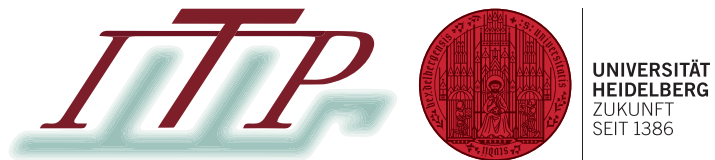


ML for particle physics in the precision era

Henning Bahl



HEP seminar, Universität Tübingen, 5.10.2025

The goal of particle physics

→ Answer the big fundamental questions!

Nature of EWSB

Neutrino masses

.....

Dark matter

Baryon asymmetry

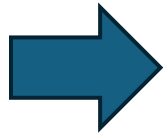
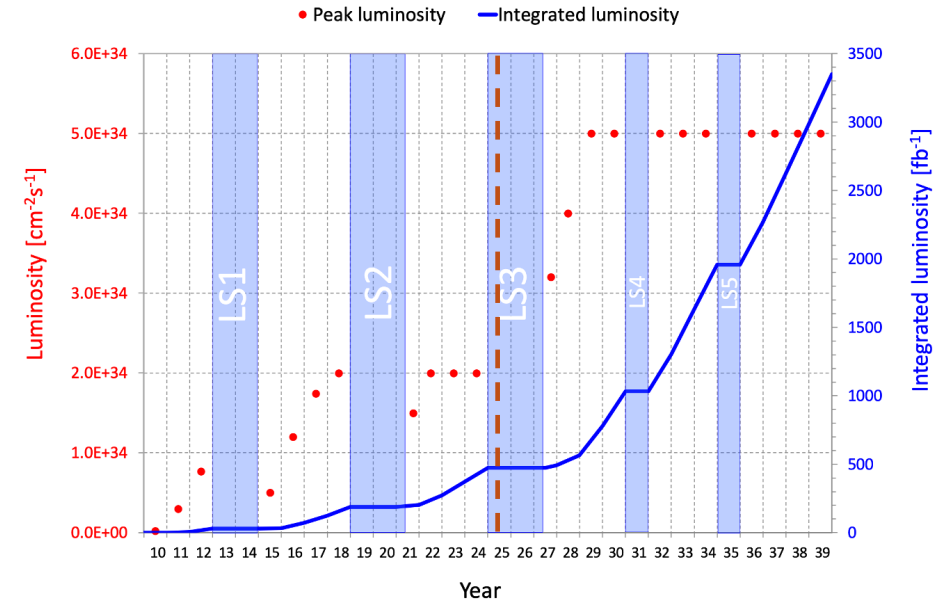
Naturalness

Can ML find answer these questions for us? **No!**

Can it help us with it? **Yes!**

The challenge ahead

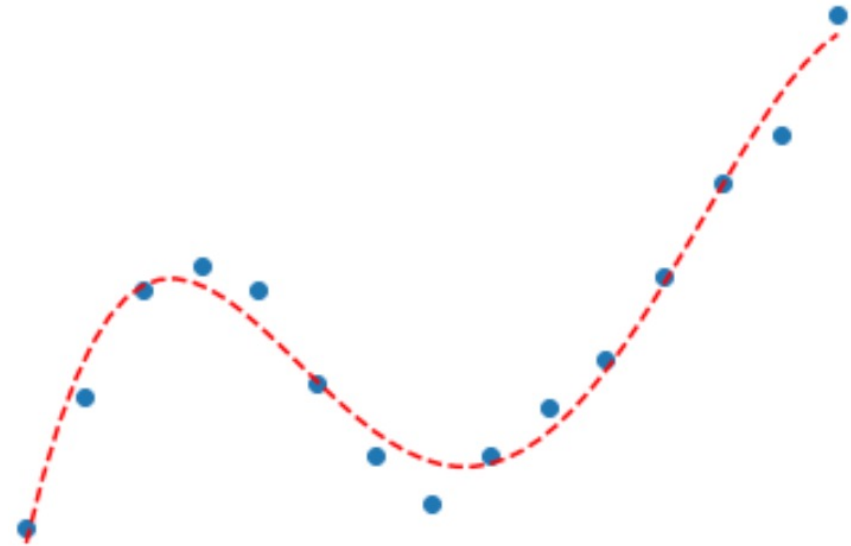
- general trend: larger-and-larger experiments collecting more-and-more data
- e.g. LHC: already enormous dataset will be further enlarged by a factor ~ 10
- costs for future experiments increasing



Fully exploit the available data!

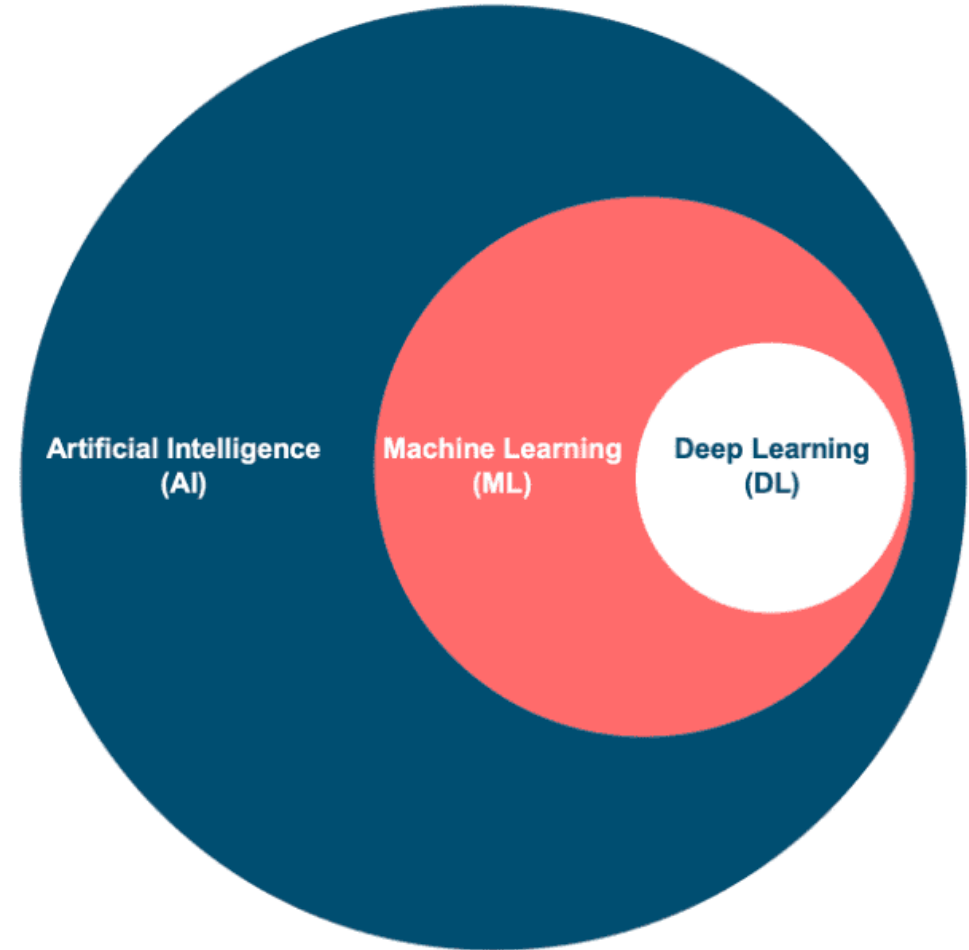
- new analysis methods
- theory precision \simeq experimental precision
- in particular: high-precision MC simulation

ML in a nutshell

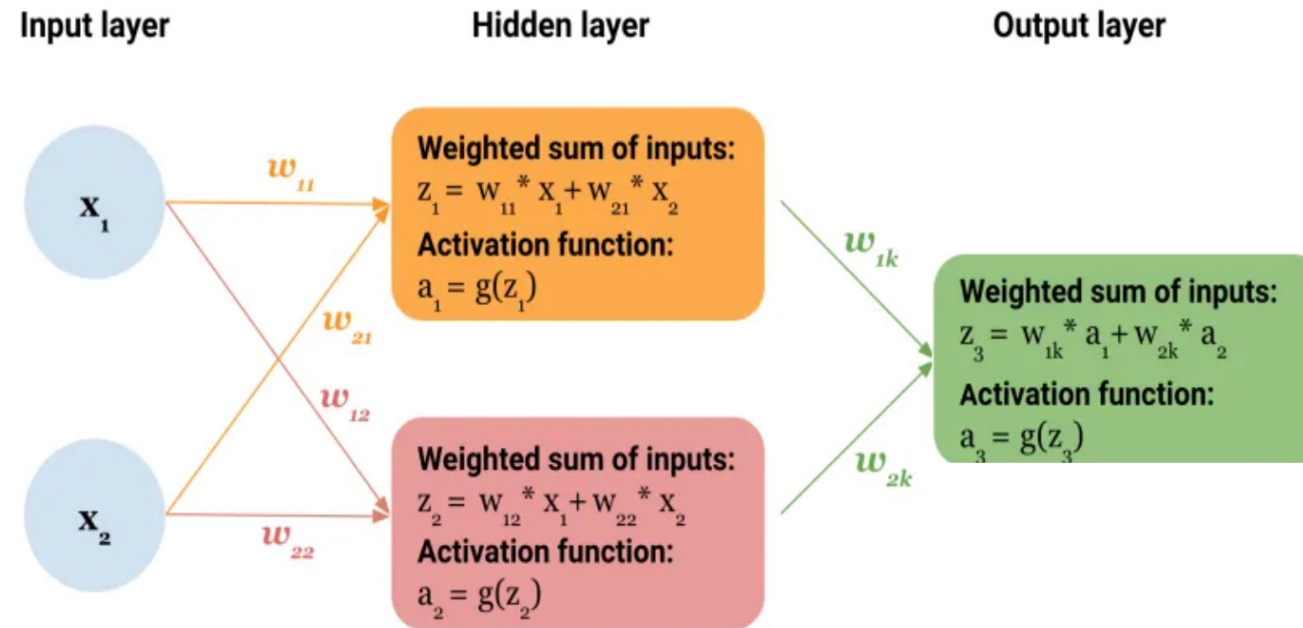


Terminology

- **Artificial Intelligence (AI)**
 - machines performing complex tasks
 - e.g. Feynman diagram generators, ...
- **Machine Learning (ML)**
 - subfield of AI where machines learn from data
 - e.g. linear regression, BDTs, ...
- **Deep Learning (DL)**
 - subfield of ML using deep neural networks



Neural networks

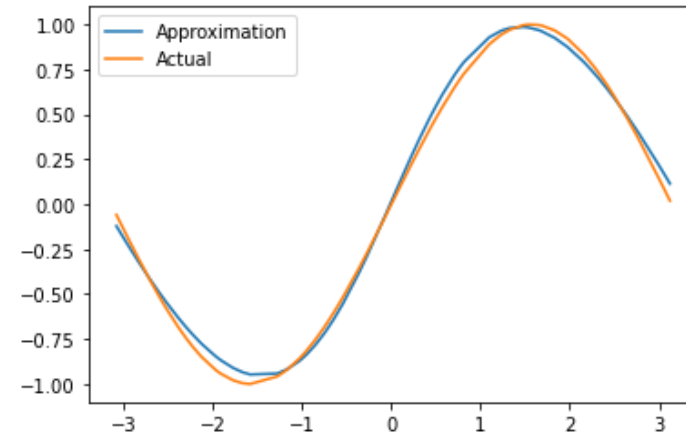
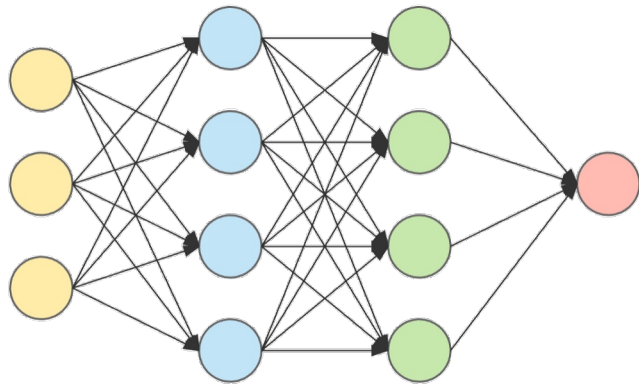


- activation introduces non-linearity (e.g. $g(x) = \max(0, x)$)
- adjust weights by minimizing loss

The Universal Approximation Theorem

Theorem (informal):

“A feedforward neural network with enough neurons can approximate any continuous function with arbitrary accuracy.”



Limitations in practice:

1) amount of **training data**, 2) **size** of NN, and 3) **compute** spent for training

Types of ML (selection)

Tasks

- regression (e.g. calorimeter calibration)
- classification (e.g. jet tagging)
- generation (e.g. event generation)


Learning types

- supervised (e.g. amplitude regression)
- unsupervised (e.g. data clustering)
- semi-supervised (e.g. anomaly detection)

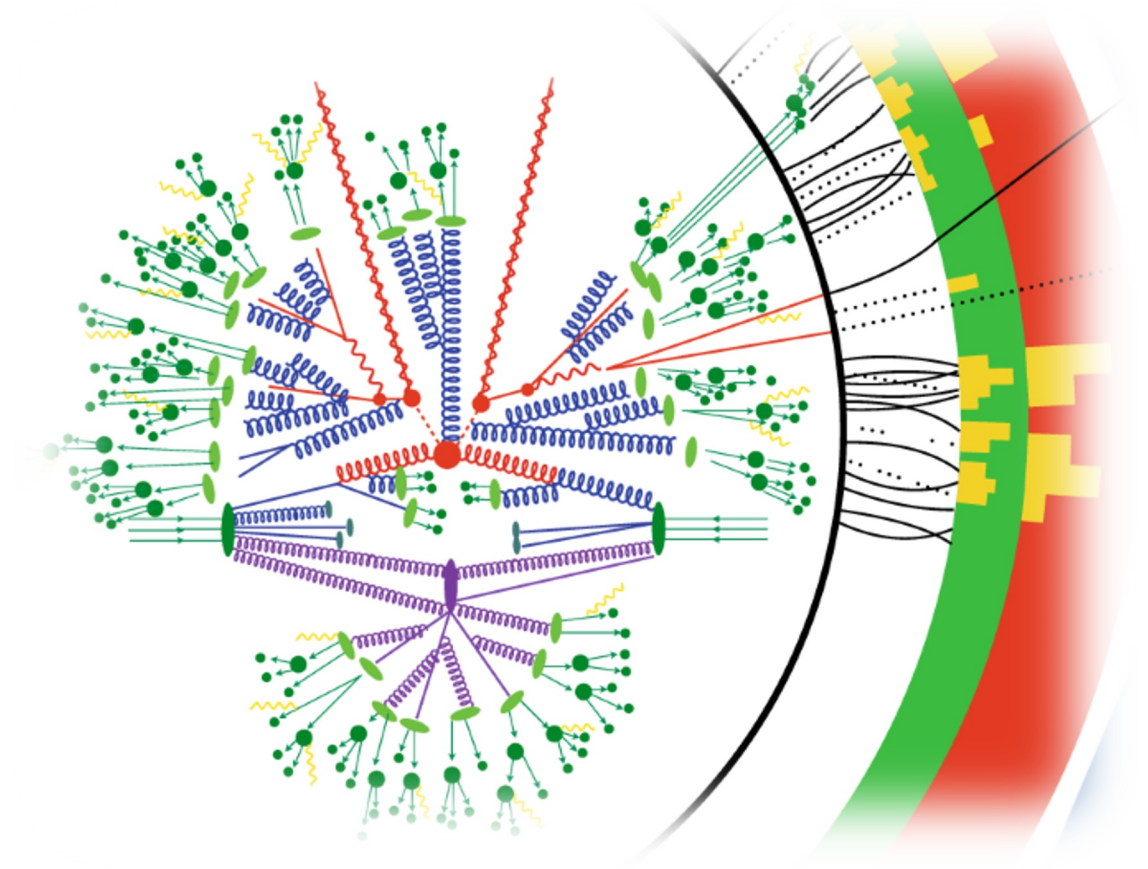
ML workflow

1. define the problem
2. collect and preprocess the dataset
3. define your ML model
4. training
5. evaluation

