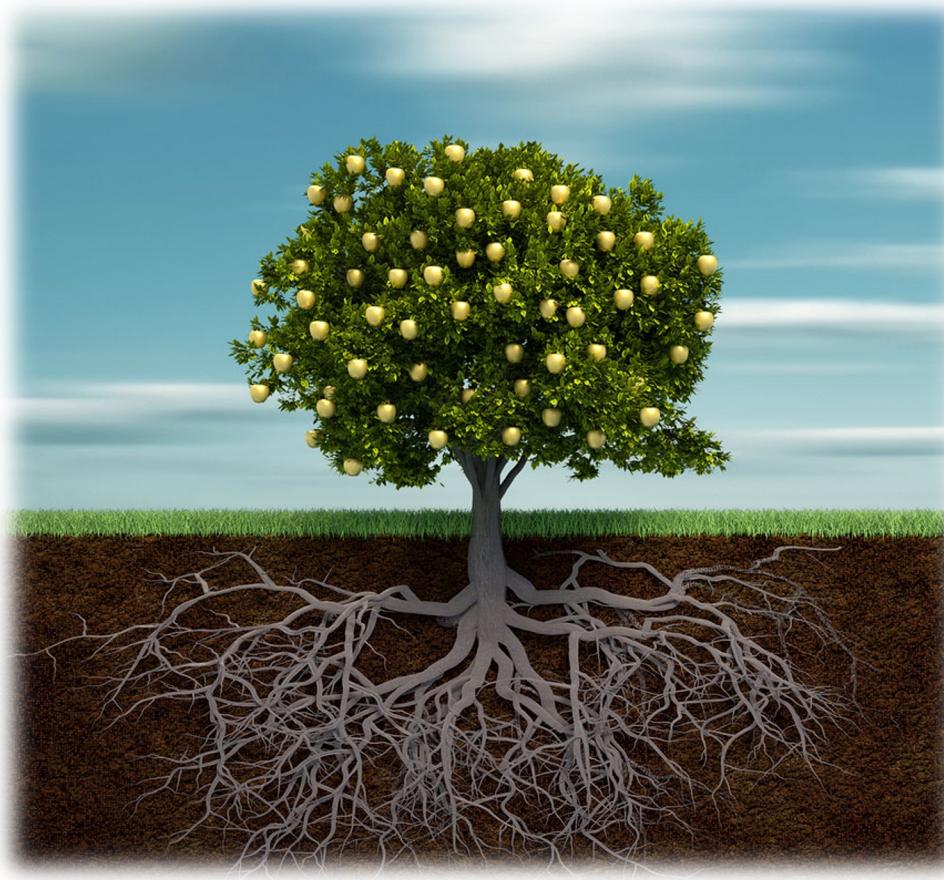
- particle physics is in the precision era
→ large amounts of multidimensional data
- ML methods excel in such an environment
- important requirements: uncertainties and interpretability
- key ingredient: representation learning based on particle theory
- methods widely applicable

