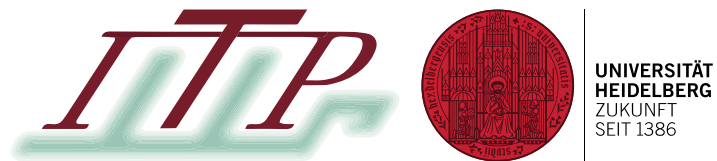


ML for particle physics in the precision era

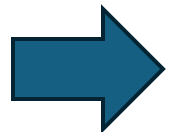
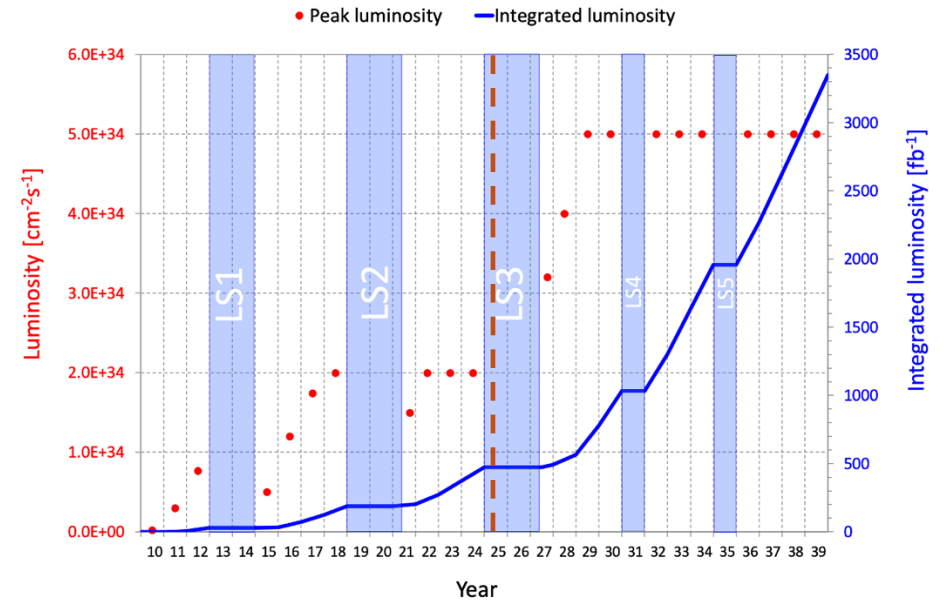
Henning Bahl



Theory Workshop, DESY Hamburg, 24.9.2025

The challenge ahead

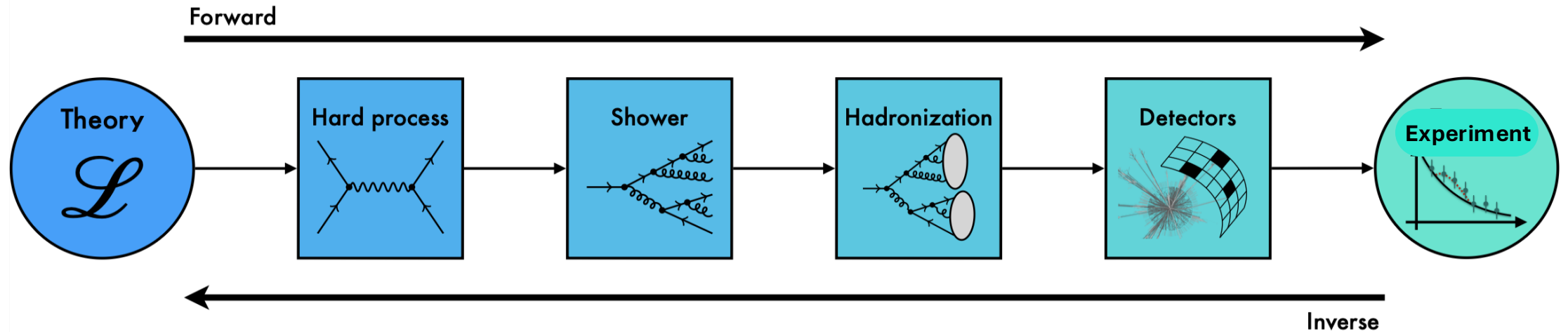
- general trend: larger-and-larger experiments collecting more-and-more data
- e.g. LHC: already enormous dataset will be further enlarged by a factor ~ 10
- costs for future experiments increasing



Fully exploit the available data!

- new analysis methods
- theory precision \simeq experimental precision
- in particular: high-precision MC simulation

The particle physics workflow



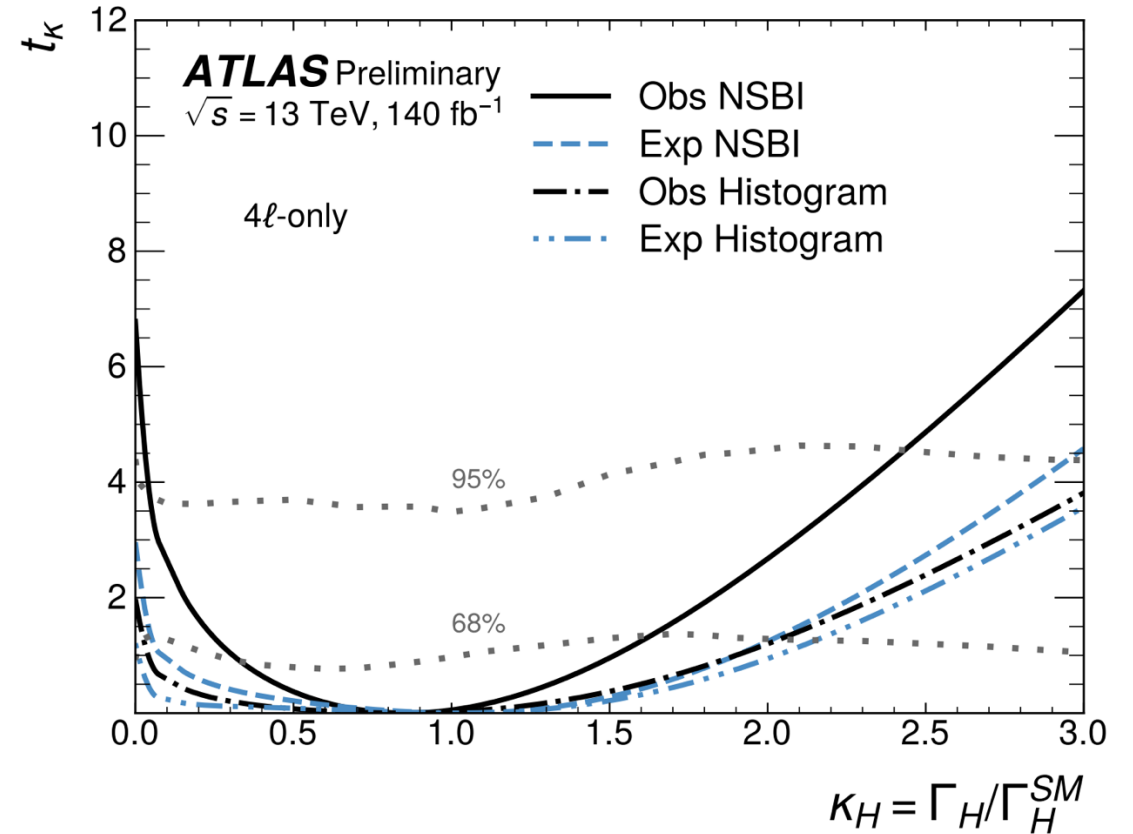
ML can help with each of these steps by increasing