ML workflow

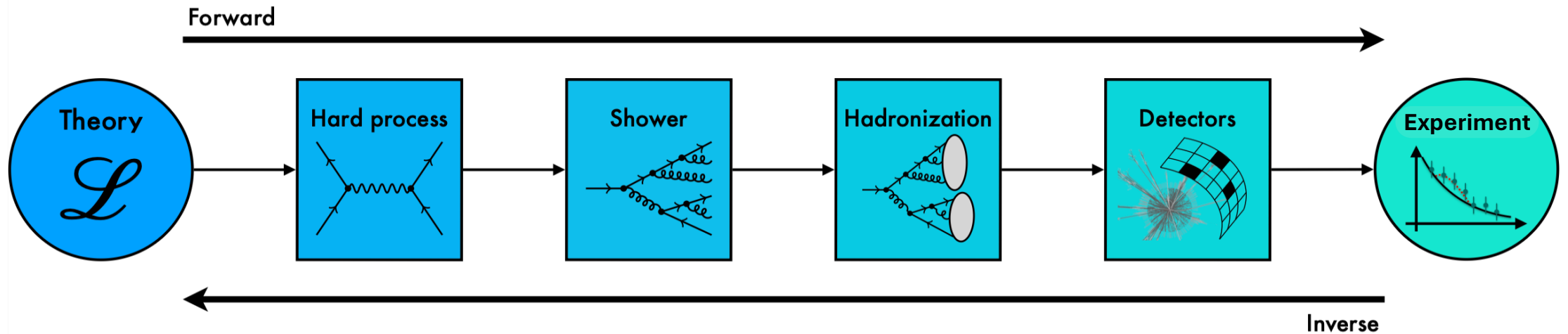
1. define the problem
 2. collect and preprocess the dataset
 3. define your ML model
 4. training
 5. evaluation
- 
- ML strategy — *multiple ways to approach problem*
 - loss — *what objective do I want to optimize?*
 - architecture — *what is the best structure for my NN?*
 - encode physics knowledge — *symmetries, ...*

ML for particle physics



[Iulia Georgescu, 2021]

The particle physics workflow



ML can help with each of these steps by increasing

- accuracy/performance
- speed

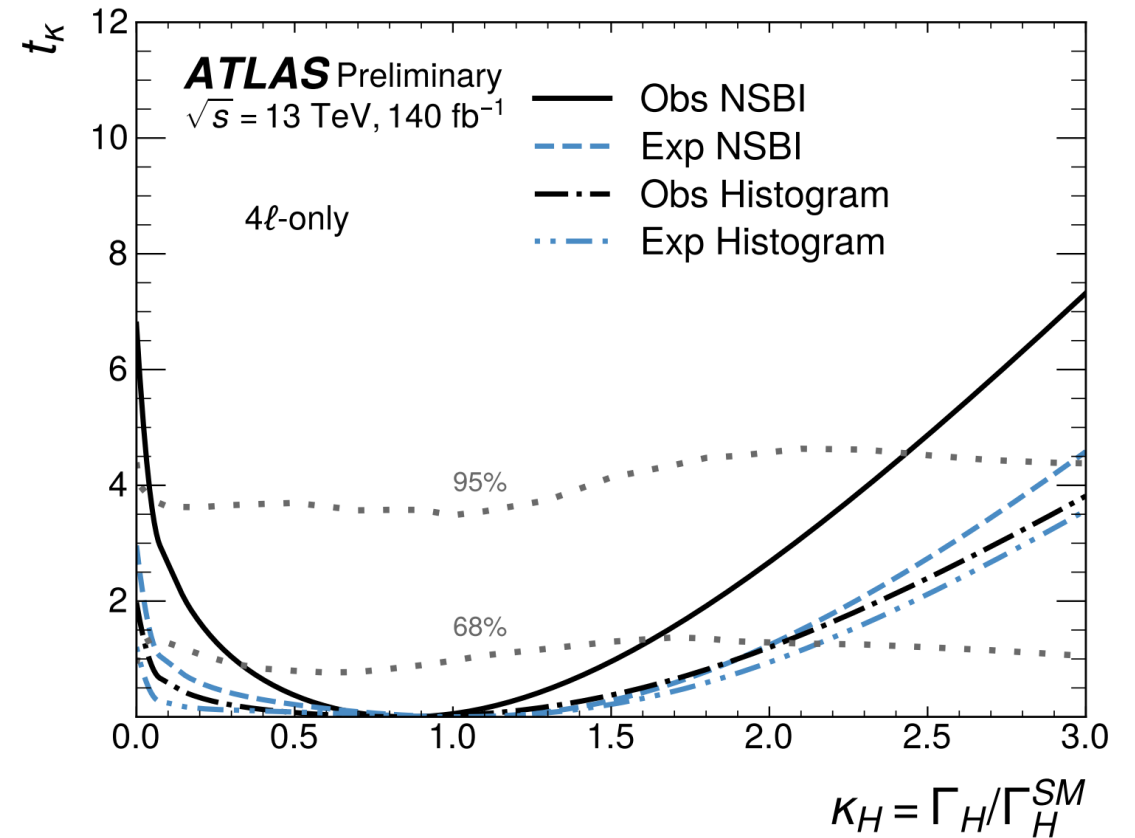
Motivating example: simulation-based inference

- simulation-based inference (SBI) allows to exploit full kinematic information
- significant improvement in comparison to histogram approach

Motivating example: simulation-based inference

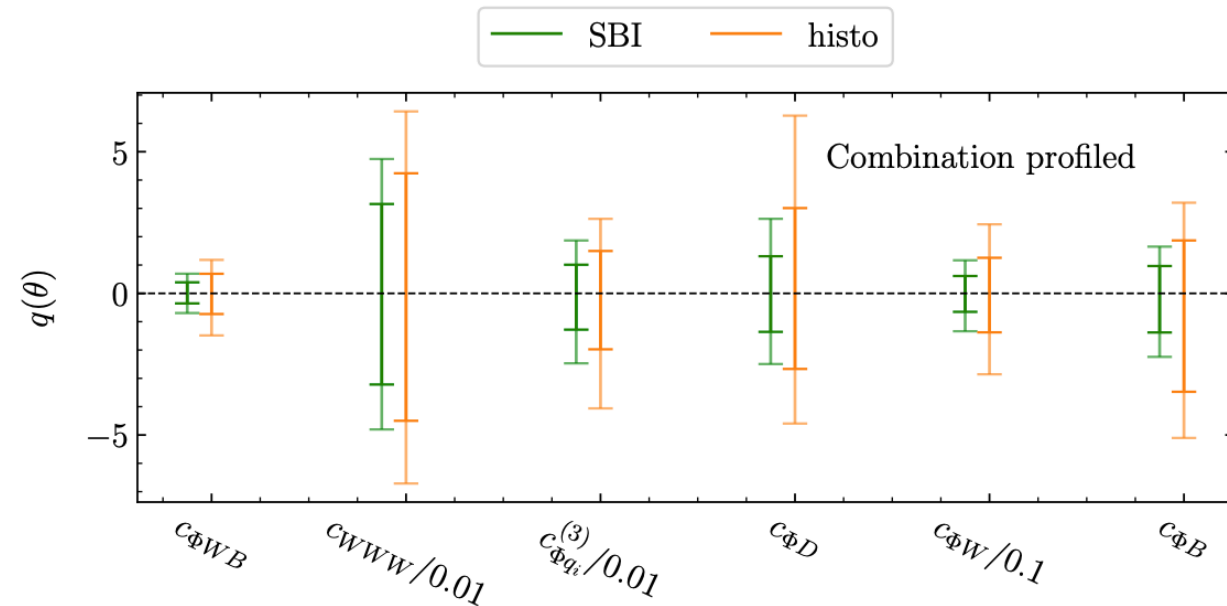
- simulation-based inference (SBI) allows to exploit full kinematic information
- significant improvement in comparison to histogram approach
- 1st experimental analysis: measure off-shell signal strength in $H \rightarrow ZZ$ channel

[ATLAS-CONF-2024-016]



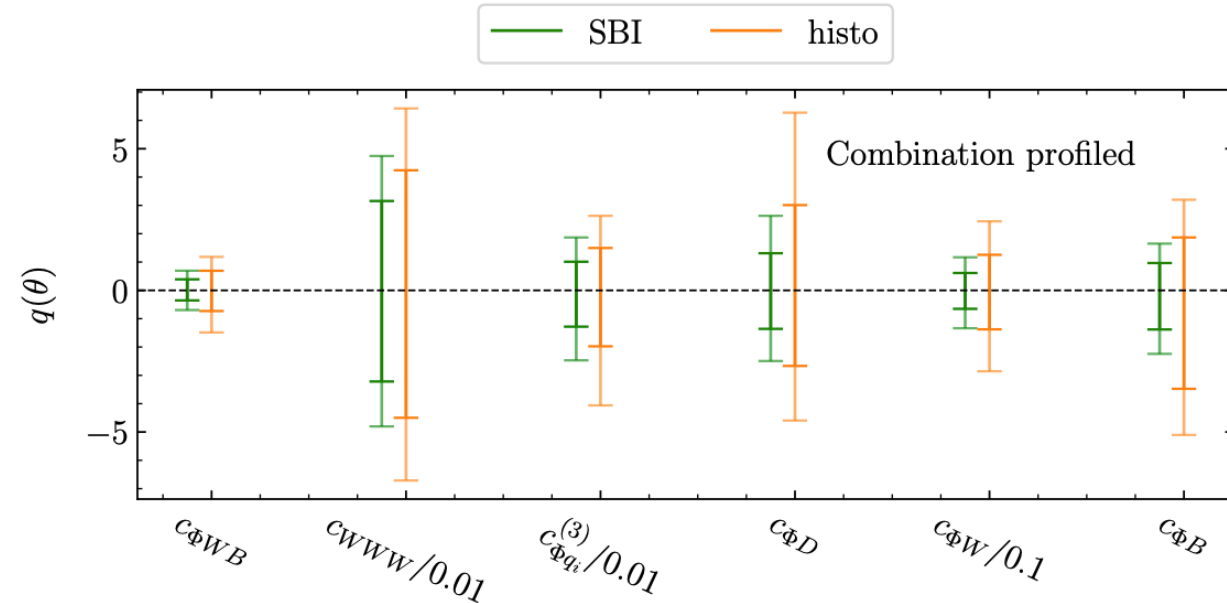
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[ATLAS-CONF-2024-016]
- also persists in global analyses
[HB,Plehn,Schmal,2509.05409]



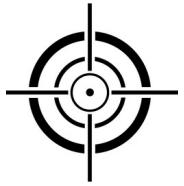
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[ATLAS-CONF-2024-016]
- also persists in global analyses
[HB,Plehn,Schmal,2509.05409]



➡ What is needed to apply ML successfully?