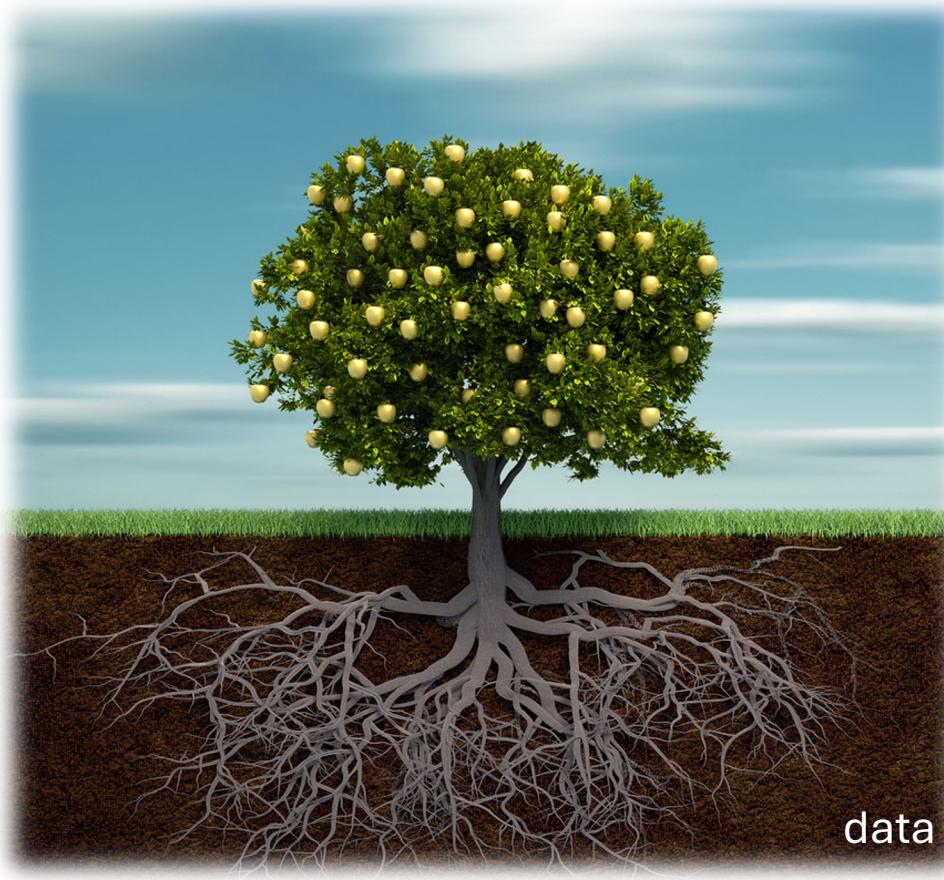


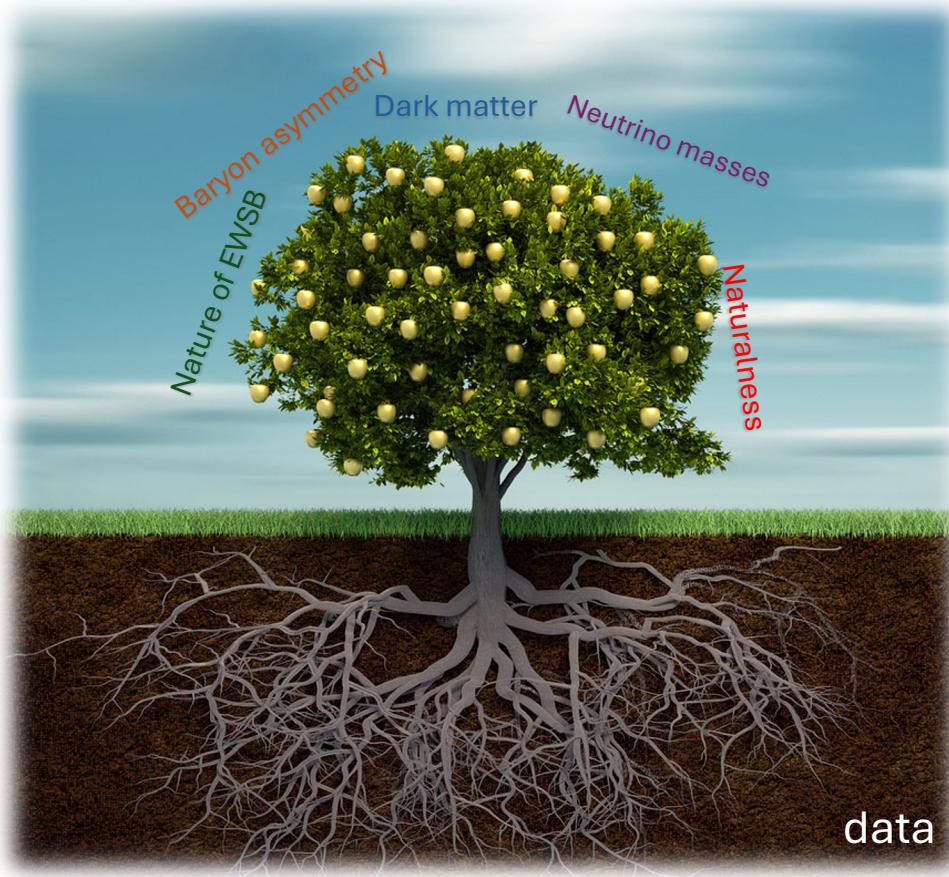
ML is an essential tool for the future of particle physics