- accuracy/performance
- speed

Example: 1st experimental SBI analysis

[ATLAS-CONF-2024-016]

- goal: measure off-shell signal strength in $H \rightarrow ZZ$ channel
- simulation-based inference (SBI) allows to exploit full kinematic information
- significant improvement in comparison to histogram approach



What is needed to apply ML successfully?

ML for particle physics



accuracy



speed

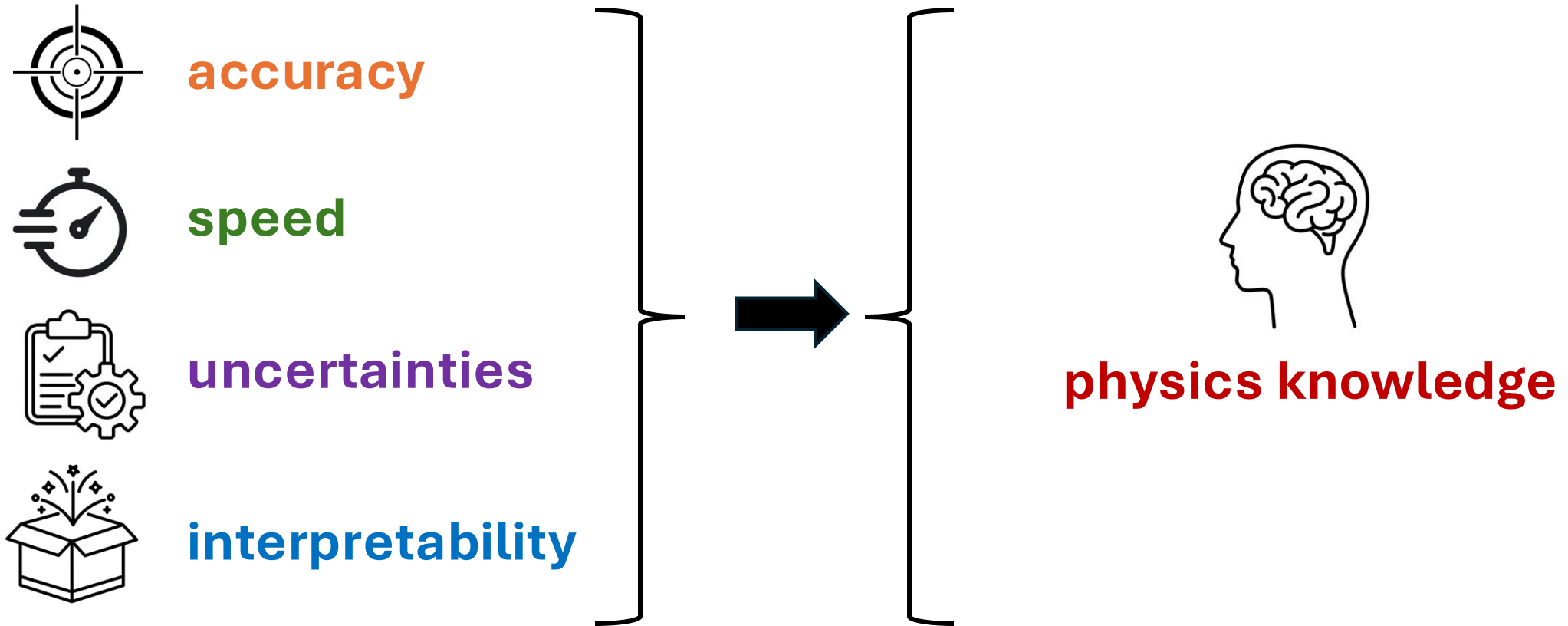


uncertainties

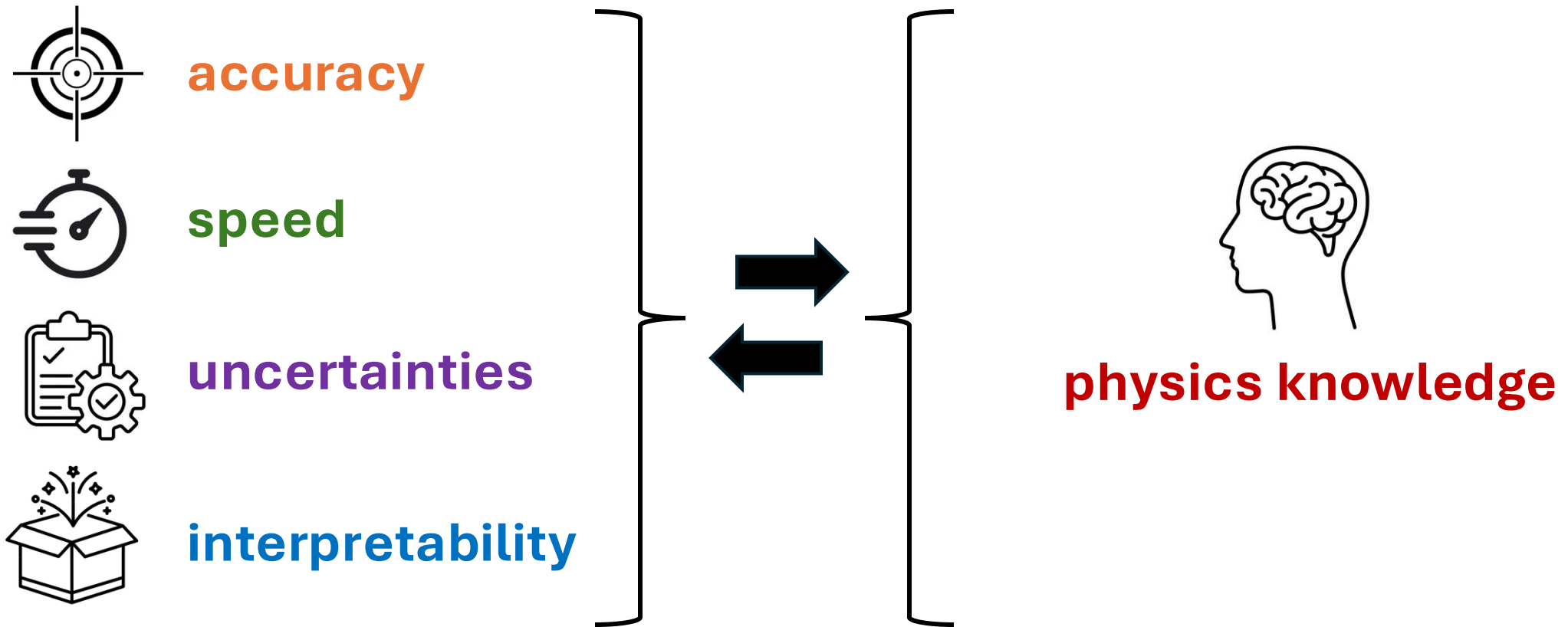


interpretability