ML for particle physics



accuracy



speed

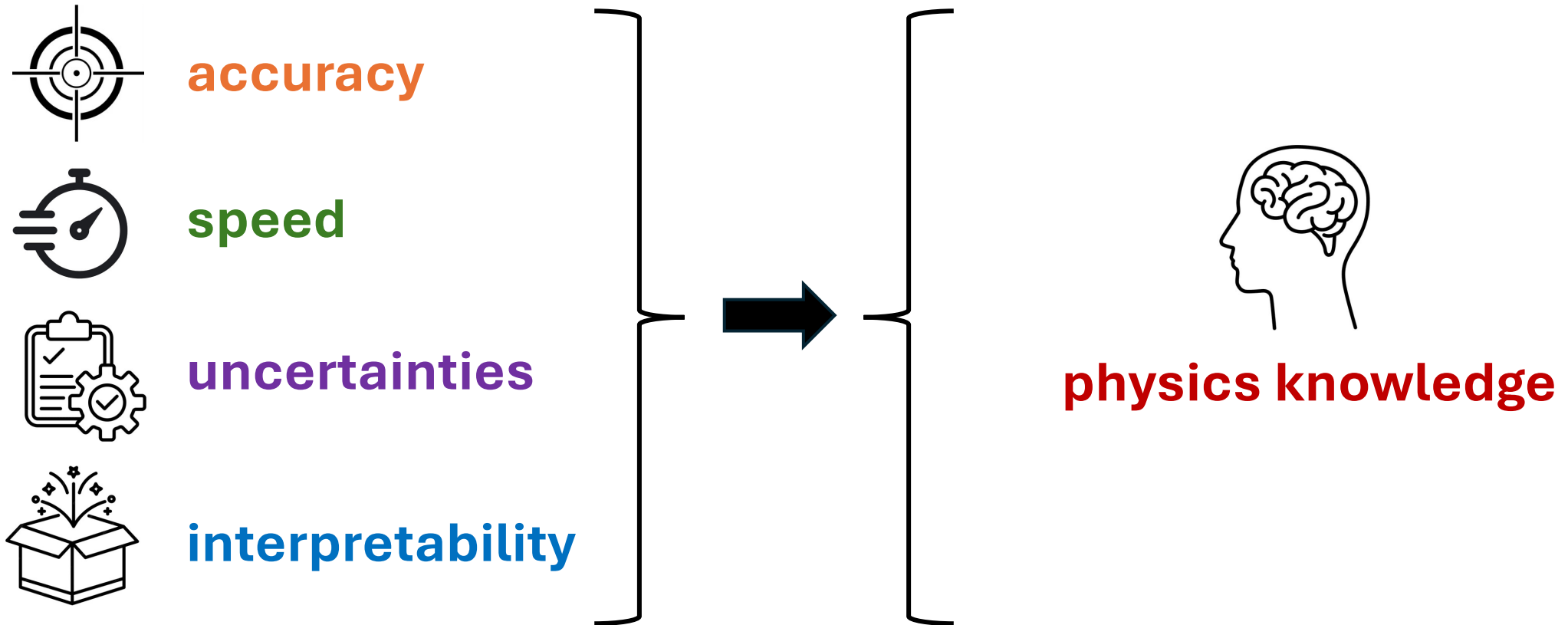


uncertainties

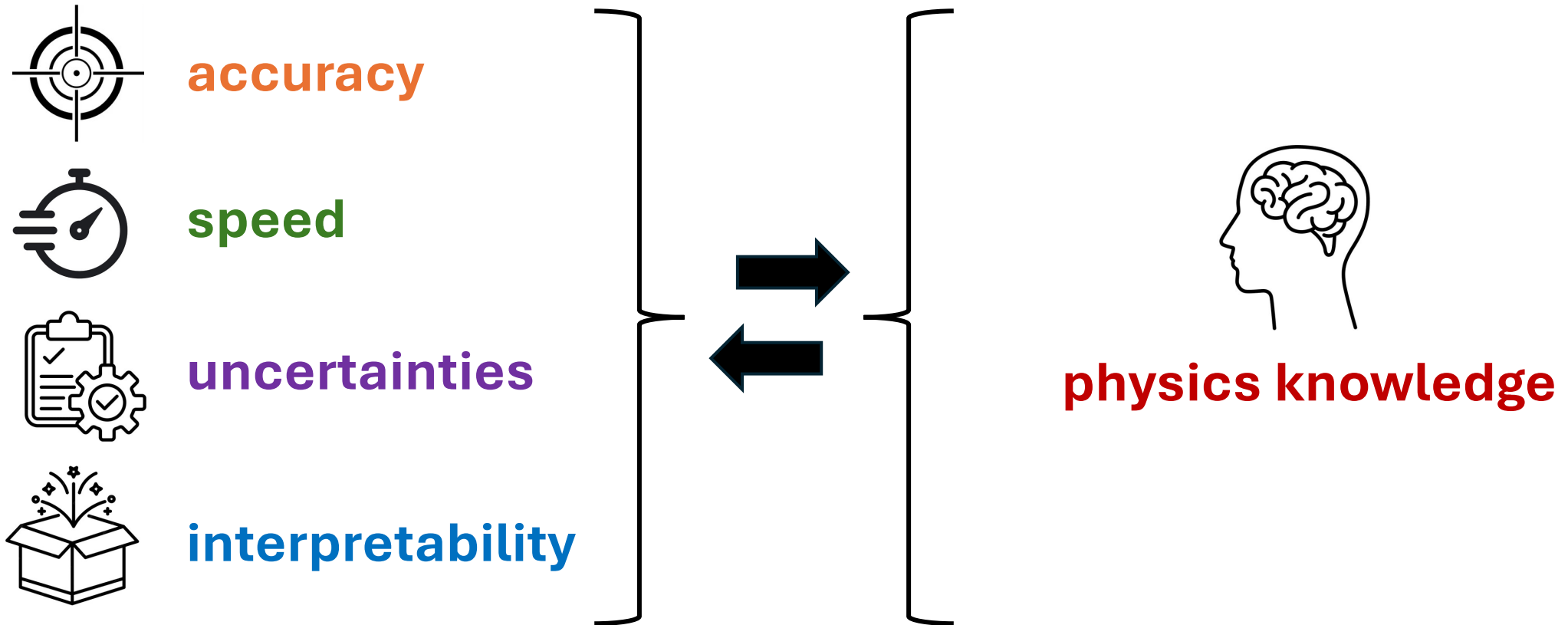


interpretability

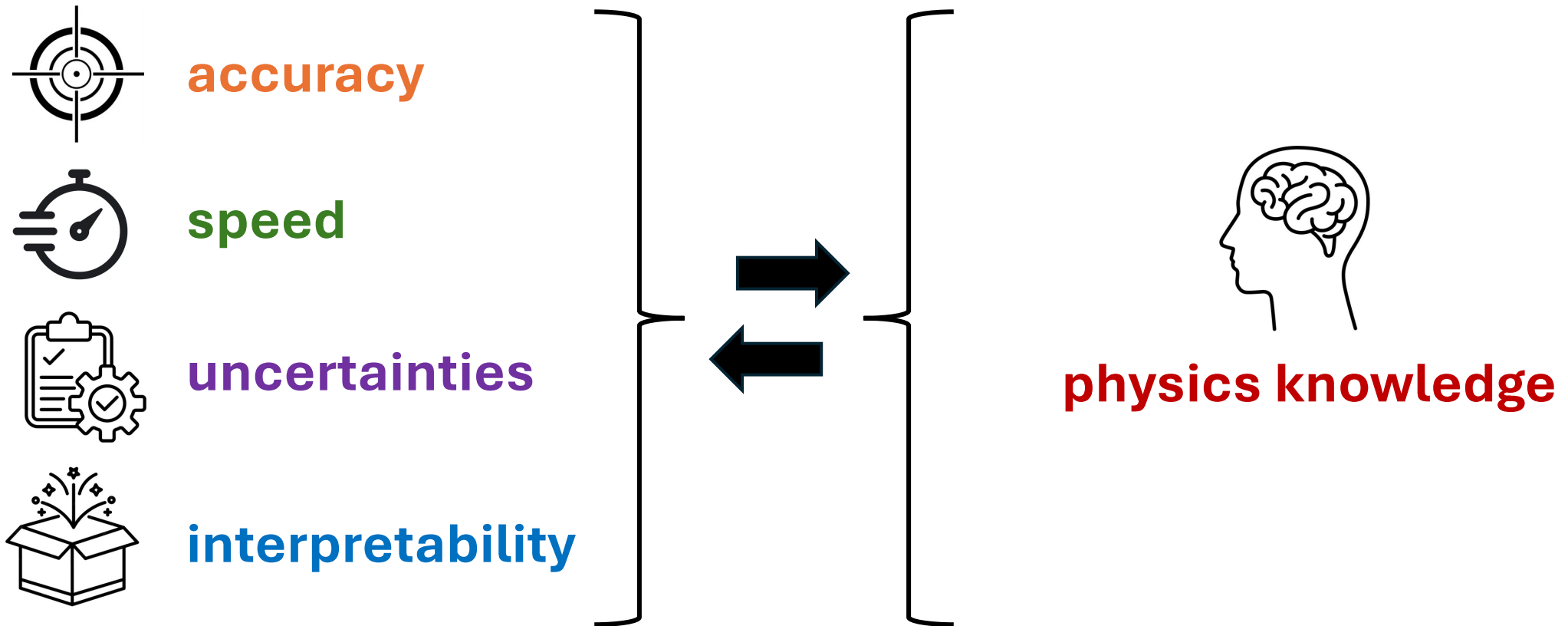
ML for particle physics



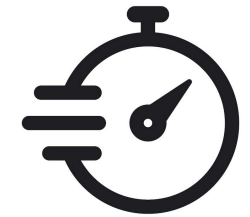
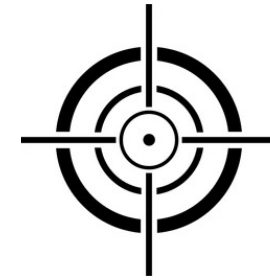
ML for particle physics



ML for particle physics

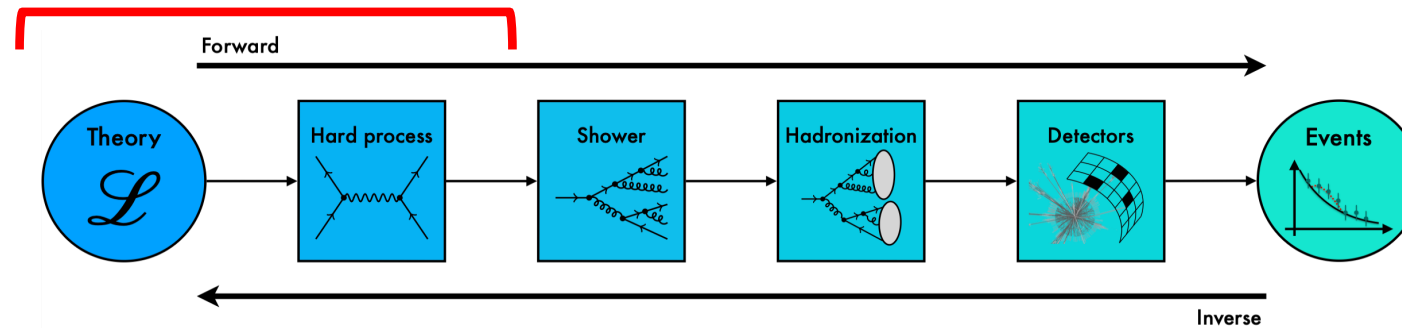


➡ Key to all these aspects: finding good representations of the data



Accuracy & speed

fast higher-order amplitude surrogates



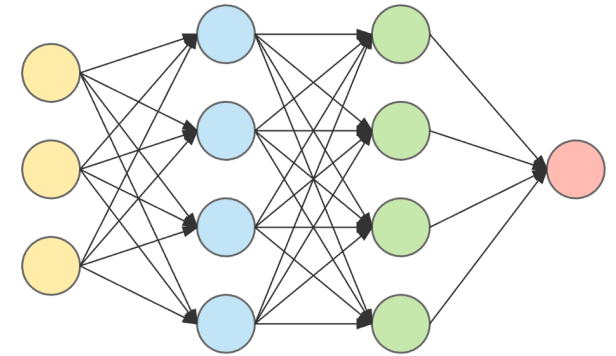
Amplitude surrogates

- evaluating analytic expressions for amplitudes $|\mathcal{M}|^2$ can be very expensive due to
 - higher-order corrections
 - large final-state multiplicities

- idea:
 - generate small training sample using full analytic expression
 - train a NN to approximate $|\mathcal{M}|^2$
 - generate events using NN surrogate \rightarrow fast to evaluate

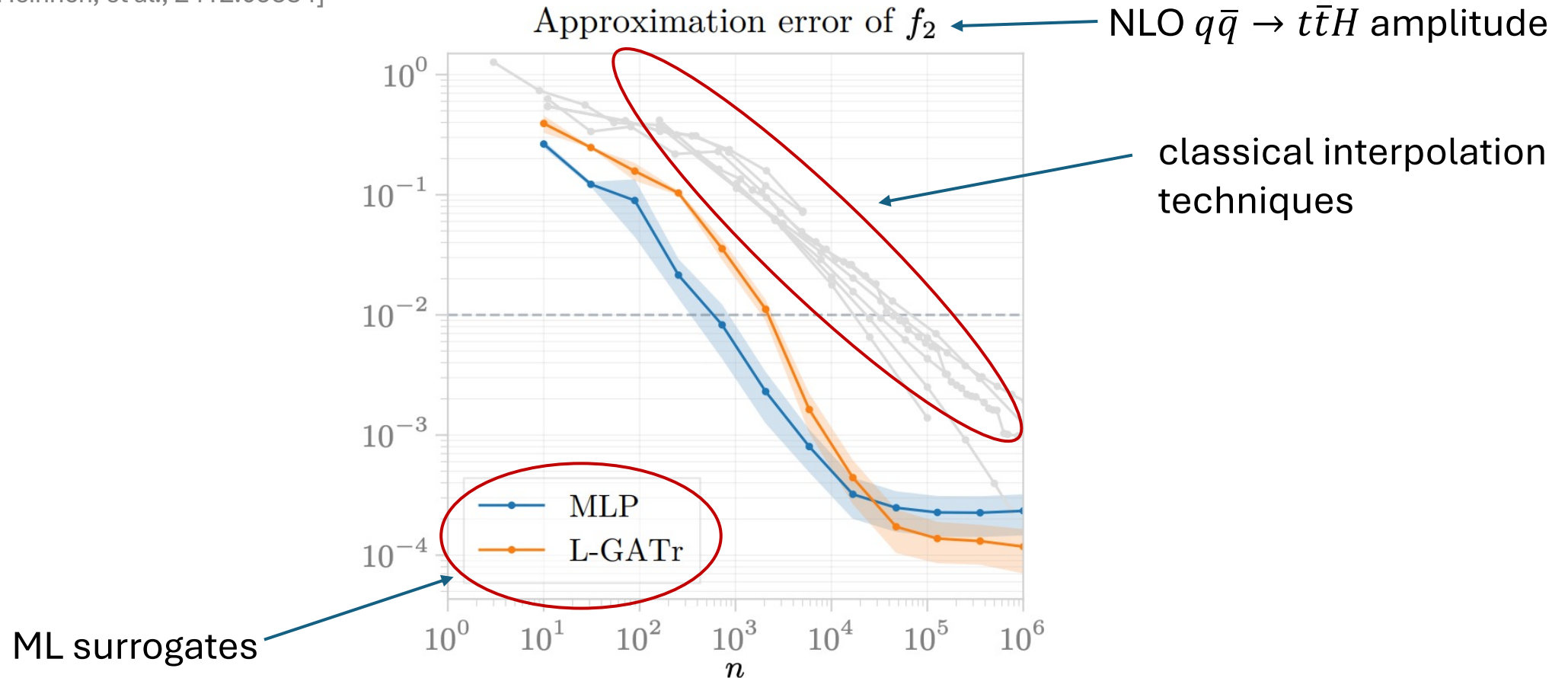
\rightarrow fast high-precision event generation

$$|\mathcal{M}|^2 \approx$$



Comparison to classical interpolation

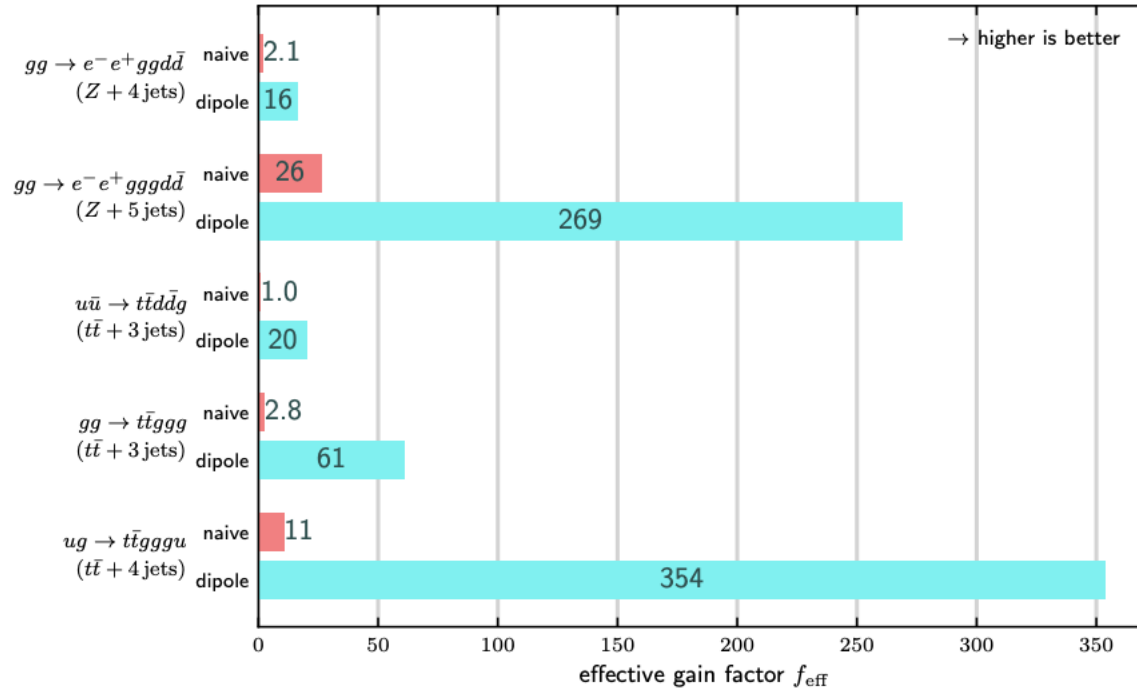
[Bresó, Heinrich, et al., 2412.09534]



➡ ML surrogates outperform classical interpolation techniques

Speed comparison

[Janßen et al., 2301.13562]



$$f_{\text{eff}} = \frac{T_{\text{standard}}}{T_{\text{surrogate}}}$$



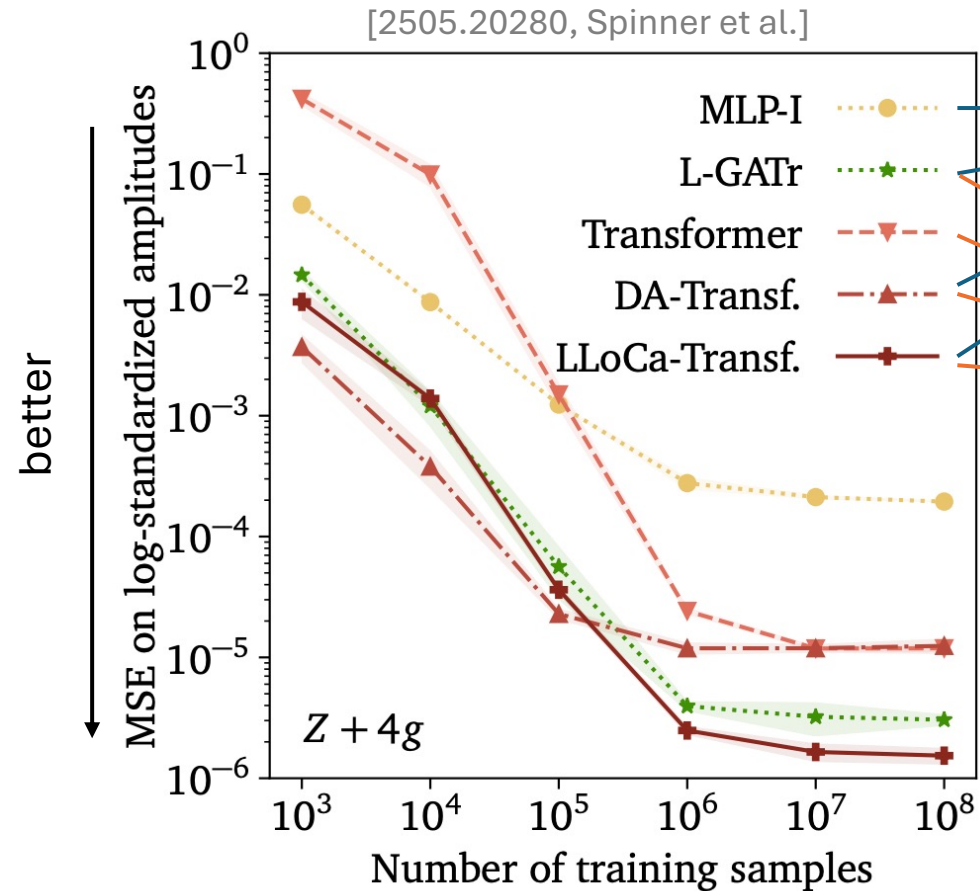
dipole vs naïve:
encode singularity structure of amplitudes