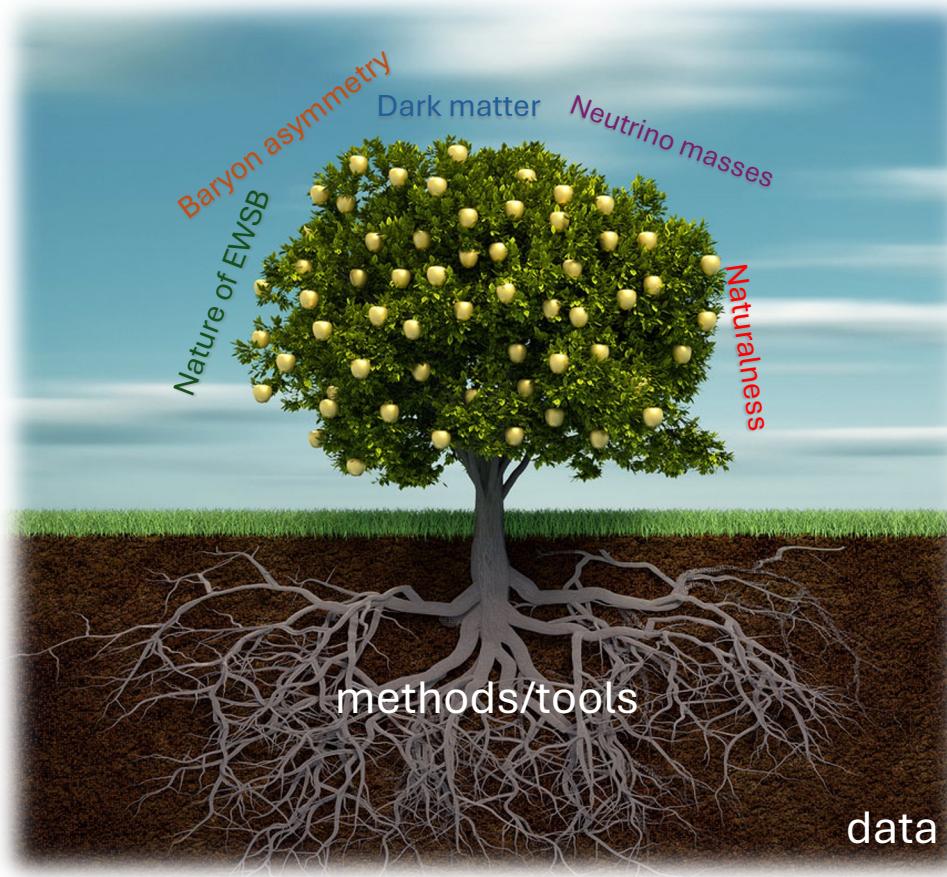


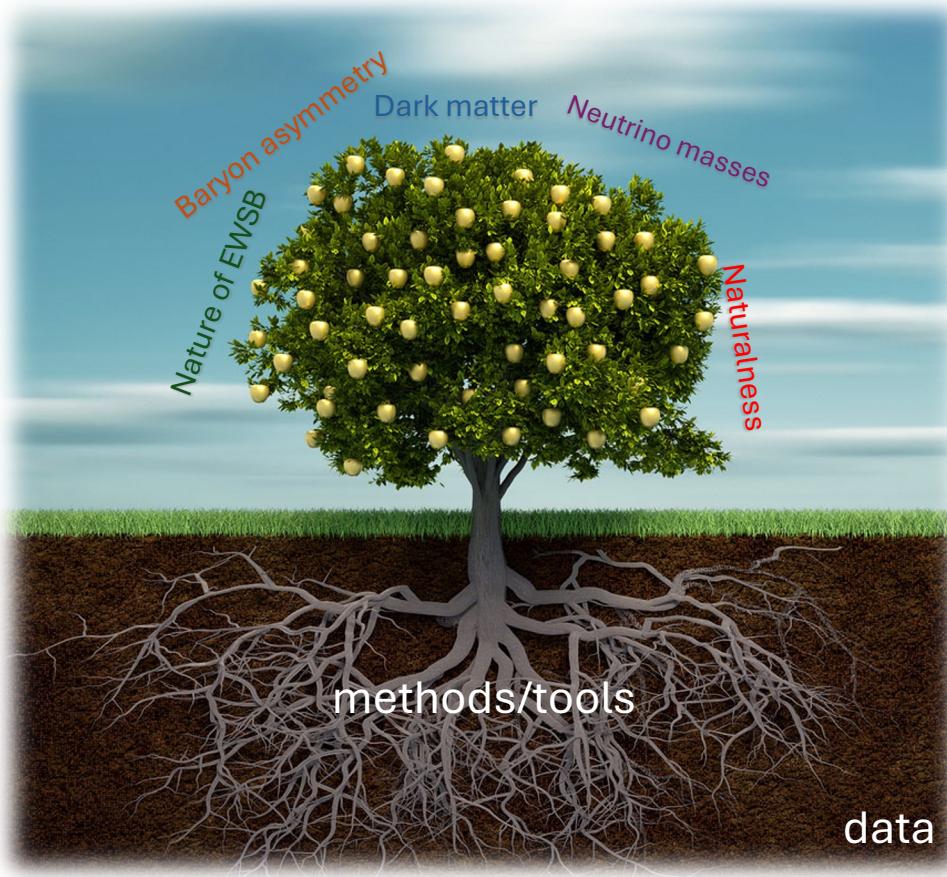
Appendix





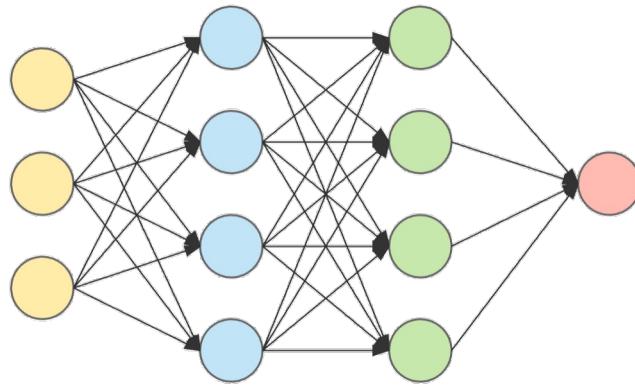






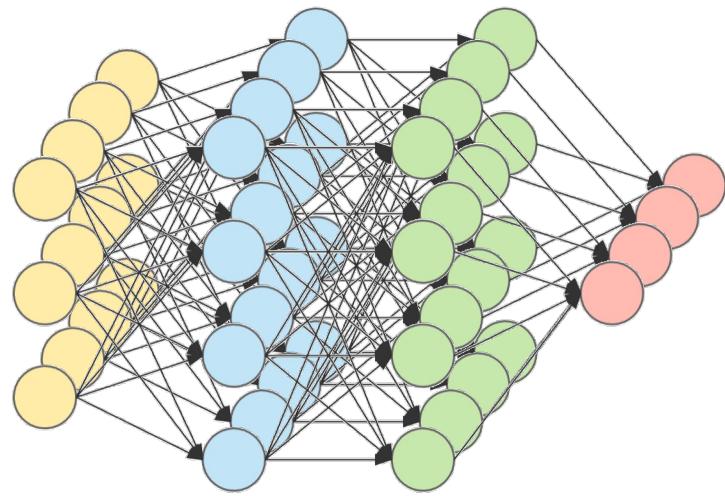
Thanks for your attention!