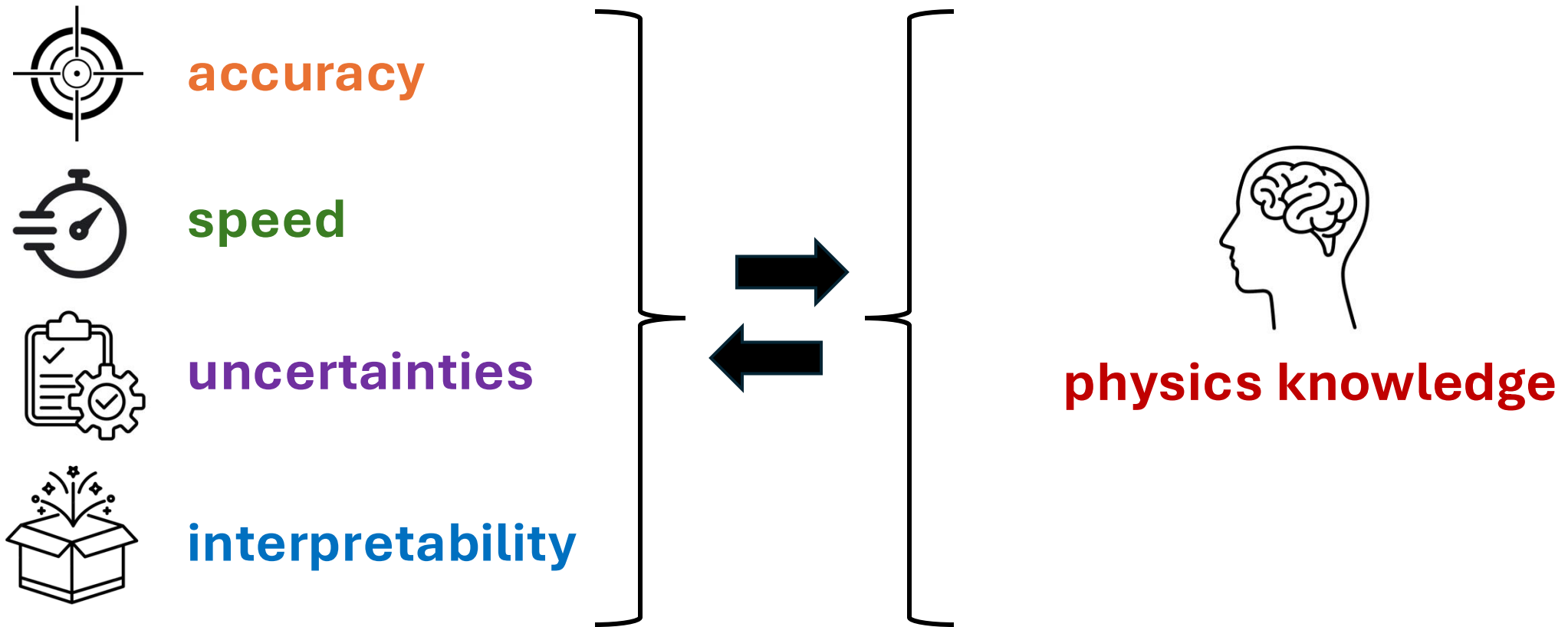
ML for particle physics



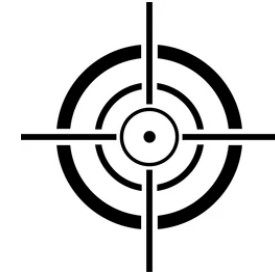
ML for particle physics



ML for particle physics

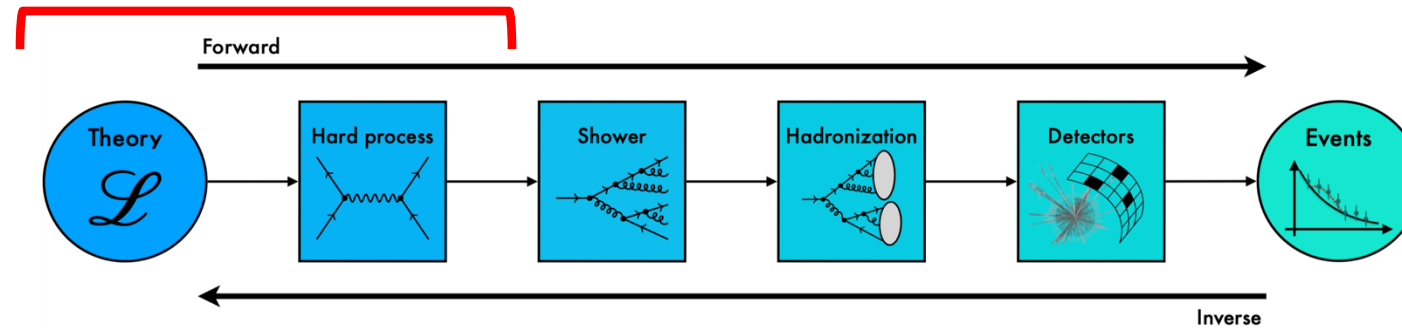


➡ Key to all these aspects: finding good representations of the data



Accuracy & speed

fast higher-order amplitude surrogates



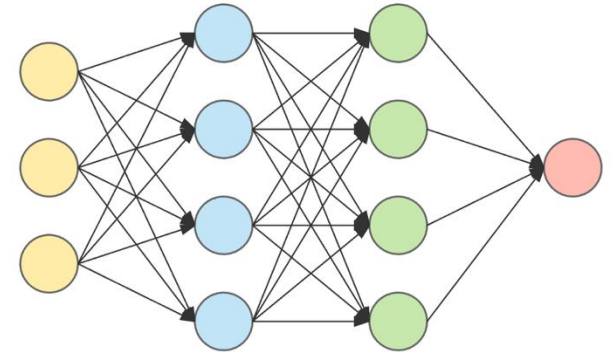
Amplitude surrogates

- evaluating analytic expressions for amplitudes $|\mathcal{M}|^2$ can be very expensive due to
 - higher-order corrections
 - large final-state multiplicities