Large speed-ups possible!

| Process | SHERPA default | | | with dipole-model surrogate | | | | f_{eff} |
|--|----------------------------|----------------------------|--------------------------|------------------------------|------------------|------------------------------|------------------------------|------------------|
| | $t_{\text{ME}}[\text{ms}]$ | $t_{\text{PS}}[\text{ms}]$ | ϵ_{full} | $t_{\text{surr}}[\text{ms}]$ | x_{max} | $\epsilon_{1\text{st,surr}}$ | $\epsilon_{2\text{nd,surr}}$ | |
| $gg \rightarrow e^- e^+ gg d \bar{d}$ | 54 | 0.40 | 1.411 % | 0.14 | 2.6 | 1.418 % | 39 % | 16 |
| $gg \rightarrow e^- e^+ g g d \bar{d}$ | 16 216 | 5.70 | 0.076 % | 0.20 | 3.6 | 0.085 % | 29 % | 269 |

Exploiting known symmetries



Lorentz invariance



permutation invariance ($g_i \leftrightarrow g_j$)

Enforcing symmetries drastically improves performance!
→ physic-informed data representations

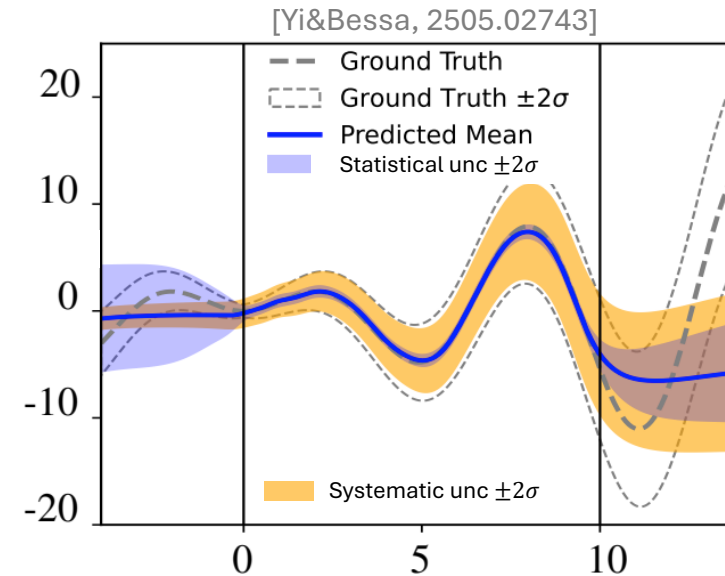
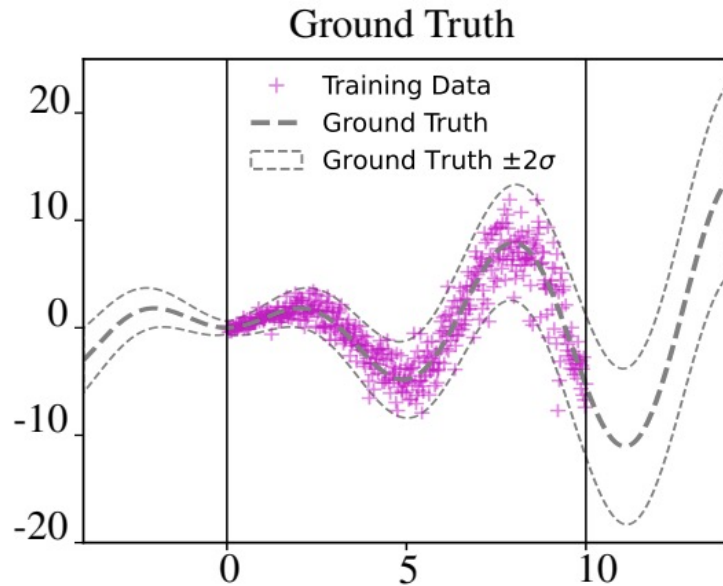


Uncertainties

"All models are wrong, but some — those that know when they can be trusted — are useful!"

George Box (adapted)

Regression with uncertainties



- statistical uncertainty $\hat{=}$ lack of training data
- systematic uncertainty $\hat{=}$ noise in the data, lack in model expressivity

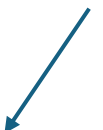


Can we the NNs encode a representation of their own uncertainties?

Probabilistic learning

Learn amplitude statistically

NN parameters

$$p(A|x) = \int d\theta p(\theta|D_{\text{train}}) p(A|x, \theta) \approx \int d\theta q(\theta) p(A|x, \theta)$$


Then, we can calculate the mean prediction and uncertainties as

$$A_{\text{NN}}(x) = \int dA A p(A|x) = \int d\theta q(\theta) \bar{A}(x, \theta) \quad \text{with} \quad \bar{A}(x, \theta) = \int dA A p(A|x, \theta)$$

$$\sigma_{\text{syst}}^2(x) = \int d\theta q(\theta) [\bar{A}^2(x, \theta) - \bar{A}(x, \theta)^2] \quad \longrightarrow \quad \text{vanishes for perfect data: } p(A|\theta) \rightarrow \delta(A - A_0)$$

$$\sigma_{\text{stat}}^2(x) = \int d\theta q(\theta) [\bar{A}(x, \theta) - A_{\text{NN}}(x)]^2 \quad \longrightarrow \quad \text{vanishes for perfect training: } q(\theta) \rightarrow \delta(\theta - \theta_0)$$

Modelling the systematic uncertainty

- log-likelihood loss:

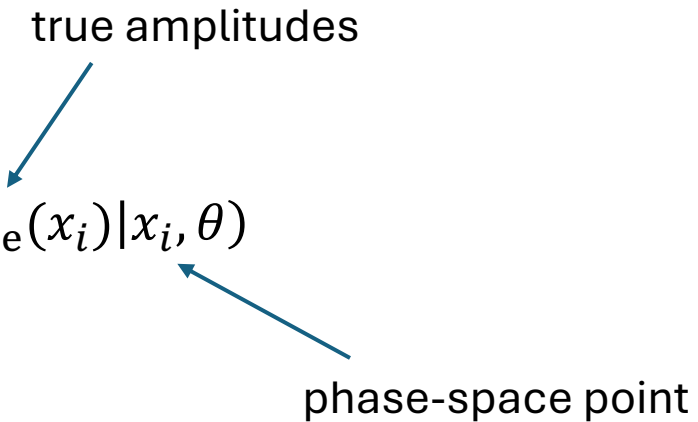
$$\mathcal{L} = - \sum_{x_i, A_i \in D_{\text{train}}} \log p(A_{\text{true}}(x_i) | x_i, \theta)$$


Diagram illustrating the log-likelihood loss equation. The equation is $\mathcal{L} = - \sum_{x_i, A_i \in D_{\text{train}}} \log p(A_{\text{true}}(x_i) | x_i, \theta)$. A blue arrow points from the text "true amplitudes" to the term $A_{\text{true}}(x_i)$. Another blue arrow points from the text "phase-space point" to the term x_i .

- assume Gaussian likelihood: $p(A|x) = \mathcal{N}(\bar{A}(x), \sigma_{\text{syst}}^2(x))$

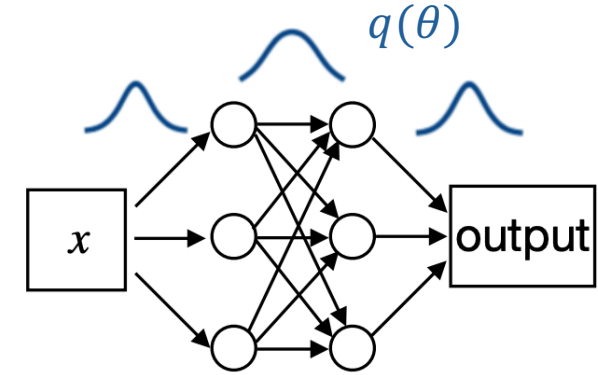
- NN learns both: $\bar{A}(x)$ and $\sigma_{\text{syst}}(x)$

$$\Rightarrow \text{heteroskedastic loss: } \mathcal{L} = \sum_i \left[\frac{(\bar{A}(x_i) - A_{\text{true}}(x_i))^2}{2\sigma_{\text{syst}}^2(x_i)} + \log(\sigma_{\text{syst}}(x_i)) \right]$$

- if needed: replace by Gaussian mixture model

Modelling the statistical uncertainty

- variational approximation: $p(\theta|D_{\text{train}}) \simeq q(\theta)$
- promote each NN parameter to Gaussian distribution
- train by minimizing KL divergence:



$$\begin{aligned} \text{KL}[q(\theta), p(\theta|D_{\text{train}})] &= \int d\theta \, q(\theta) \log \frac{q(\theta)}{p(\theta|D_{\text{train}})} \\ \text{Bayes' theorem} \quad &\rightarrow = \int d\theta \, q(\theta) \log \frac{q(\theta)p(D_{\text{train}})}{p(\theta)p(D_{\text{train}}|\theta)} \\ &= \underbrace{\text{KL}[q(\theta), p(\theta)]}_{\text{prior}} - \underbrace{\int d\theta \, q(\theta) \log p(D_{\text{train}}|\theta)}_{\text{log likelihood}} + \dots \end{aligned}$$

Alternative: repulsive ensembles

- can describe NN training via ODE or continuity equation:

$$\frac{d\theta}{dt} = v(\theta, t) \quad \text{or} \quad \frac{\partial \rho(\theta, t)}{\partial t} = -\nabla_{\theta} [v(\theta, t) \rho(\theta, t)]$$

- choose $v(\theta, t) = -\nabla_{\theta} \log \frac{\rho(\theta, t)}{\pi(\theta)}$ → solution: $\rho(\theta) = \pi(\theta) \equiv p(\theta|D_{\text{train}})$

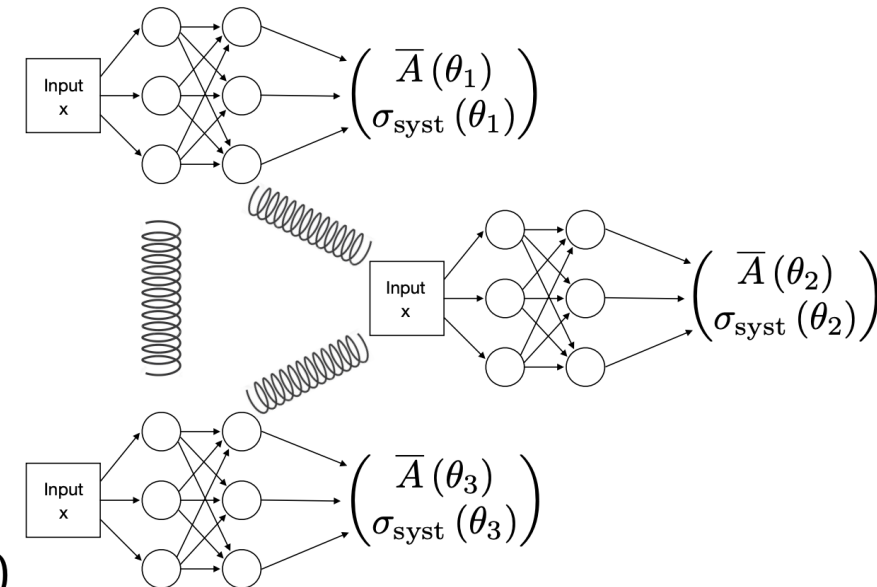
- estimate density via NN ensemble: $\rho(\theta^t) \approx \frac{1}{n} \sum_{i=1}^n k(\theta^t, \theta_i^t)$

kernel

- NN parameter update rule

$$\frac{d\theta}{dt} = -\nabla_{\theta} \left[\log \left(\frac{1}{n} \sum_i k(\theta, \theta_i) \right) - \log p(\theta|x) \right]$$

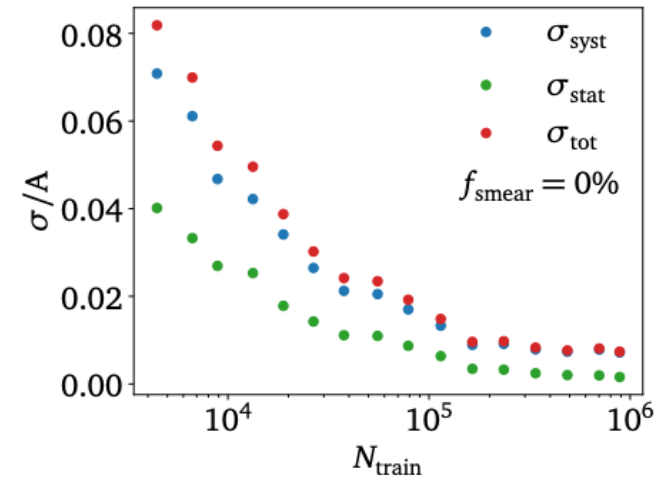
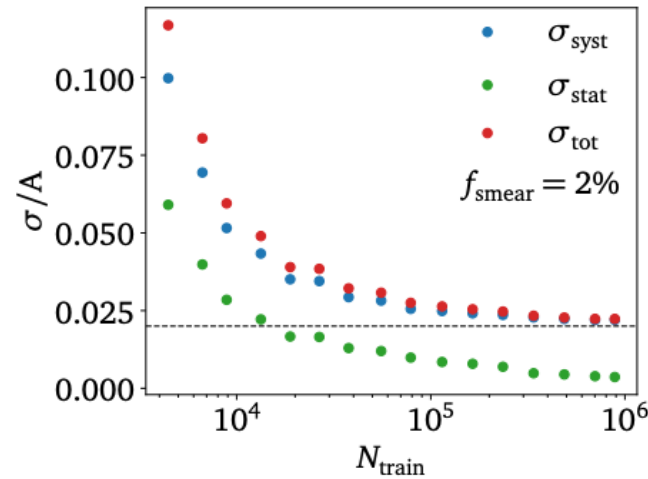
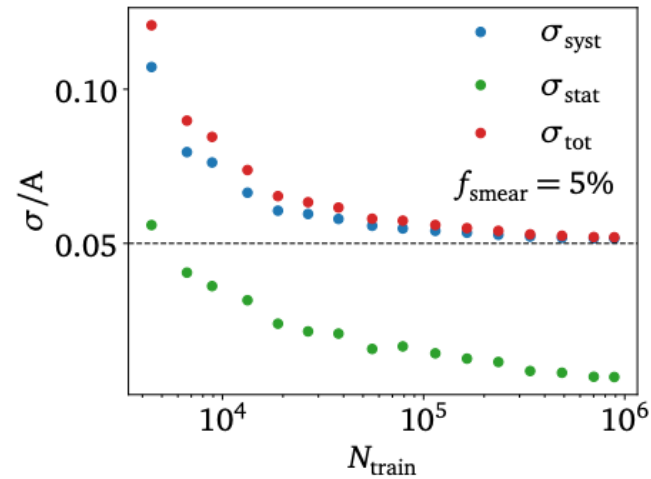
➡ NN ensemble with repulsive force ensuring $\theta \sim p(\theta|D_{\text{train}})$