Modelling the statistical uncertainty

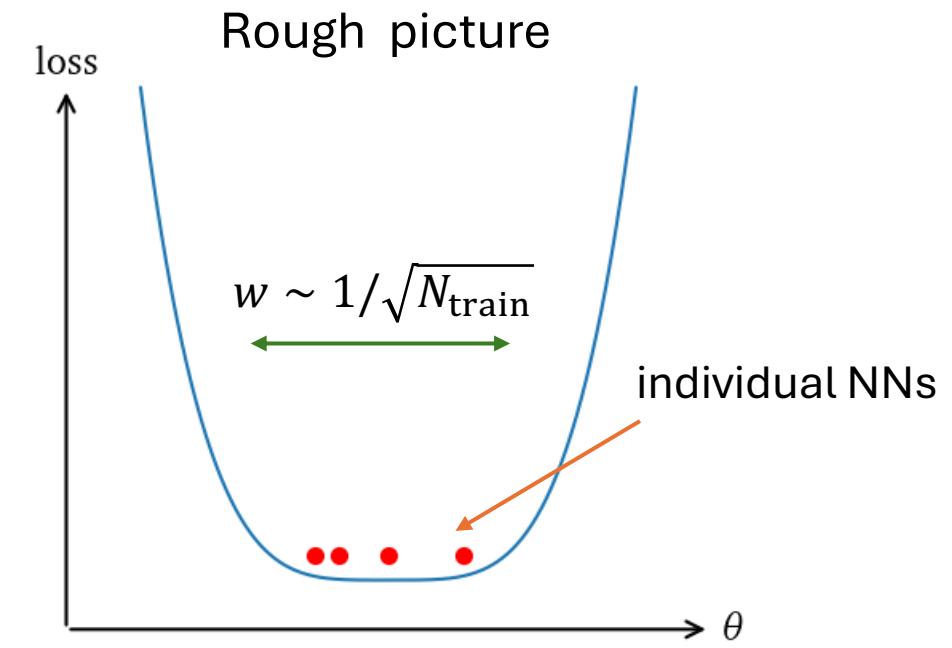


- train ensemble of networks
- each networks leads to slightly different result
- spread of network predictions \sim statistical uncertainty
- less data \rightarrow higher spread