- idea:
 - generate small training sample using full analytic expression
 - train a NN to approximate $|\mathcal{M}|^2$
 - generate events using NN surrogate → fast to evaluate

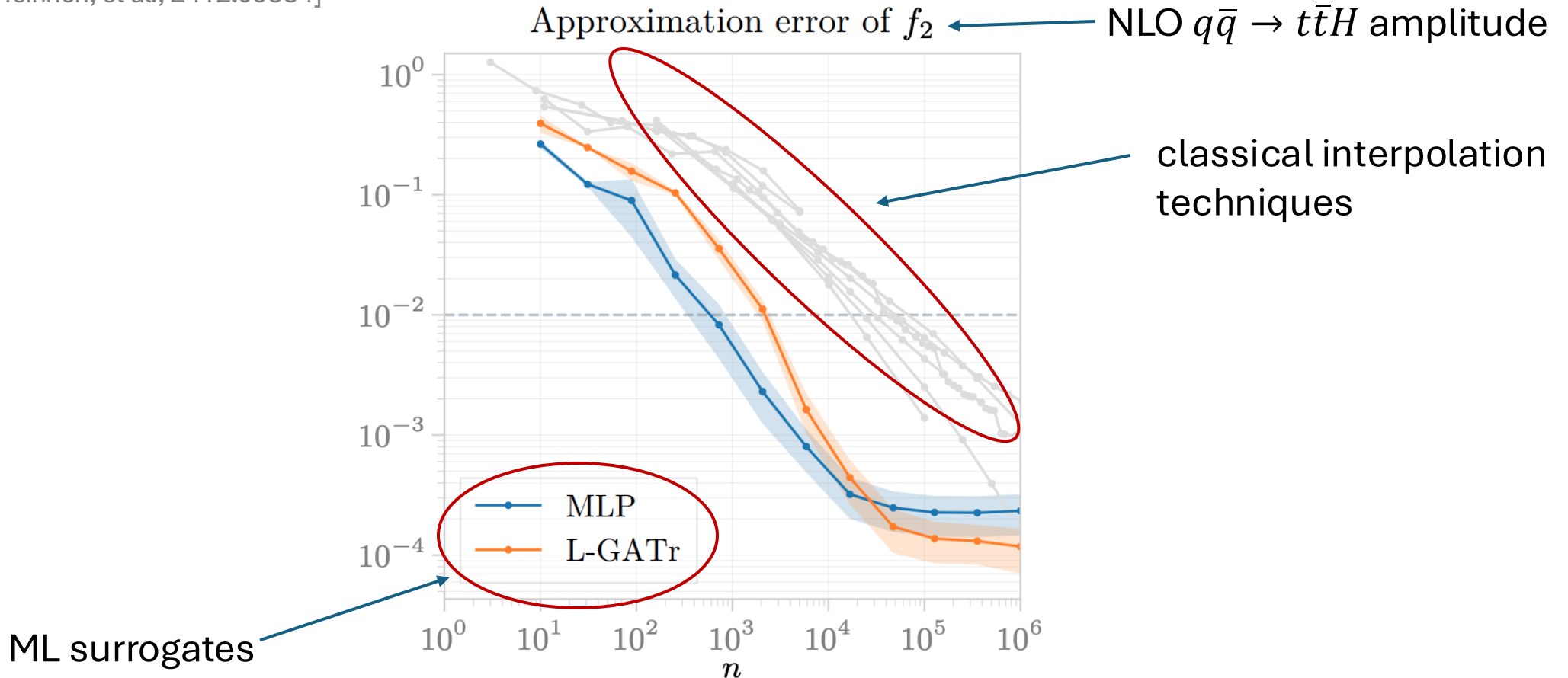
→ fast high-precision event generation

$$|\mathcal{M}|^2 \approx$$



Comparison to classical interpolation

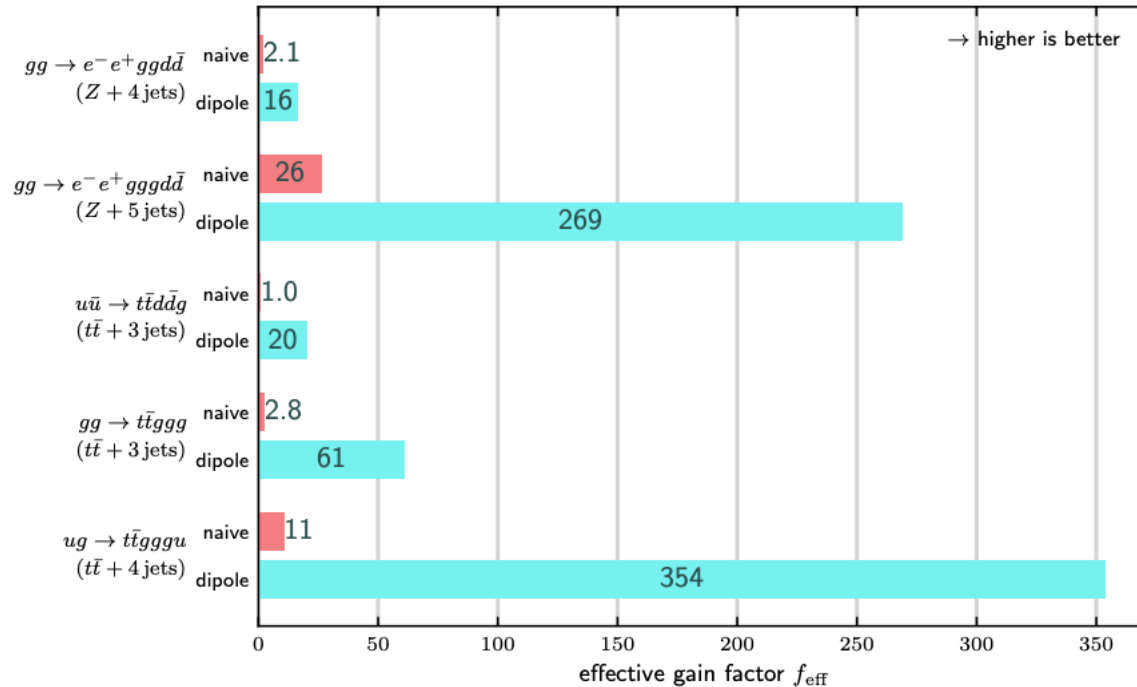
[Bresó, Heinrich, et al., 2412.09534]