Behavior of uncertainties

[HB,Elmer,Favaro,...,2412.12069]

$$A_{\text{train}} \sim \mathcal{N}(A_{\text{true}}, \sigma_{\text{train}}^2)$$
$$\sigma_{\text{train}} = f_{\text{smear}} A_{\text{true}}$$



test: apply Gaussian noise to $gg \rightarrow \gamma\gamma g$ amplitudes

- statistical unc. decreases with more training data
- systematic unc. converges to level of applied noise

→ reliable uncertainty estimate

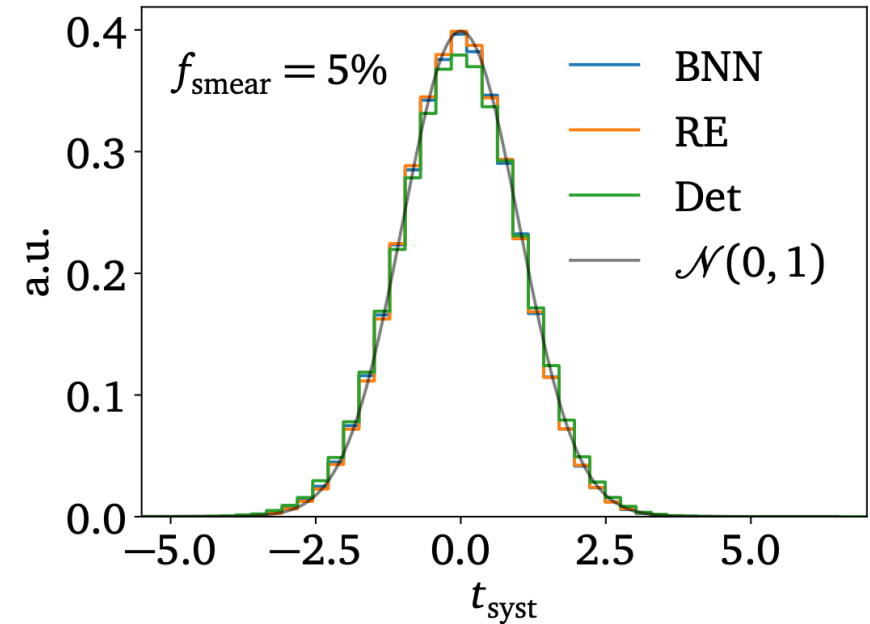
Are these uncertainties calibrated?

- statistical uncertainties play minor role for amplitude regression

- define systematic pull:

$$t_{\text{syst}} = \frac{\langle A \rangle(x) - A_{\text{train}}(x)}{\sigma_{\text{syst}}(x)}$$

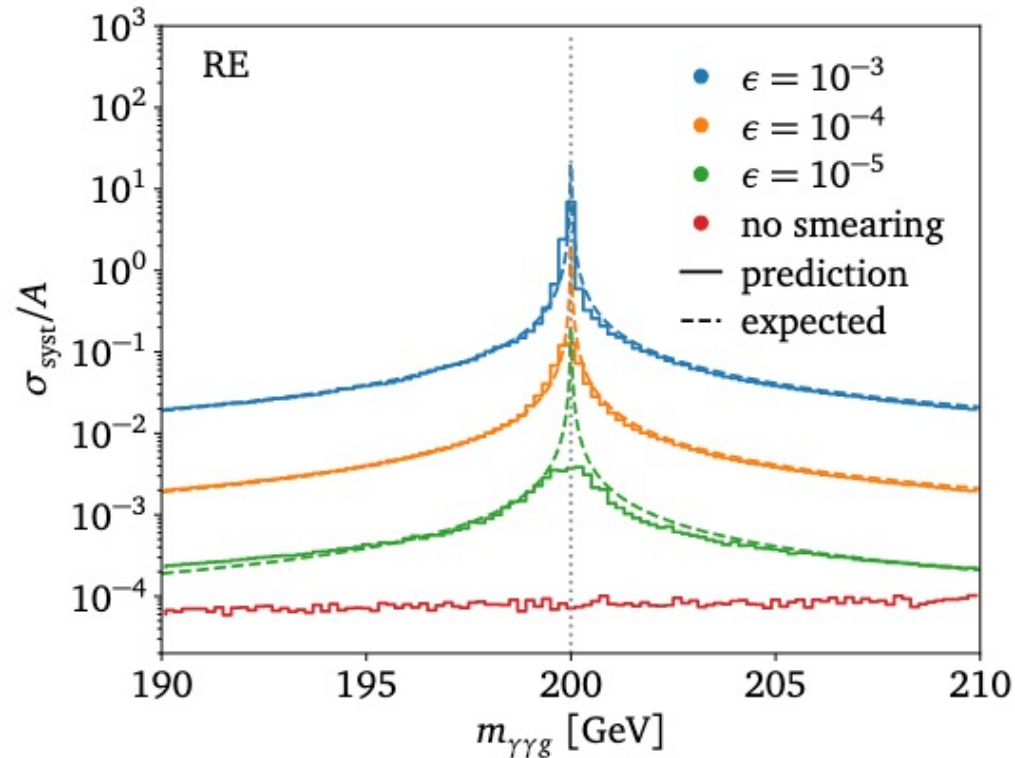
- if calibrated, t_{syst} distribution should follow $\mathcal{N}(0, 1)$



Almost perfectly calibration → reliable uncertainty estimate

Localized noise

[HB,Elmer,Plehn,Winterhalder, 2509.00155]



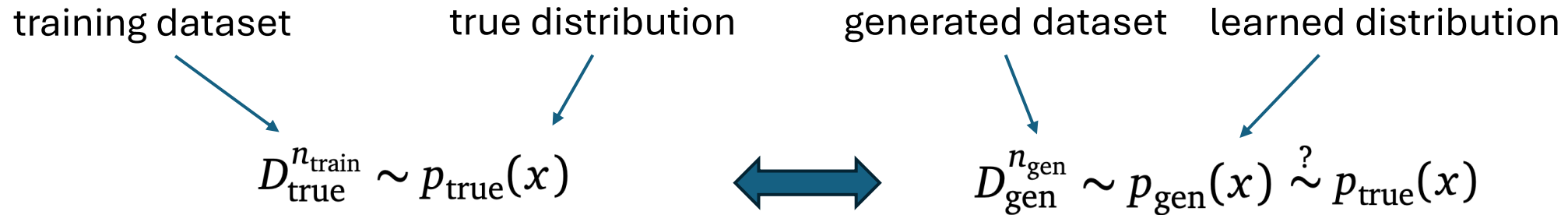
$$A_{\text{train}}(x) = \mathcal{N}\left(A_{\text{true}}(x), \frac{\epsilon m_{\text{thresh}}}{|m_{\gamma\gamma g}(x) - m_{\text{thresh}}|} A_{\text{true}}(x)\right)$$

- emulates numerical noise close to threshold
- well captured by systematic uncertainties
- NN effectively finds the mean prediction
- uncertainties still well calibrated

Same techniques also applicable to all kind of other regression problems!

Controlling generative ML

[HB,Diefenbacher,Elmer,..., 2509.08048]



How can we quantify the performance of the generative NN?

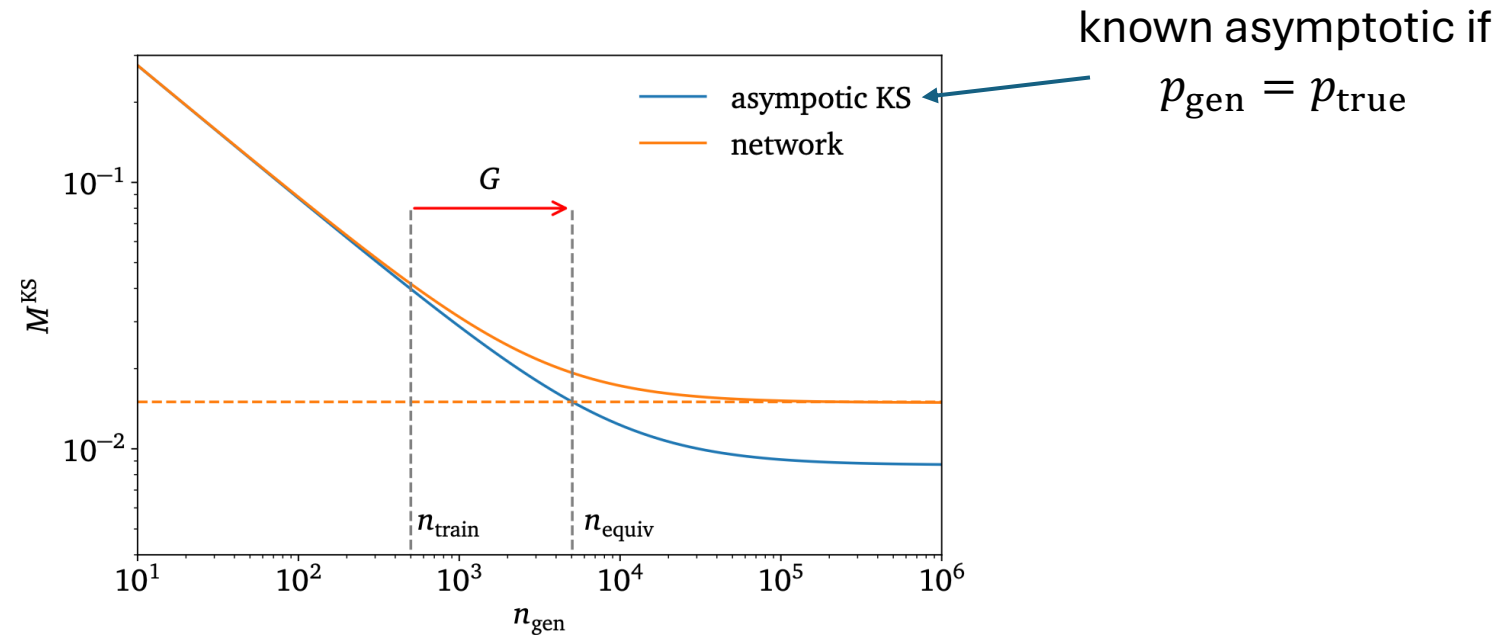
→ determine n_{equiv} such that $M(D_{\text{true}}^{n_{\text{equiv}}}, p_{\text{true}}(x)) \equiv M(D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{true}}(x))$ with $D_{\text{true}}^{n_{\text{equiv}}} \sim p_{\text{true}}(x)$

comparison metric

amplification factor $G = \frac{n_{\text{equiv}}}{n_{\text{train}}}$

Controlling generative ML

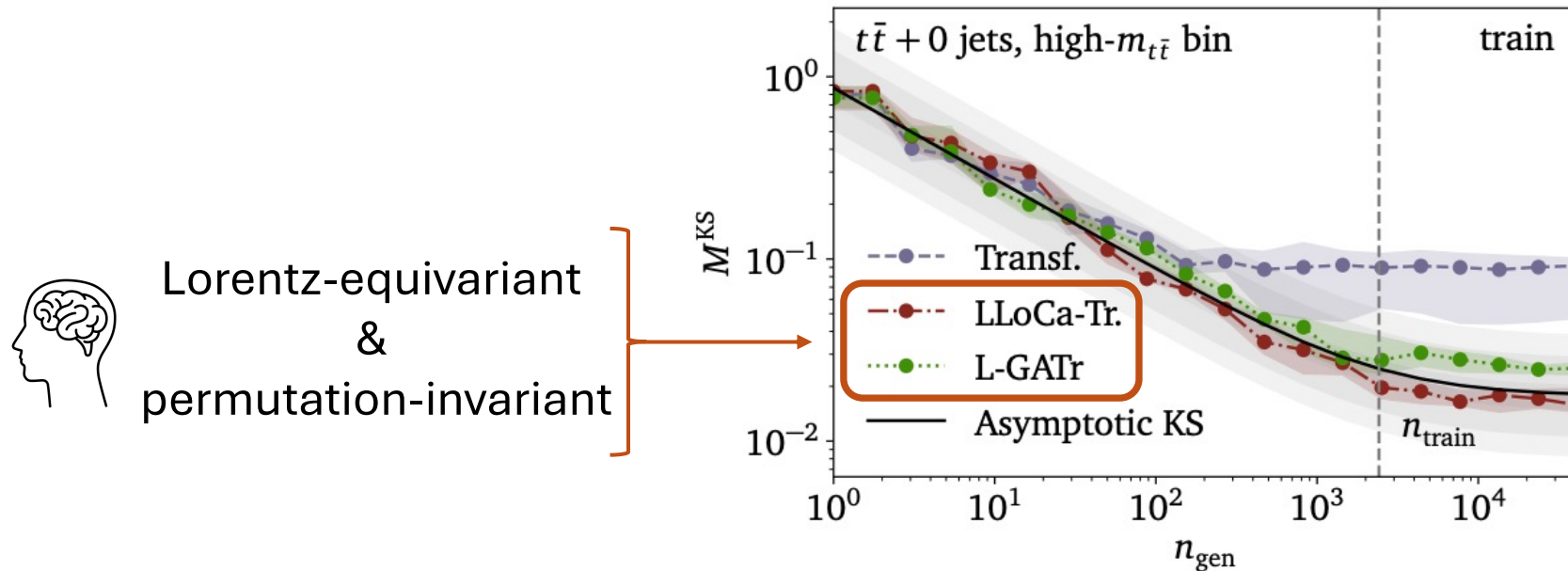
one option for M : Kolmogorov-Smirnov test comparing D_{train} and D_{gen}



➡ systematic approach to assess quality of generative NNs

Controlling generative ML

one option for M : Kolmogorov-Smirnov test comparing D_{train} and D_{gen}



➡ systematic approach to assess quality of generative NNs

Interpretable ML

looking under the hood



Back to the formula – symbolic regression

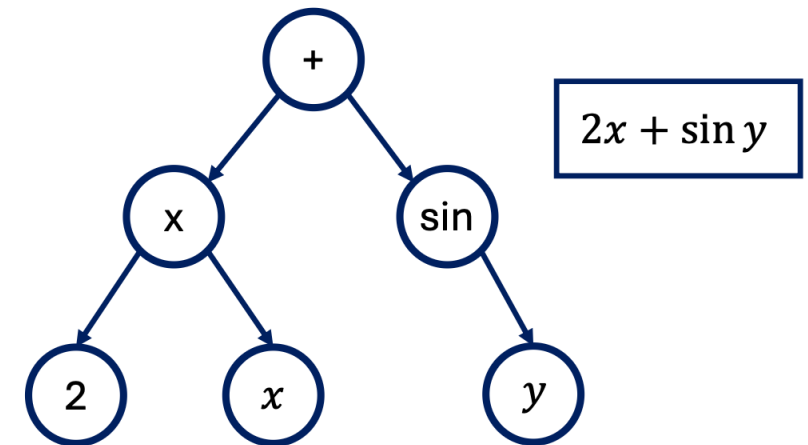
- many ways to make ML interpretable
- goal: find most relevant representation/observables describing the data

→ maximal interpretability: analytic equation!