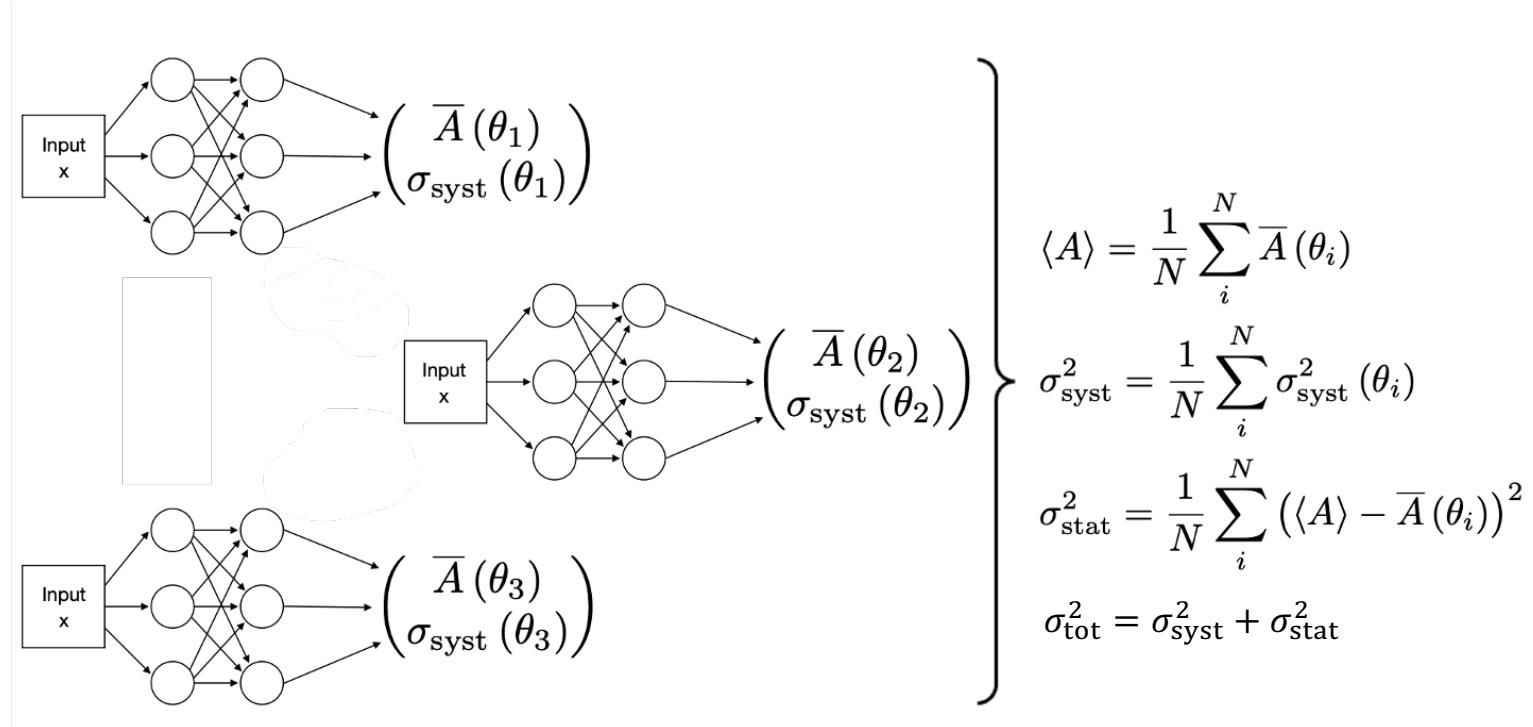
Modelling the statistical uncertainty



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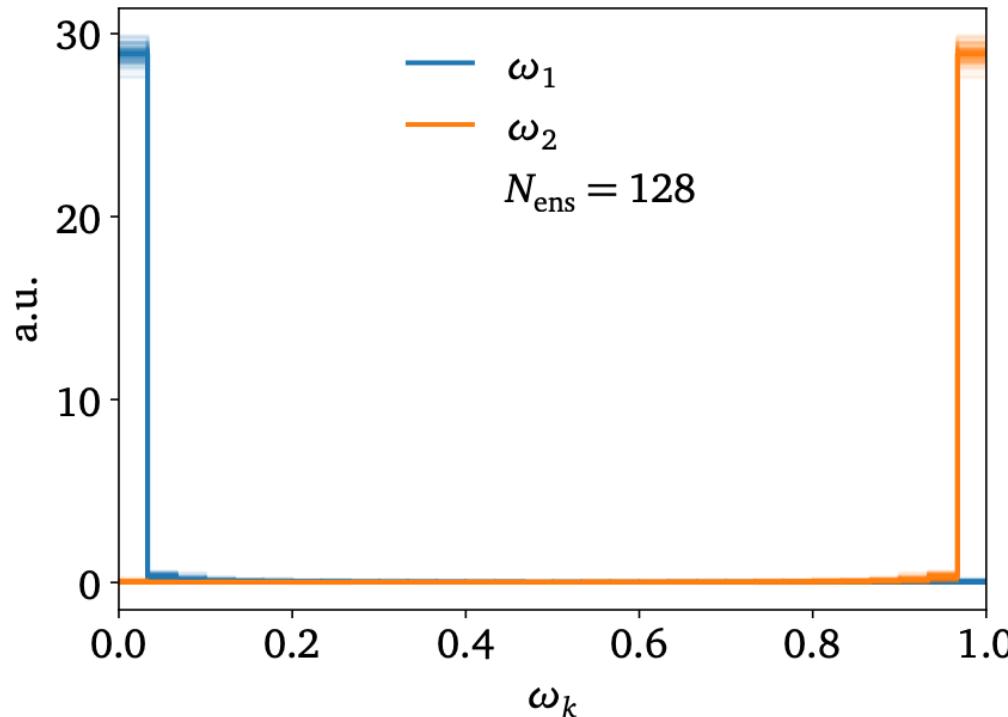
Bringing it all together



→ Combined learnable modelling of systematic and statistical uncertainties!

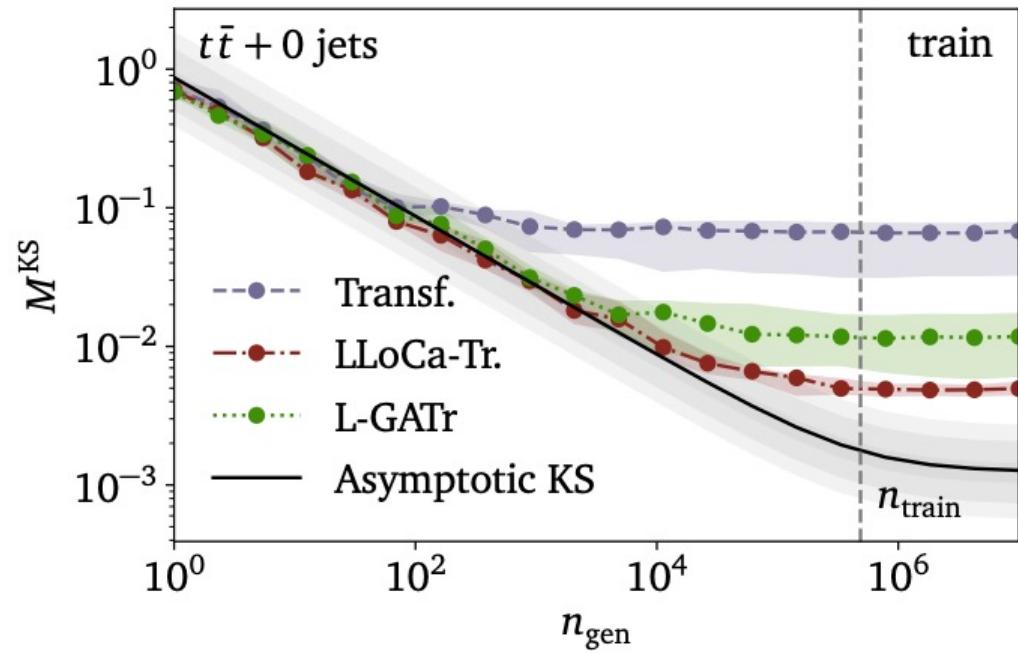
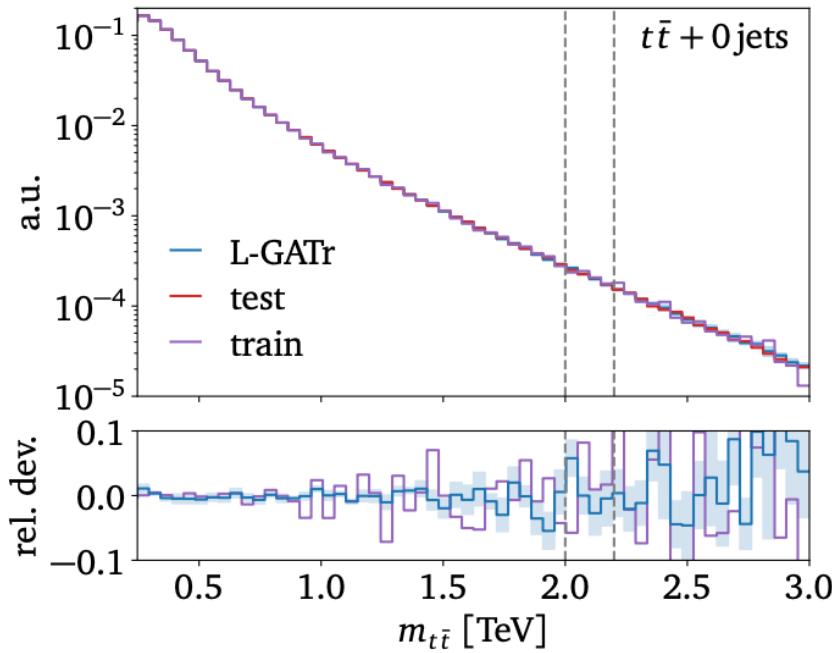
Alternative approaches: Bayesian neural networks, evidential regression