➡ ML surrogates outperform classical interpolation techniques

Speed comparison

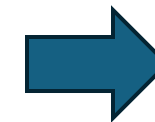
[Janßen et al., 2301.13562]



$$f_{\text{eff}} = \frac{T_{\text{standard}}}{T_{\text{surrogate}}}$$



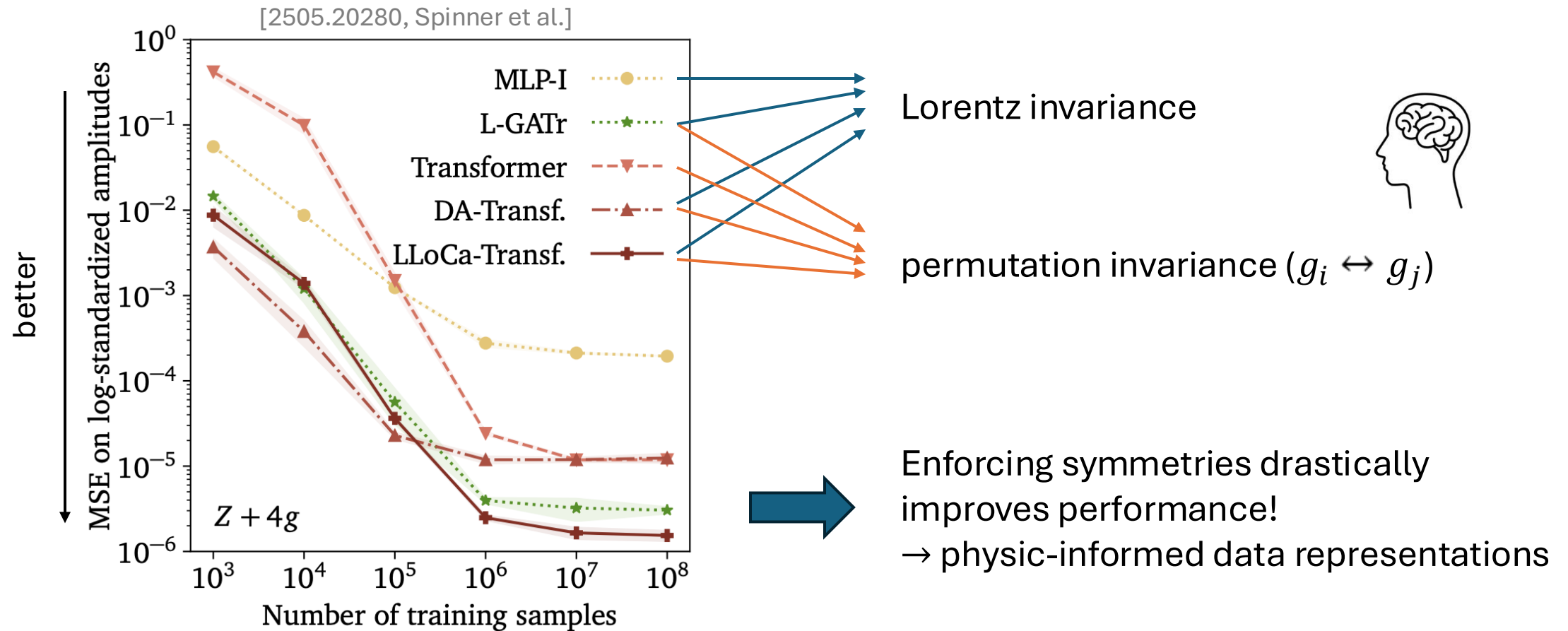
dipole vs naïve:
encode singularity structure of amplitudes



Large speed-ups possible!

Process	SHERPA default			with dipole-model surrogate				f_{eff}
	$t_{\text{ME}}[\text{ms}]$	$t_{\text{PS}}[\text{ms}]$	ϵ_{full}	$t_{\text{surr}}[\text{ms}]$	x_{max}	$\epsilon_{\text{1st,surr}}$	$\epsilon_{\text{2nd,surr}}$	
$gg \rightarrow e^- e^+ gg d \bar{d}$	54	0.40	1.411 %	0.14	2.6	1.418 %	39 %	16
$gg \rightarrow e^- e^+ g g d \bar{d}$	16 216	5.70	0.076 %	0.20	3.6	0.085 %	29 %	269

Exploiting known symmetries



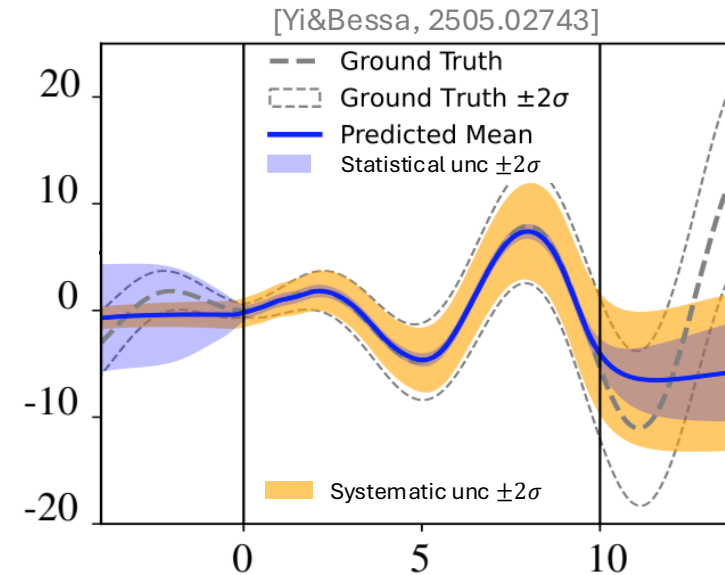
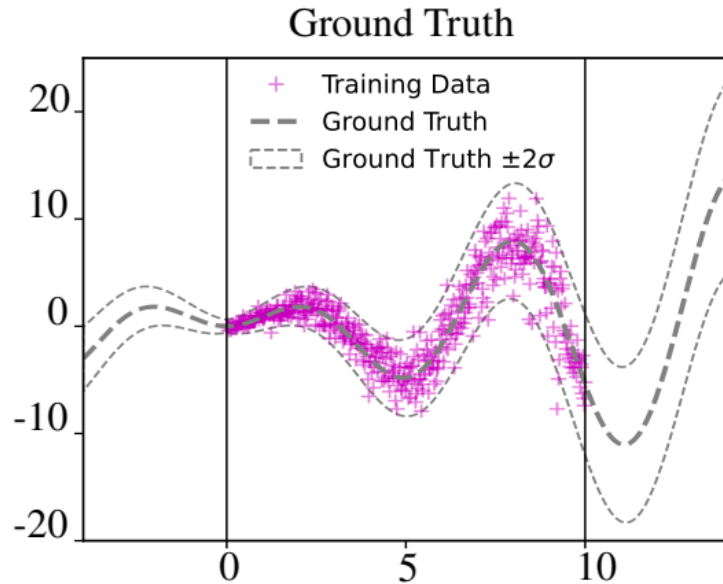


Uncertainties

"All models are wrong, but some — those that know when they can be trusted — are useful!"