- construct them dynamically using symbolic regression

[Schmidt&Lipson`09, Udrescu&Tegmark`19, Cranmer et al.`19,`20,`23]

- build upon genetic algorithm successively forming equation
- interplay between goodness-of-fit and complexity of equation



Example: Higgs CP test for VBF

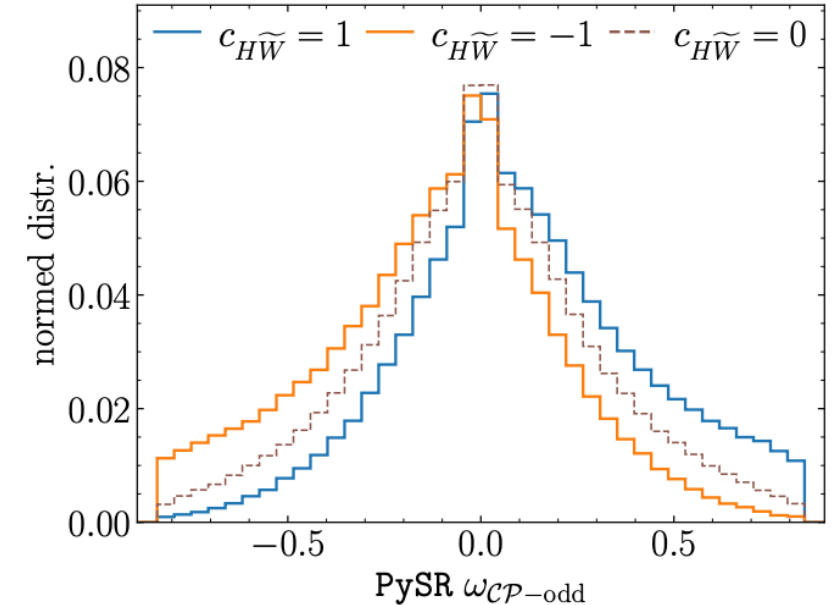
[HB,Menen,Fuchs,Plehn,2507.05858]

- consider dim-6 operator $\frac{c_{H\widetilde{W}}}{\Lambda^2} \Phi^\dagger \Phi \widetilde{W}_{\mu\nu}^a W^{a\mu\nu}$
- unambiguous CP test \rightarrow CP-odd observables
- construct optimal reco-level CP-odd obs. by training a classifier on $c_{H\widetilde{W}} = \pm 1$ samples
- analytic equation \rightarrow ensure learned observable is indeed CP-odd



$$d^{\text{PySR}} = \frac{1.8566 \sin \Delta \phi_{jj}}{\left| \frac{0.3080 x_{j_1} \log \Delta \eta_{jj} + \log \Delta \eta_{jj} \sinh(x_{j_2} - 2.5977) + 0.3080 \sinh x_h}{x_{j_1} \log \Delta \eta_{jj} + \sinh x_h} \right| + 0.6047}$$

with $x = p_T/m_h$



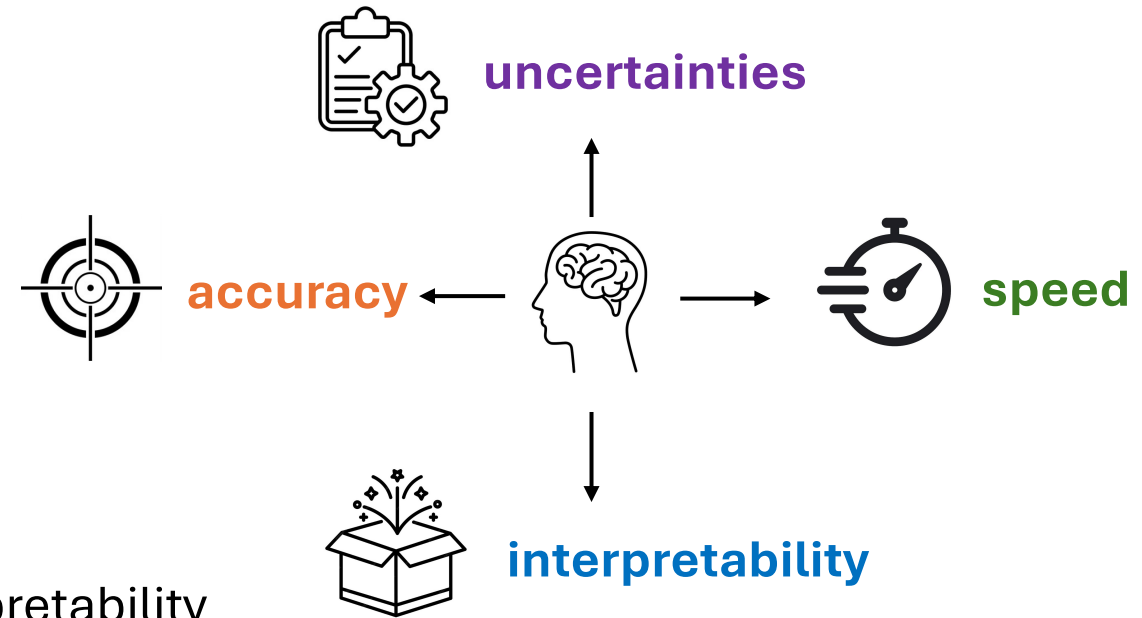
| | $ \sigma(c_{H\widetilde{W}} = 1 \text{ vs. SM}) $ |
|---|---|
| $p_{T,j_1} p_{T,j_2} \sin \Delta \phi_{jj}$ | 6.76 |
| trained on $c_{H\widetilde{W}} = \pm 1$ | |
| PySR | 6.98 |
| SymbolNet | 7.07 |
| BDT | 6.71 |

Conclusions



Conclusions

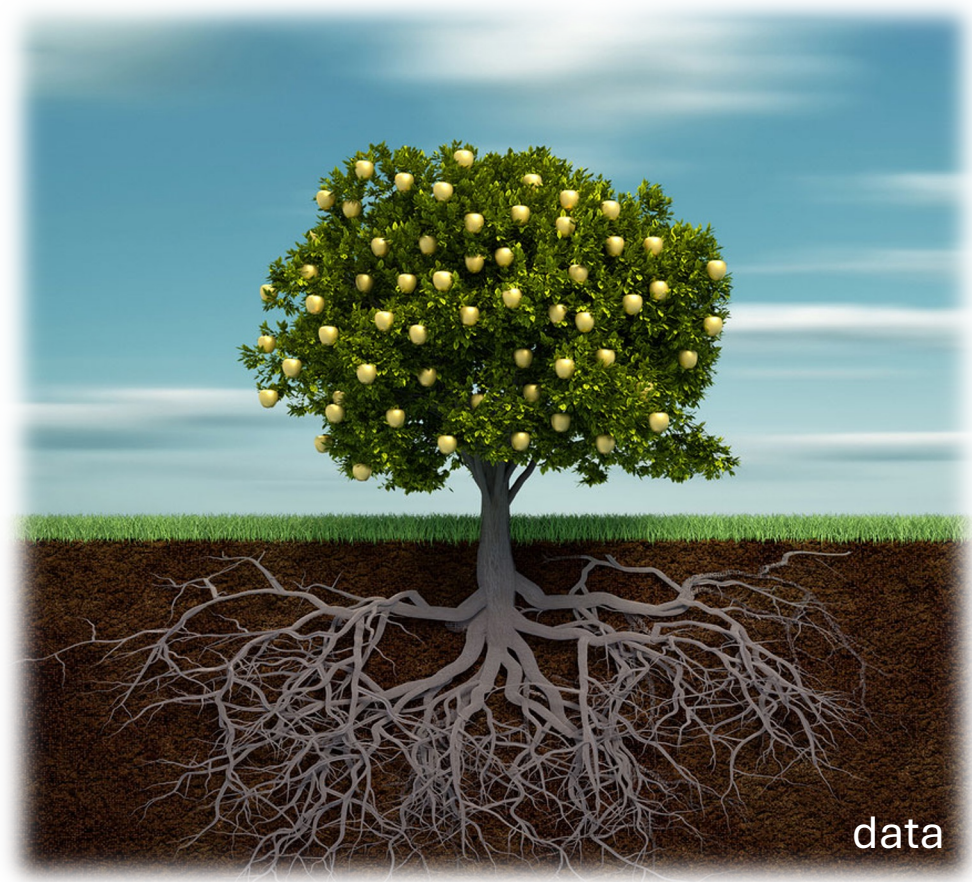
- particle physics is in the precision era
→ large amounts of multidimensional data
- ML methods excel in such an environment
- important requirements: uncertainties and interpretability
- key ingredient: representation learning based on particle theory
- methods widely applicable

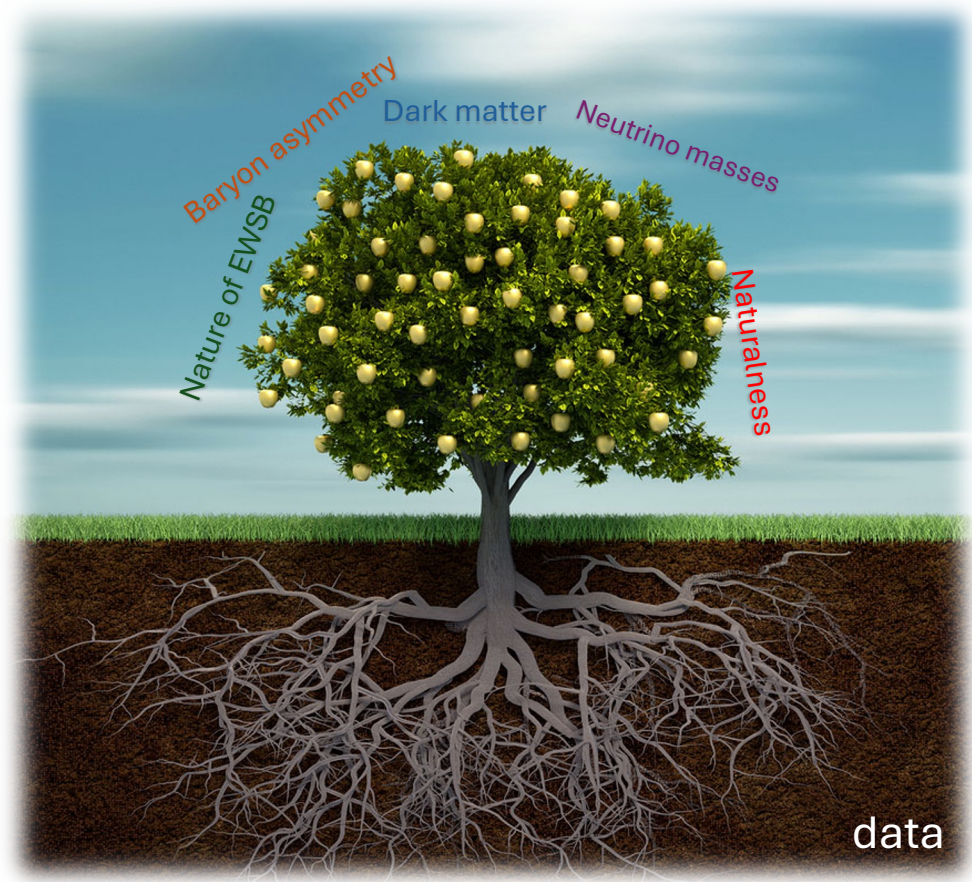


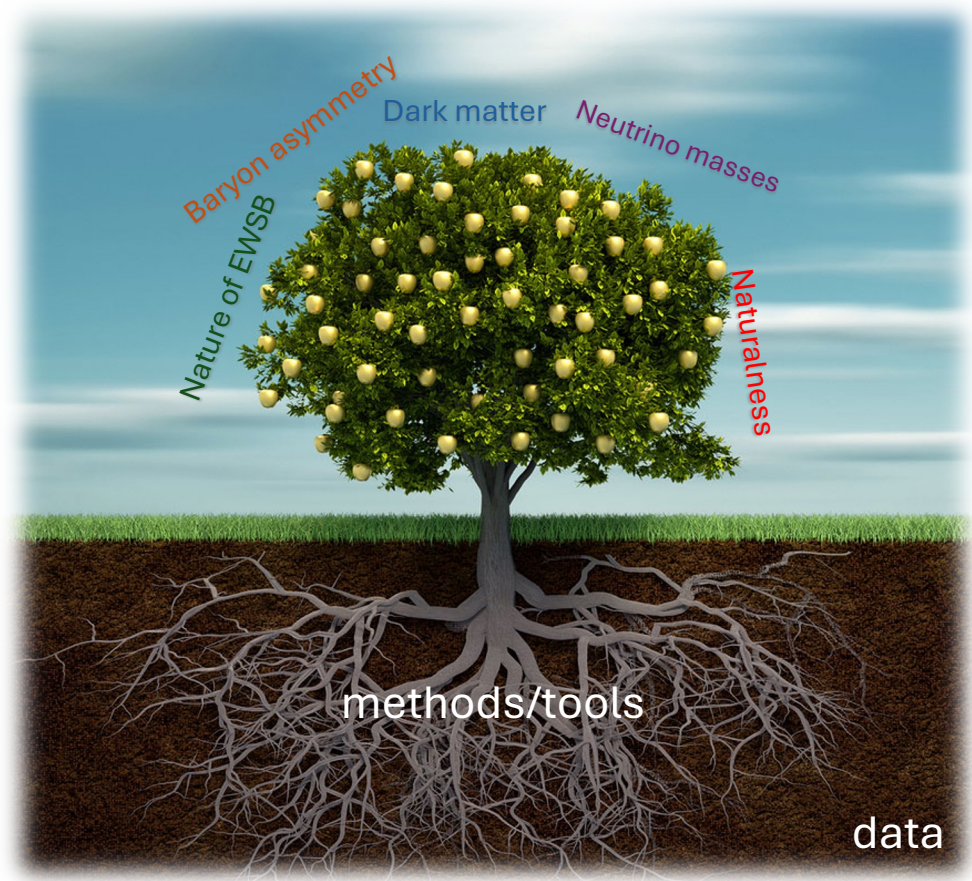
ML is an essential tool for the future of particle physics

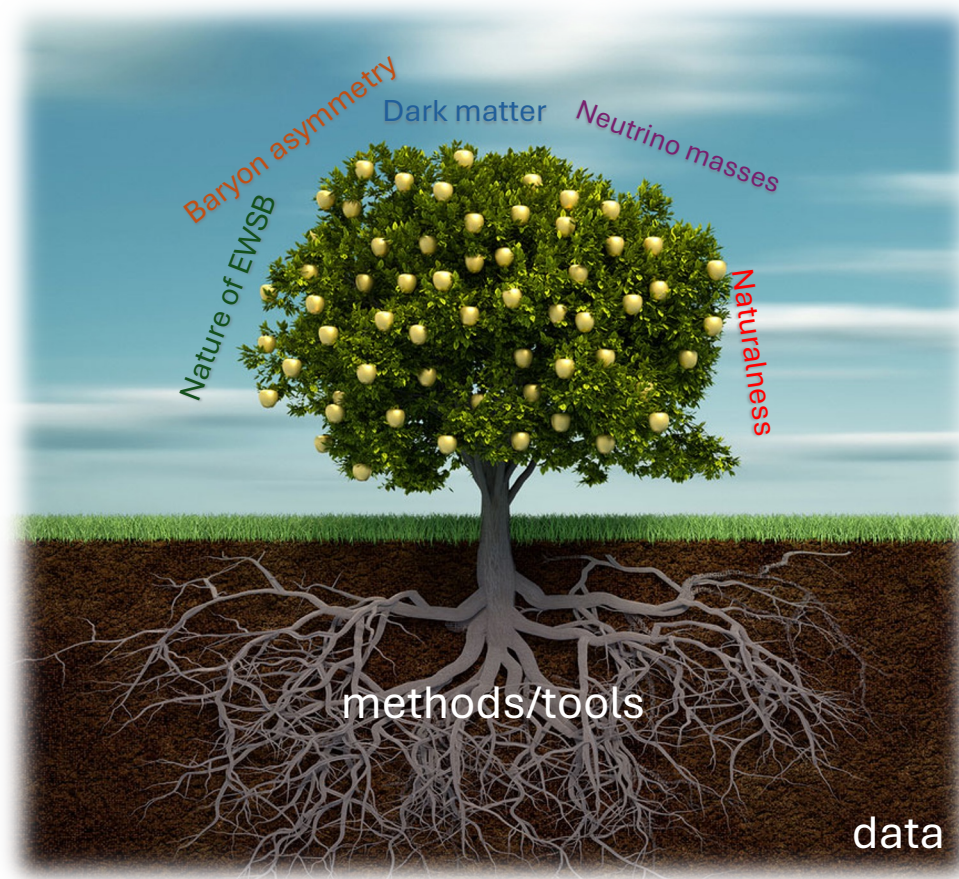
Appendix





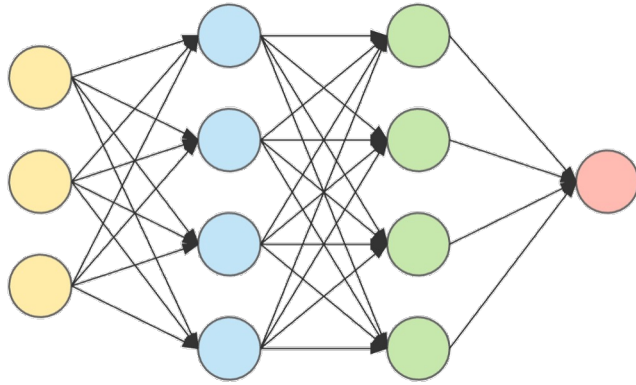






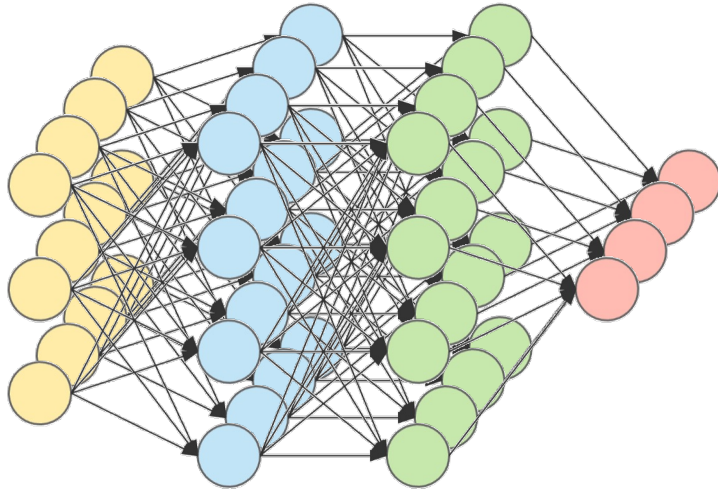
Thanks for your attention!