Gaussian mixture model



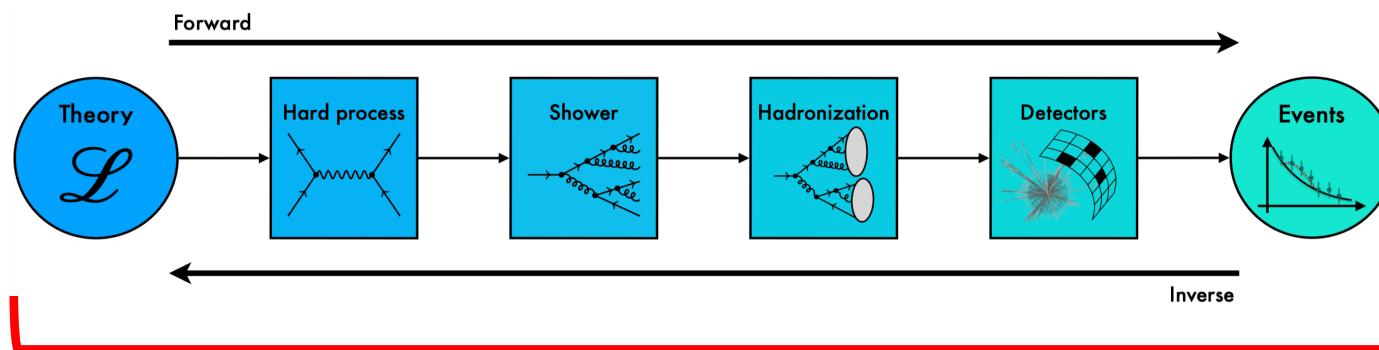
$$p_{\text{GMM}}(A|x, \theta) = \sum_{k=1}^K \omega_k(x, \theta) \mathcal{N}(A | \bar{A}_k(x, \theta), \sigma_k^2(x, \theta)), \quad \text{with} \quad \sum_{k=1}^K \omega_k(x, \theta) = 1$$

Controlling generative ML



Simulation-Based Inference

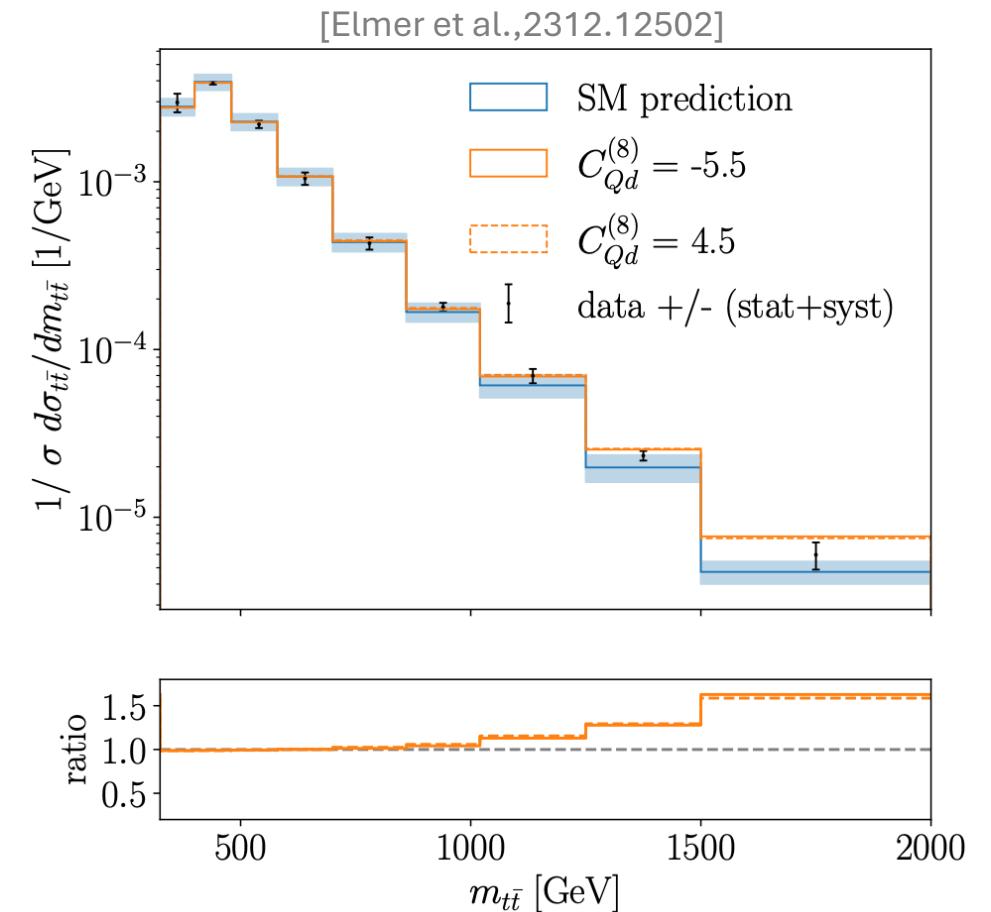
fully exploiting high-dimensional data



Classical parameter inference

- reduce dimension of phase space summary statistics
- bin summary statistics
- compare resulting histogram to SM/BSM predictions