George Box (adapted)

Regression with uncertainties



- statistical uncertainty $\hat{=}$ lack of training data
- systematic uncertainty $\hat{=}$ noise in the data, lack in model expressivity




Can we the NNs encode a representation of their own uncertainties?

Probabilistic learning

Learn amplitude statistically

NN parameters

$$p(A|x) = \int d\theta p(\theta|D_{\text{train}}) p(A|x, \theta) \approx \int d\theta q(\theta) p(A|x, \theta)$$


Then, we can calculate the mean prediction and uncertainties as

$$A_{\text{NN}}(x) = \int dA A p(A|x) = \int d\theta q(\theta) \bar{A}(x, \theta) \quad \text{with} \quad \bar{A}(x, \theta) = \int dA A p(A|x, \theta)$$

$$\sigma_{\text{syst}}^2(x) = \int d\theta q(\theta) [\bar{A}^2(x, \theta) - \bar{A}(x, \theta)^2] \quad \longrightarrow \quad \text{vanishes for perfect data: } p(A|\theta) \rightarrow \delta(A - A_0)$$

$$\sigma_{\text{stat}}^2(x) = \int d\theta q(\theta) [\bar{A}(x, \theta) - A_{\text{NN}}(x)]^2 \quad \longrightarrow \quad \text{vanishes for perfect training: } q(\theta) \rightarrow \delta(\theta - \theta_0)$$

Modelling the systematic uncertainty

- log-likelihood loss:

$$\mathcal{L} = - \sum_{x_i, A_i \in D_{\text{train}}} \log p(A_{\text{true}}(x_i) | x_i, \theta)$$

true amplitudes

phase-space point

- assume Gaussian likelihood: $p(A|x) = \mathcal{N}(\bar{A}(x), \sigma_{\text{syst}}^2(x))$

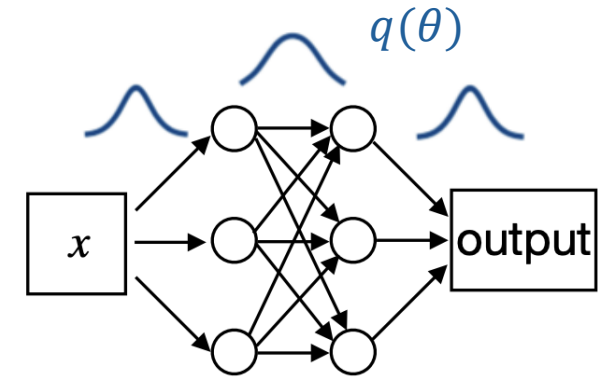
- NN learns both: $\bar{A}(x)$ and $\sigma_{\text{syst}}(x)$

$$\Rightarrow \text{heteroskedastic loss: } \mathcal{L} = \sum_i \left[\frac{(\bar{A}(x_i) - A_{\text{true}}(x_i))^2}{2\sigma_{\text{syst}}^2(x_i)} + \log(\sigma_{\text{syst}}(x_i)) \right]$$

- if needed: replace by Gaussian mixture model

Modelling the statistical uncertainty

- variational approximation: $p(\theta|D_{\text{train}}) \simeq q(\theta)$
- promote each NN parameter to Gaussian distribution
- train by minimizing KL divergence:



$$\begin{aligned} \text{KL}[q(\theta), p(\theta|D_{\text{train}})] &= \int d\theta \, q(\theta) \log \frac{q(\theta)}{p(\theta|D_{\text{train}})} \\ \text{Bayes' theorem} \quad &\rightarrow = \int d\theta \, q(\theta) \log \frac{q(\theta)p(D_{\text{train}})}{p(\theta)p(D_{\text{train}}|\theta)} \\ &= \underbrace{\text{KL}[q(\theta), p(\theta)]}_{\text{prior}} - \underbrace{\int d\theta \, q(\theta) \log p(D_{\text{train}}|\theta)}_{\text{log likelihood}} + \dots \end{aligned}$$

Alternative: repulsive ensembles

- can describe NN training via ODE or continuity equation:

$$\frac{d\theta}{dt} = v(\theta, t) \quad \text{or} \quad \frac{\partial \rho(\theta, t)}{\partial t} = -\nabla_{\theta} [v(\theta, t)\rho(\theta, t)]$$

- choose $v(\theta, t) = -\nabla_{\theta} \log \frac{\rho(\theta, t)}{\pi(\theta)}$ → solution: $\rho(\theta) = \pi(\theta) \equiv p(\theta|D_{\text{train}})$

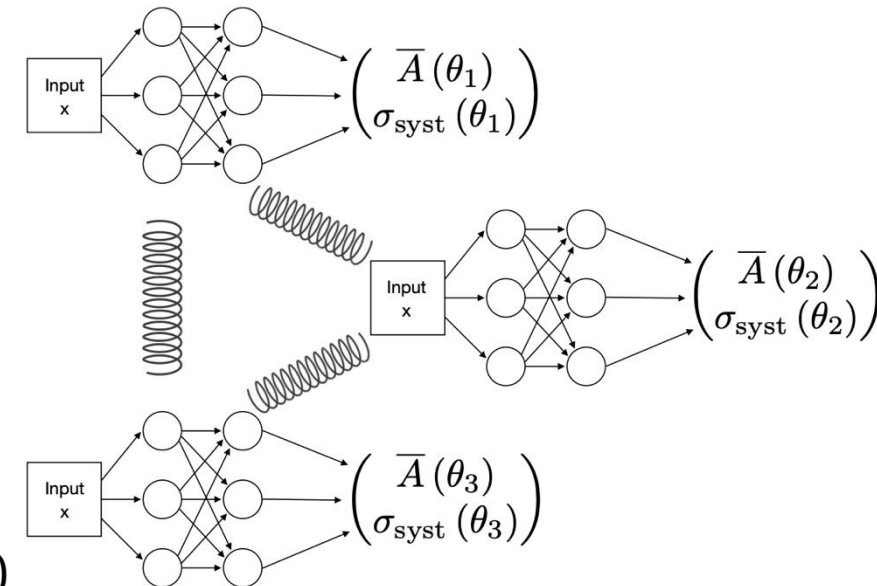
- estimate density via NN ensemble: $\rho(\theta^t) \approx \frac{1}{n} \sum_{i=1}^n k(\theta^t, \theta_i^t)$

kernel

- NN parameter update rule

$$\frac{d\theta}{dt} = -\nabla_{\theta} \left[\log \left(\frac{1}{n} \sum_i k(\theta, \theta_i) \right) - \log p(\theta|x) \right]$$