Modelling the statistical uncertainty

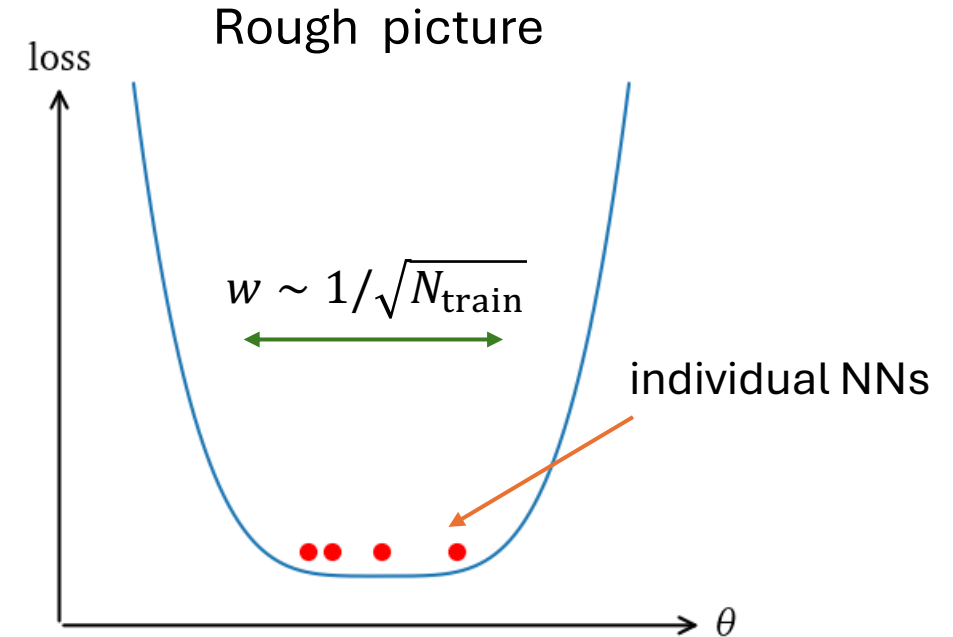


- train ensemble of networks
- each networks leads to slightly different result
- spread of network predictions \sim statistical uncertainty
- less data \rightarrow higher spread

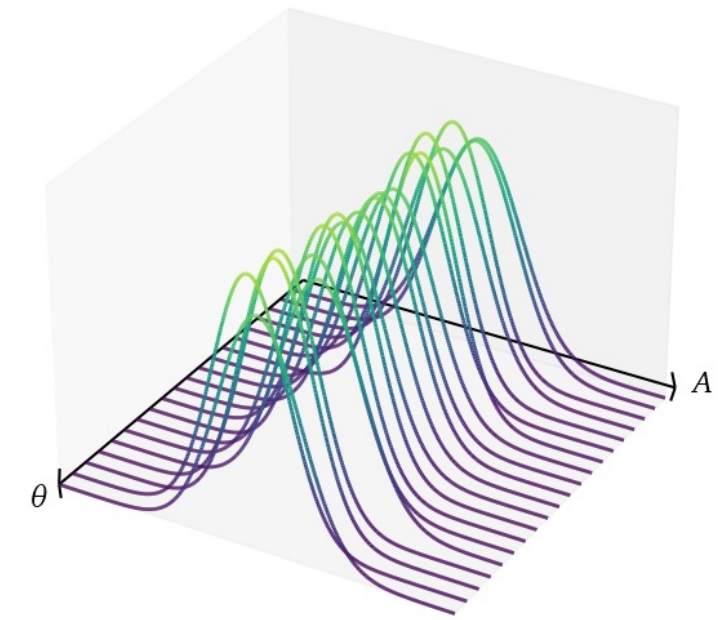
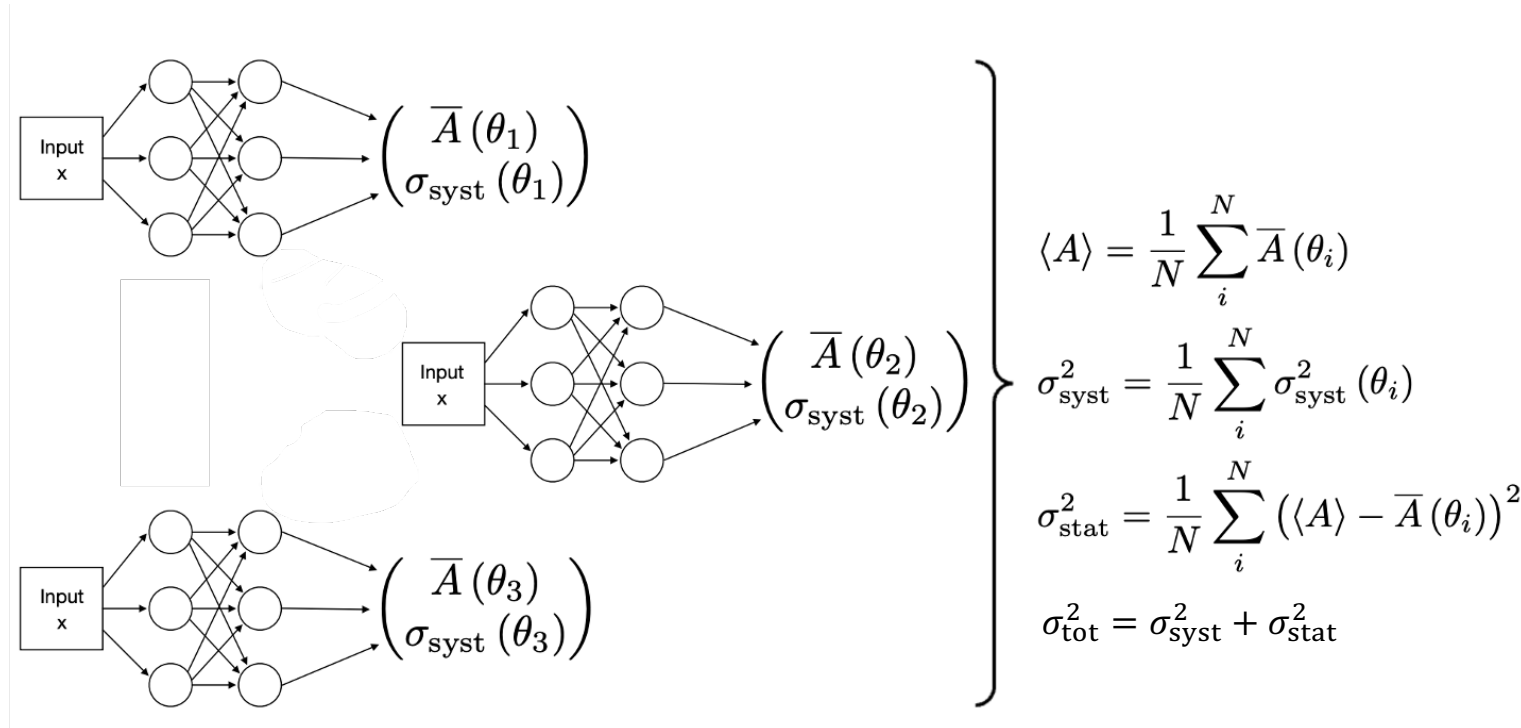
Modelling the statistical uncertainty



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- spread of network predictions \sim statistical uncertainty
- less data \rightarrow higher spread



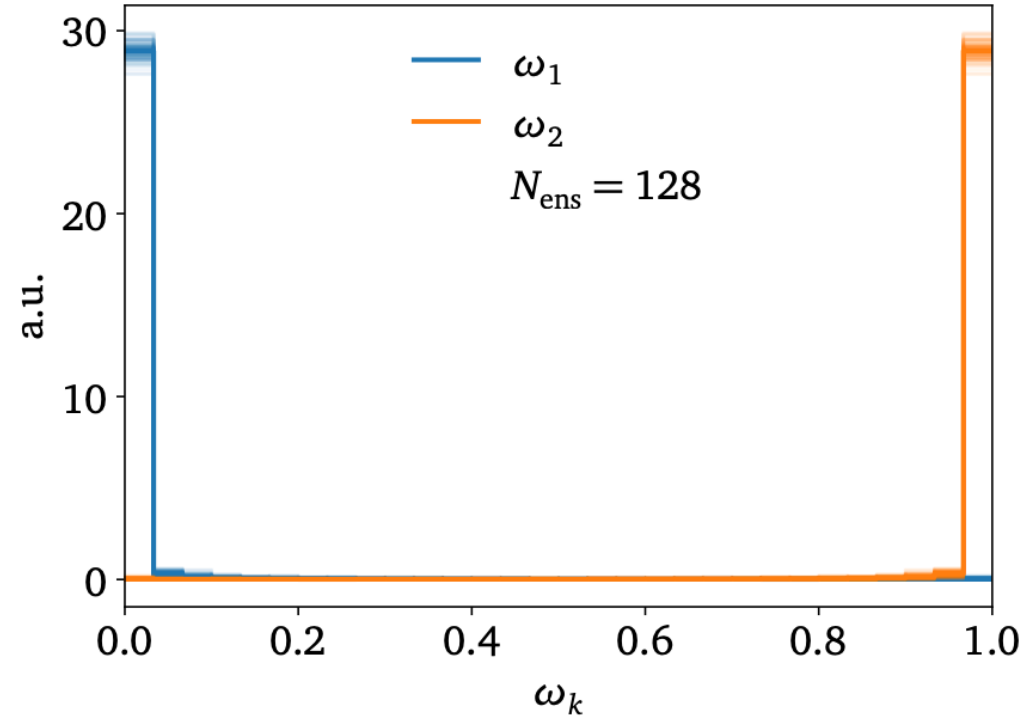
Bringing it all together



➡ Combined learnable modelling of systematic and statistical uncertainties!

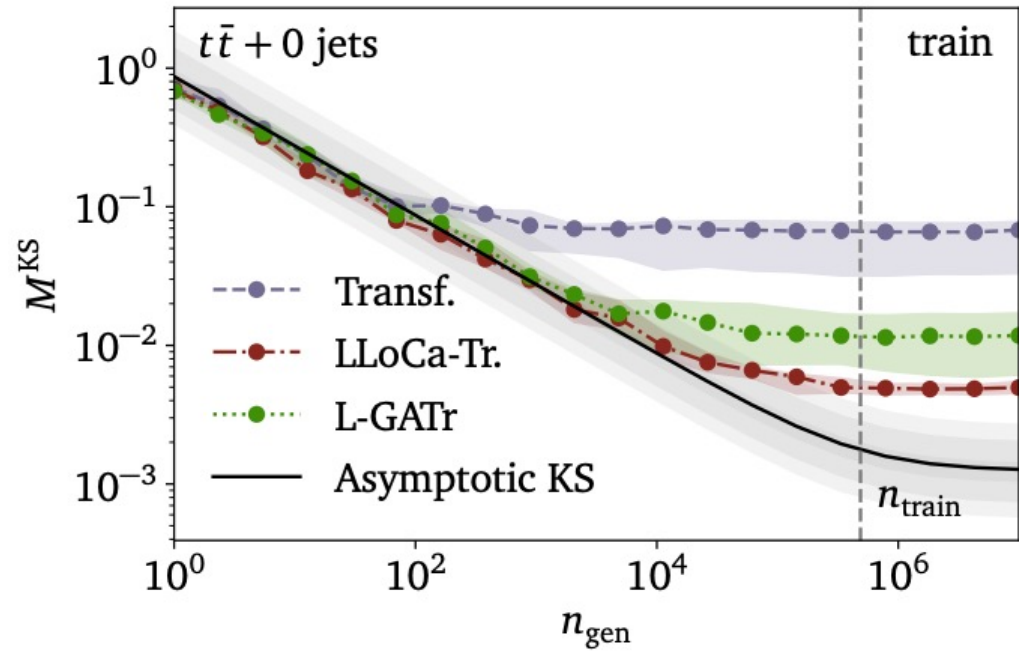
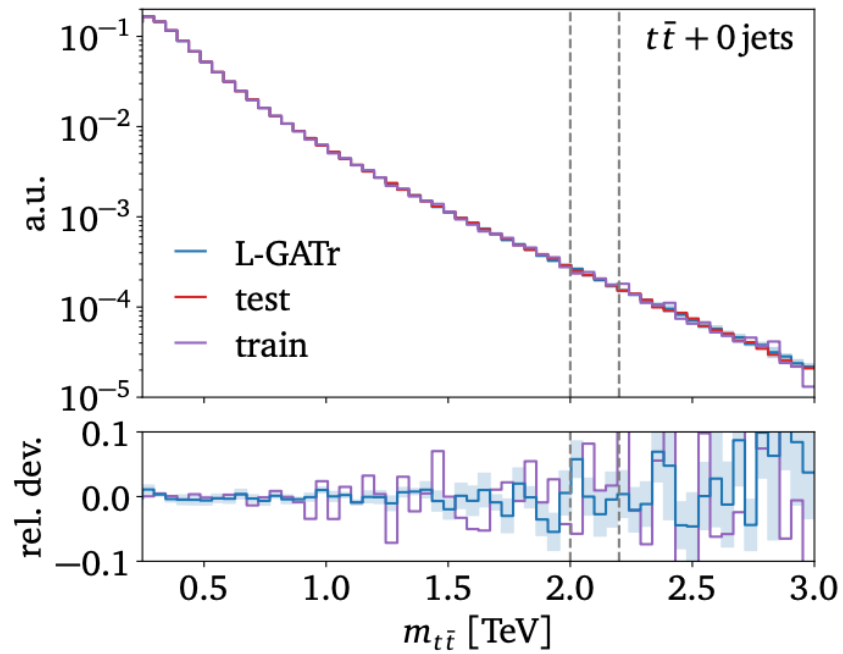
Alternative approaches: Bayesian neural networks, evidential regression