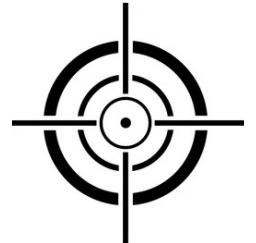
→



Advantage: humanly digestible plots

Disadvantage: loss of information

Full likelihood



- Monte-Carlo simulation chain allows us to sample full likelihood $p(x|\theta)$. But cannot directly compute it.
- Neyman-Pearson lemma: likelihood ratio $r(x|\theta, \theta_0) \equiv \frac{p(x|\theta)}{p(x|\theta_0)}$ is most powerful statistical test
- but we can regress to reco-level $r(x|\theta, \theta_0)$ using known parton-level $r(z_p|\theta, \theta_0)$:

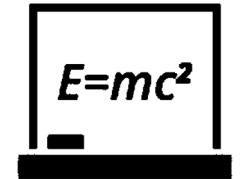
$$\mathcal{L} = \left\langle \left[r(z_p|\theta, \theta_0) - \underbrace{r_\varphi(x|\theta, \theta_0)}_{\text{NN}} \right]^2 \right\rangle_{\substack{x, z_p \sim p(x|z_p)p(z_p|\theta); \theta \sim q(\theta) \\ \text{average over event sample}}}$$



unbinned multi-dimensional inference without information loss

Encoding amplitude structure

[Schöfbeck et al., 2107.10859, 2205.12976]



Theory structure for e.g. SMEFT:

$$\mathcal{L}_{\text{SMEFT}} = \mathcal{L}_{\text{SM}} + \sum_i \frac{c_i}{\Lambda^2} O_i \equiv \mathcal{L}_{\text{SM}} + \sum_i \theta_i O_i$$

$$|\mathcal{M}(z_p|\theta)|^2 = |\mathcal{M}_{\text{SM}}(z_p)|^2 + \theta_i |\mathcal{M}_i(z_p)|^2 + \theta_i \theta_j |\mathcal{M}_{ij}(z_p)|^2$$



encode into likelihood

$$R(x|\theta, \theta_0) \equiv \frac{d\sigma(x|\theta)/dx}{d\sigma(x|\theta_0)/dx} = \frac{\sigma(\theta)p(x|\theta)}{\sigma(\theta_0)p(x|\theta_0)}$$

$$R(x|\theta, \theta_0) = 1 + (\theta - \theta_0)_i R_i(x) + (\theta - \theta_0)_i (\theta - \theta_0)_j R_{ij}(x)$$

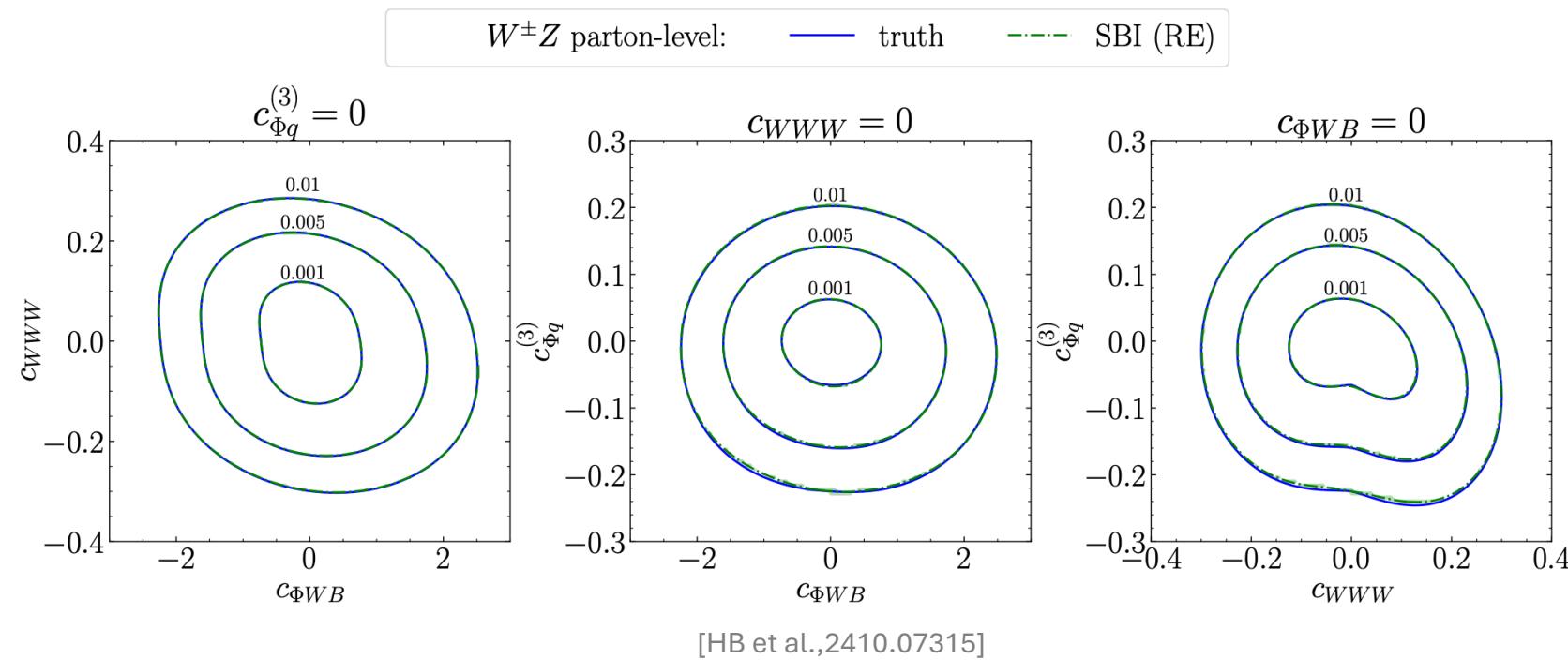
$$R_i(z_p) \equiv \frac{\partial}{\partial \theta_i} \frac{d\sigma(z_p|\theta)/dz_p}{d\sigma(z_p|\theta_0)/dz_p} \Big|_{\theta=\theta_0} = \frac{\partial_{\theta_i} |\mathcal{M}(z_p|\theta)|^2}{|\mathcal{M}(z_p|\theta_0)|^2} \Big|_{\theta_0}$$