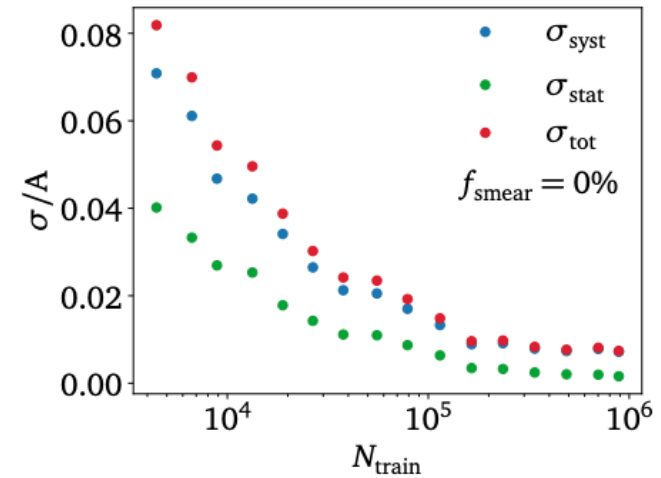
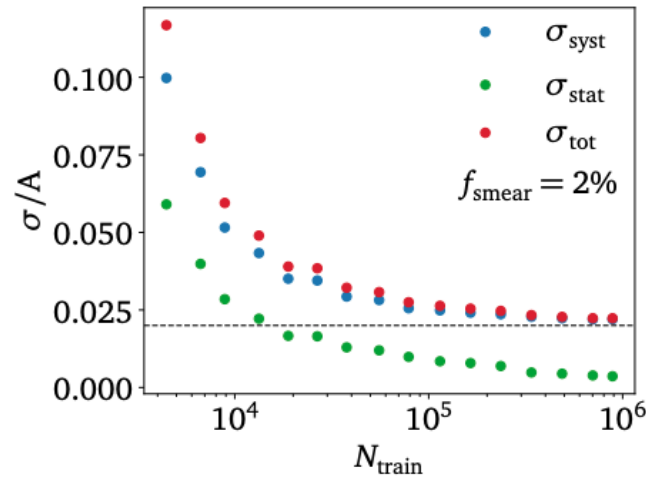
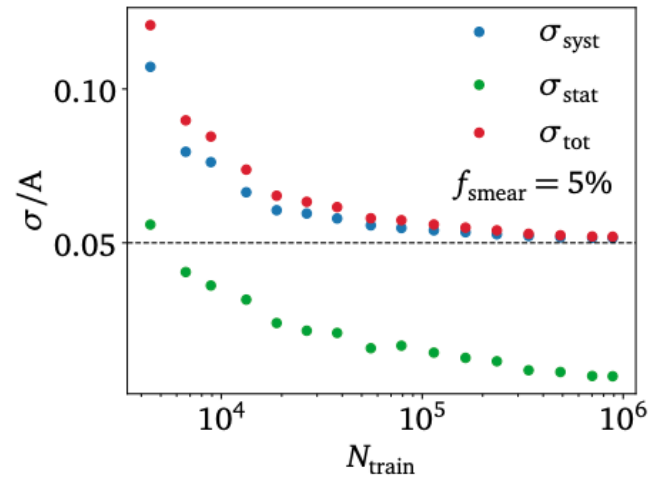
➡ NN ensemble with repulsive force ensuring $\theta \sim p(\theta|D_{\text{train}})$



Behavior of uncertainties

[HB et al., 2412.12069]

$$A_{\text{train}} \sim \mathcal{N}(A_{\text{true}}, \sigma_{\text{train}}^2)$$
$$\sigma_{\text{train}} = f_{\text{smear}} A_{\text{true}}$$



test: apply Gaussian noise to $gg \rightarrow \gamma\gamma g$ amplitudes

- statistical unc. decreases with more training data
- systematic unc. converges to level of applied noise

→ reliable uncertainty estimate

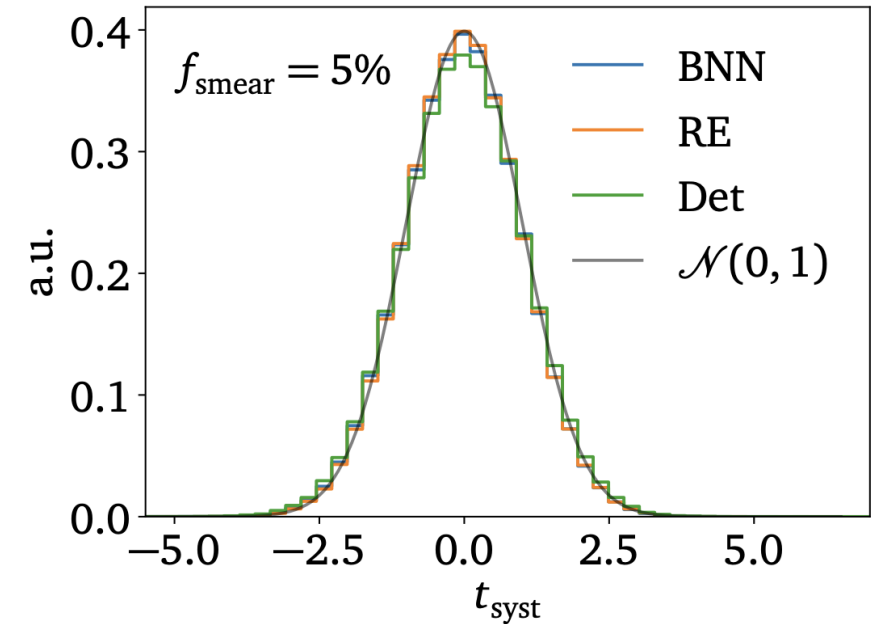
Are these uncertainties calibrated?

- statistical uncertainties play minor role for amplitude regression

- define systematic pull:

$$t_{\text{syst}} = \frac{\langle A \rangle(x) - A_{\text{train}}(x)}{\sigma_{\text{syst}}(x)}$$