Gaussian mixture model



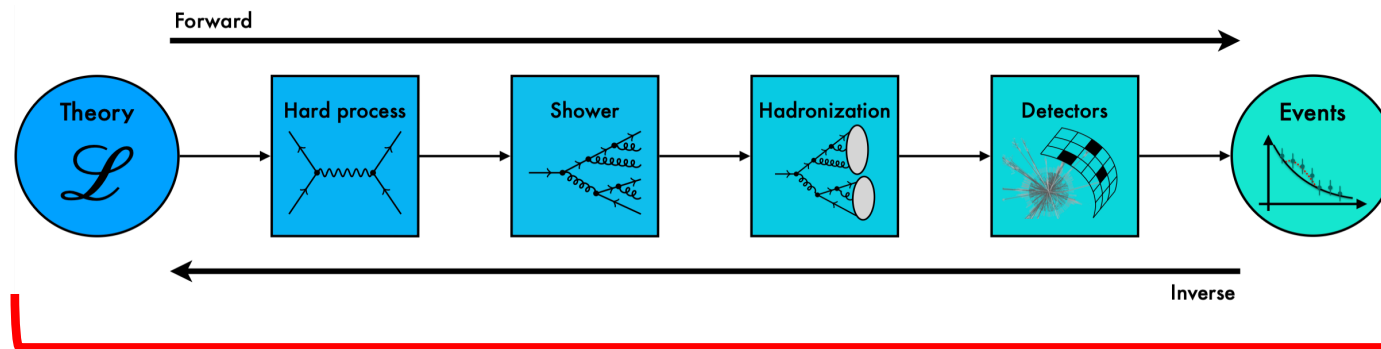
$$p_{\text{GMM}}(A|x, \theta) = \sum_{k=1}^K \omega_k(x, \theta) \mathcal{N}(A | \bar{A}_k(x, \theta), \sigma_k^2(x, \theta)), \quad \text{with} \quad \sum_{k=1}^K \omega_k(x, \theta) = 1$$

Controlling generative ML



Simulation-Based Inference

fully exploiting high-dimensional data



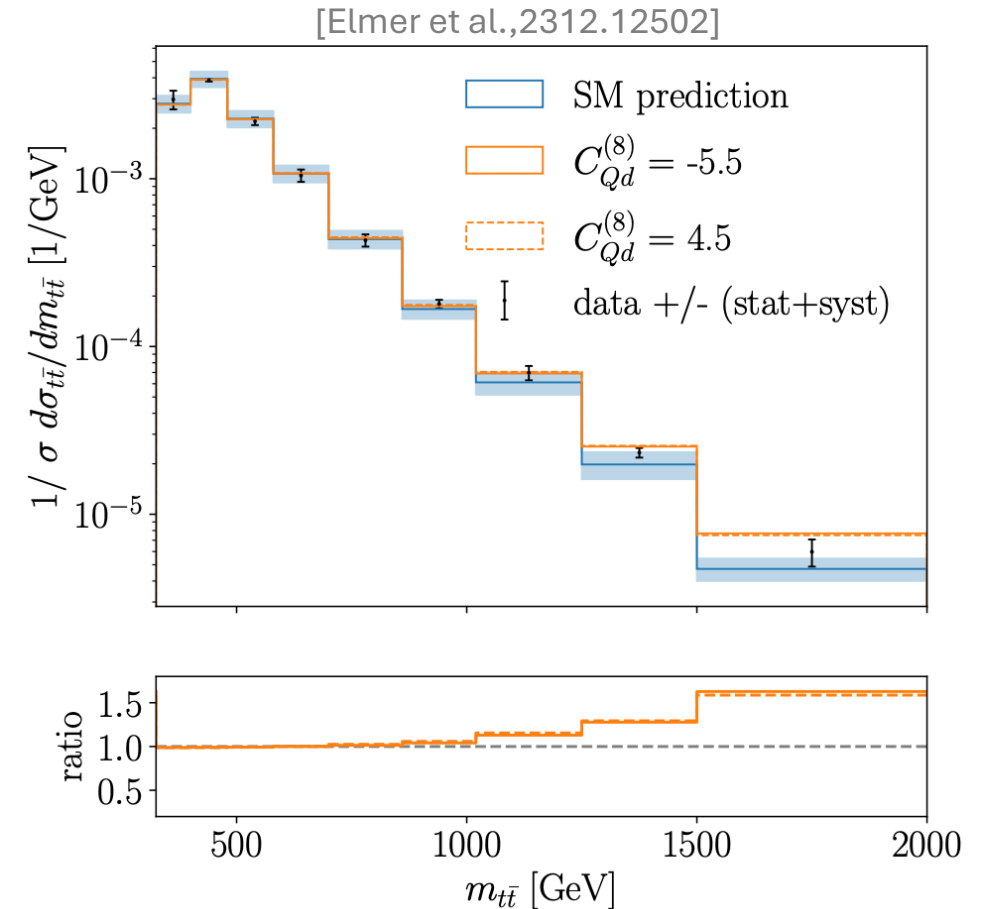
Classical parameter inference

- reduce dimension of phase space
summary statistics
- bin summary statistics
- compare resulting histogram to SM/BSM
predictions

Advantage: humanly digestible plots

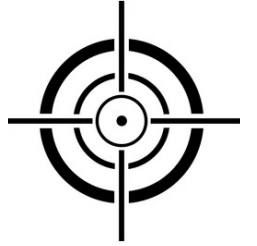
Disadvantage: loss of information

→



Full likelihood

phase space point theory parameters



- Monte-Carlo simulation chain allows us to sample full likelihood $p(x|\theta)$. But cannot directly compute it.
- Neyman-Pearson lemma: likelihood ratio $r(x|\theta, \theta_0) \equiv \frac{p(x|\theta)}{p(x|\theta_0)}$ is most powerful statistical test
- but we can regress to reco-level $r(x|\theta, \theta_0)$ using known parton-level $r(z_p|\theta, \theta_0)$:

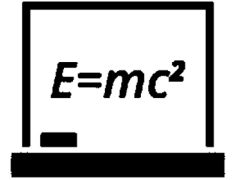
$$\mathcal{L} = \left\langle \left[r(z_p|\theta, \theta_0) - \underbrace{r_\varphi(x|\theta, \theta_0)}_{\text{NN}} \right]^2 \right\rangle_{\substack{x, z_p \sim p(x|z_p)p(z_p|\theta); \theta \sim q(\theta) \\ \text{average over event sample}}}$$



unbinned multi-dimensional inference without information loss

Encoding amplitude structure

[Schöfbeck et al., 2107.10859, 2205.12976]



Theory structure for e.g. SMEFT:

$$\mathcal{L}_{\text{SMEFT}} = \mathcal{L}_{\text{SM}} + \sum_i \frac{c_i}{\Lambda^2} O_i \equiv \mathcal{L}_{\text{SM}} + \sum_i \theta_i O_i$$

$$|\mathcal{M}(z_p|\theta)|^2 = |\mathcal{M}_{\text{SM}}(z_p)|^2 + \theta_i |\mathcal{M}_i(z_p)|^2 + \theta_i \theta_j |\mathcal{M}_{ij}(z_p)|^2$$



encode into likelihood

$$R(x|\theta, \theta_0) \equiv \frac{d\sigma(x|\theta)/dx}{d\sigma(x|\theta_0)/dx} = \frac{\sigma(\theta)p(x|\theta)}{\sigma(\theta_0)p(x|\theta_0)}$$

$$R(x|\theta, \theta_0) = 1 + (\theta - \theta_0)_i R_i(x) + (\theta - \theta_0)_i (\theta - \theta_0)_j R_{ij}(x)$$

$$R_i(z_p) \equiv \frac{\partial}{\partial \theta_i} \frac{d\sigma(z_p|\theta)/dz_p}{d\sigma(z_p|\theta_0)/dz_p} \Big|_{\theta=\theta_0} = \frac{\partial_{\theta_i} |\mathcal{M}(z_p|\theta)|^2}{|\mathcal{M}(z_p|\theta_0)|^2} \Big|_{\theta_0}$$

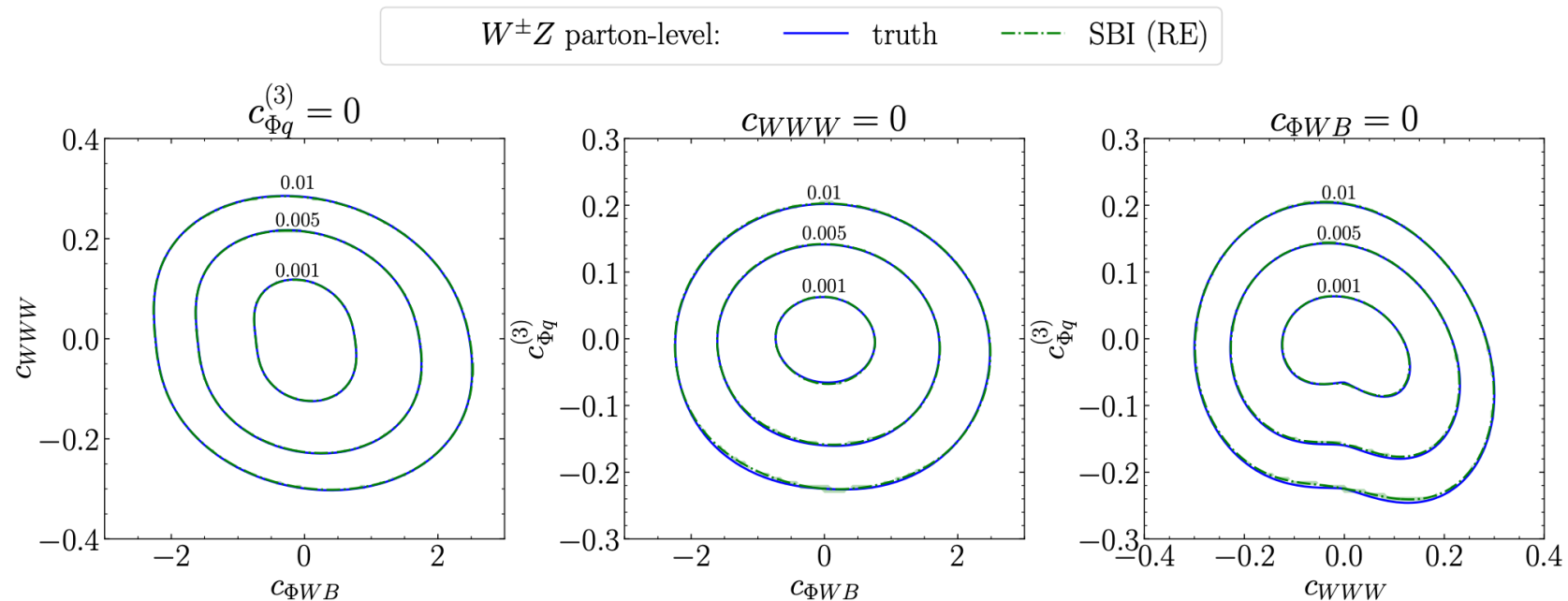
$$R_{ij}(z_p) \equiv \frac{\partial^2}{\partial \theta_i \partial \theta_j} \frac{d\sigma(z_p|\theta)/dz_p}{d\sigma(z_p|\theta_0)/dz_p} \Big|_{\theta=\theta_0} = \frac{\partial_{\theta_i} \partial_{\theta_j} |\mathcal{M}(z_p|\theta)|^2}{|\mathcal{M}(z_p|\theta_0)|^2} \Big|_{\theta_0}$$



learn coefficients $R_{i,j}$ separately \rightarrow theory parameter dependence fully factored out

Parton-level cross-check: $W^\pm Z$ production

- consider effects of three SMEFT operators



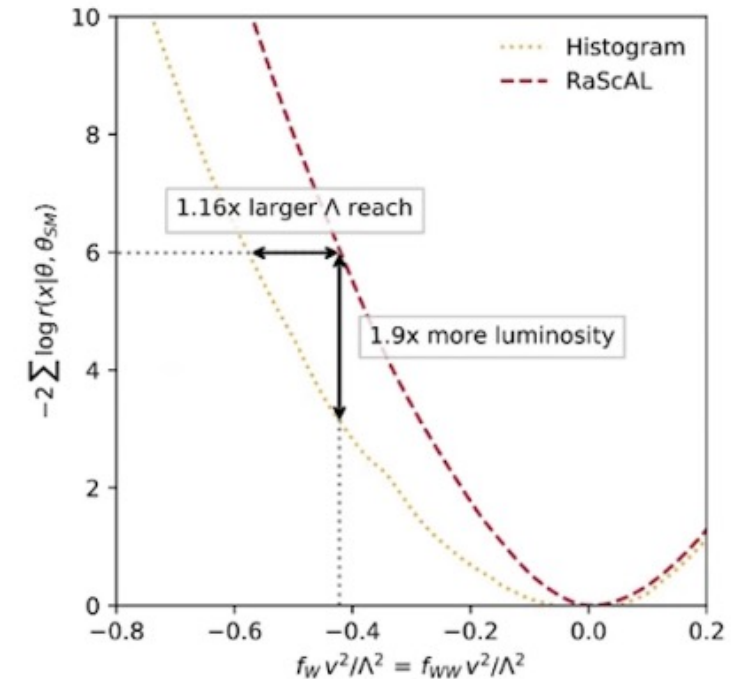
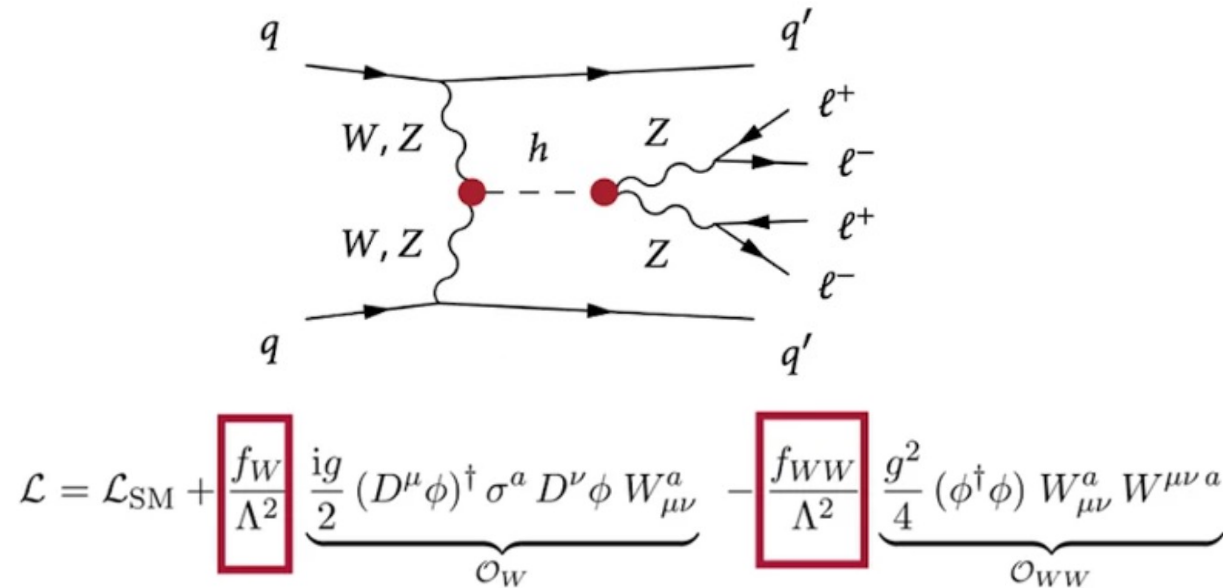
[HB et al., 2410.07315]



almost perfectly learns high-dimensional likelihood

Reco-level: VBF with $H \rightarrow 4\ell$

[Brehmer et al., 1805.00013]



➡ Huge potential to improve sensitivity of a wide variety of measurements/searches

But is SBI also viable in a realistic analysis including uncertainties etc.?