$$R_{ij}(z_p) \equiv \frac{\partial^2}{\partial \theta_i \partial \theta_j} \frac{d\sigma(z_p|\theta)/dz_p}{d\sigma(z_p|\theta_0)/dz_p} \Big|_{\theta=\theta_0} = \frac{\partial_{\theta_i} \partial_{\theta_j} |\mathcal{M}(z_p|\theta)|^2}{|\mathcal{M}(z_p|\theta)|^2} \Big|_{\theta_0}$$

→ learn coefficients $R_{i,j}$ separately → theory parameter dependence fully factored out

Parton-level cross-check: $W^\pm Z$ production

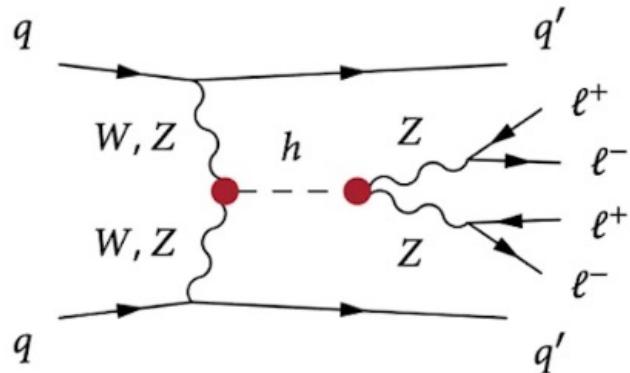
- consider effects of three SMEFT operators



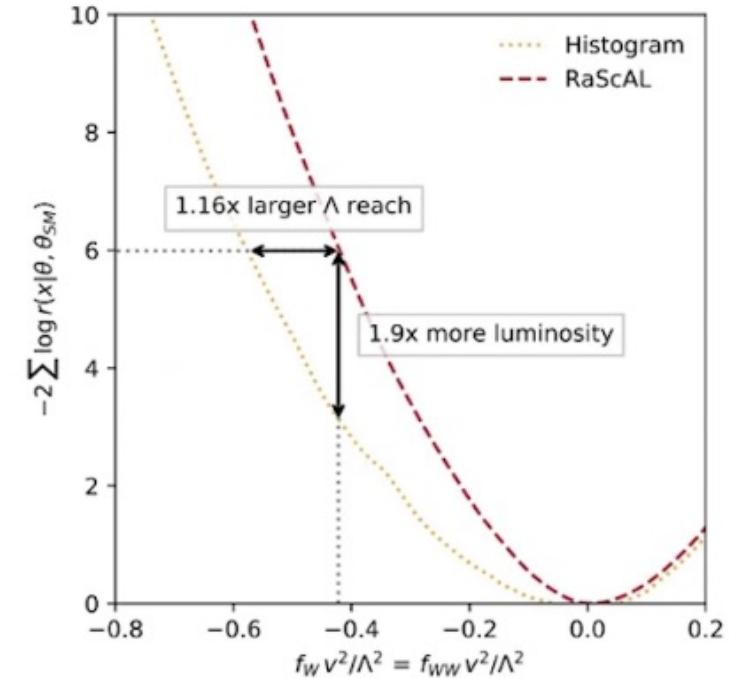
almost perfectly learns high-dimensional likelihood

Reco-level: VBF with $H \rightarrow 4\ell$

[Brehmer et al., 1805.00013]



$$\mathcal{L} = \mathcal{L}_{SM} + \boxed{\frac{f_W}{\Lambda^2}} \underbrace{\frac{ig}{2} (D^\mu \phi)^\dagger \sigma^a D^\nu \phi W_{\mu\nu}^a}_{\mathcal{O}_W} - \boxed{\frac{f_{WW}}{\Lambda^2}} \underbrace{\frac{g^2}{4} (\phi^\dagger \phi) W_{\mu\nu}^a W^{\mu\nu a}}_{\mathcal{O}_{WW}}$$



→ Huge potential to improve sensitivity of a wide variety of measurements/searches

But is SBI also viable in a realistic analysis including uncertainties etc.?