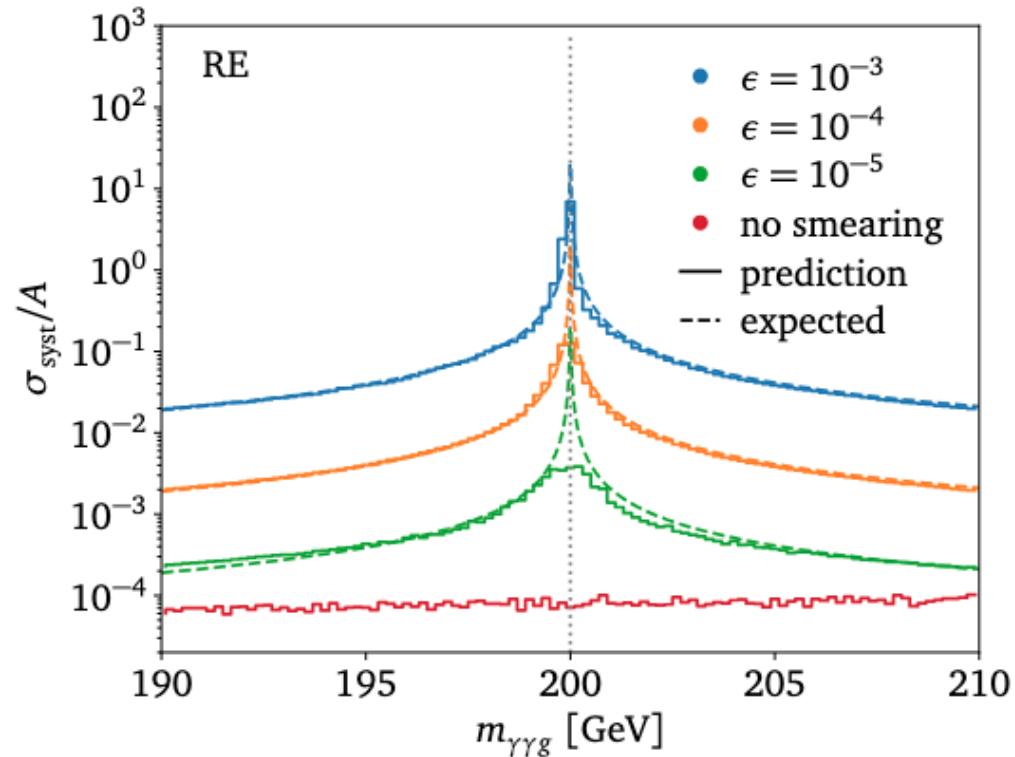
- if calibrated, t_{syst} distribution should follow $\mathcal{N}(0, 1)$



Almost perfectly calibration → reliable uncertainty estimate

Localized noise

[HB et al., 2509.00155]



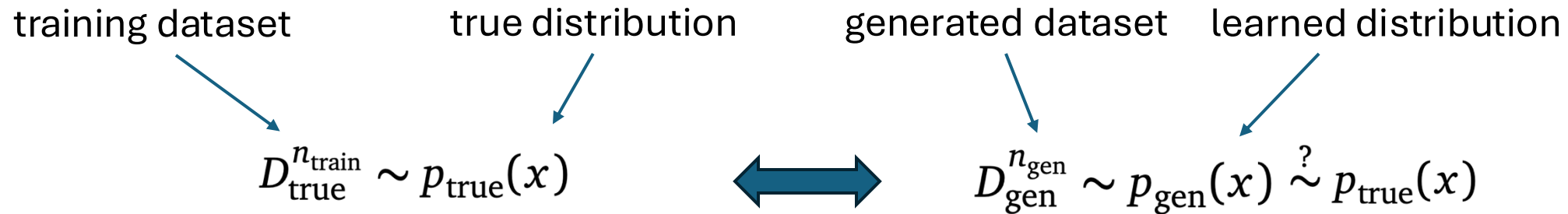
$$A_{\text{train}}(x) = \mathcal{N}\left(A_{\text{true}}(x), \frac{\epsilon m_{\text{thresh}}}{|m_{\gamma\gamma g}(x) - m_{\text{thresh}}|} A_{\text{true}}(x)\right)$$

- emulates numerical noise close to threshold
- well captured by systematic uncertainties
- NN effectively finds the mean prediction
- uncertainties still well calibrated

Same techniques also applicable to all kind of other regression problems!

Controlling generative ML

[HB et al., 2509.08048]



How can we quantify the performance of the generative NN?

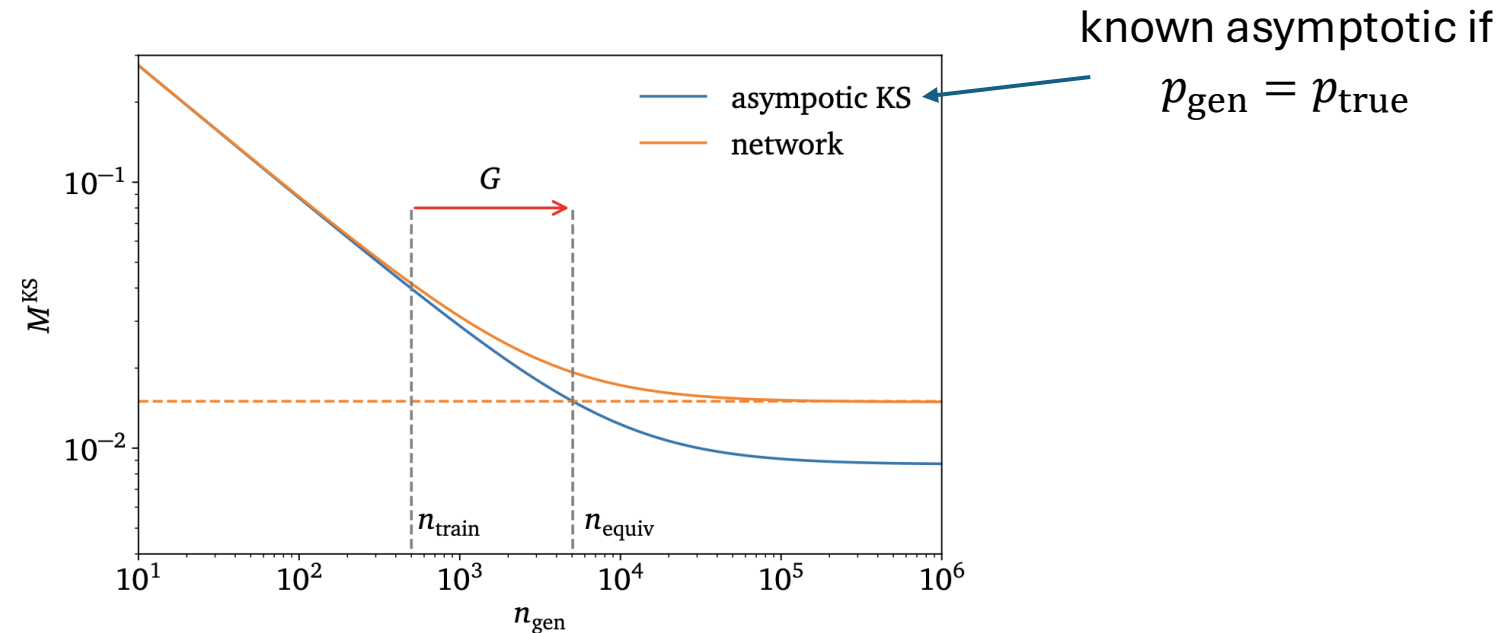
→ determine n_{equiv} such that $M(D_{\text{true}}^{n_{\text{equiv}}}, p_{\text{true}}(x)) \equiv M(D_{\text{gen}}^{n_{\text{gen}}}, p_{\text{true}}(x))$ with $D_{\text{true}}^{n_{\text{equiv}}} \sim p_{\text{true}}(x)$

comparison metric

amplification factor $G = \frac{n_{\text{equiv}}}{n_{\text{train}}}$

Controlling generative ML

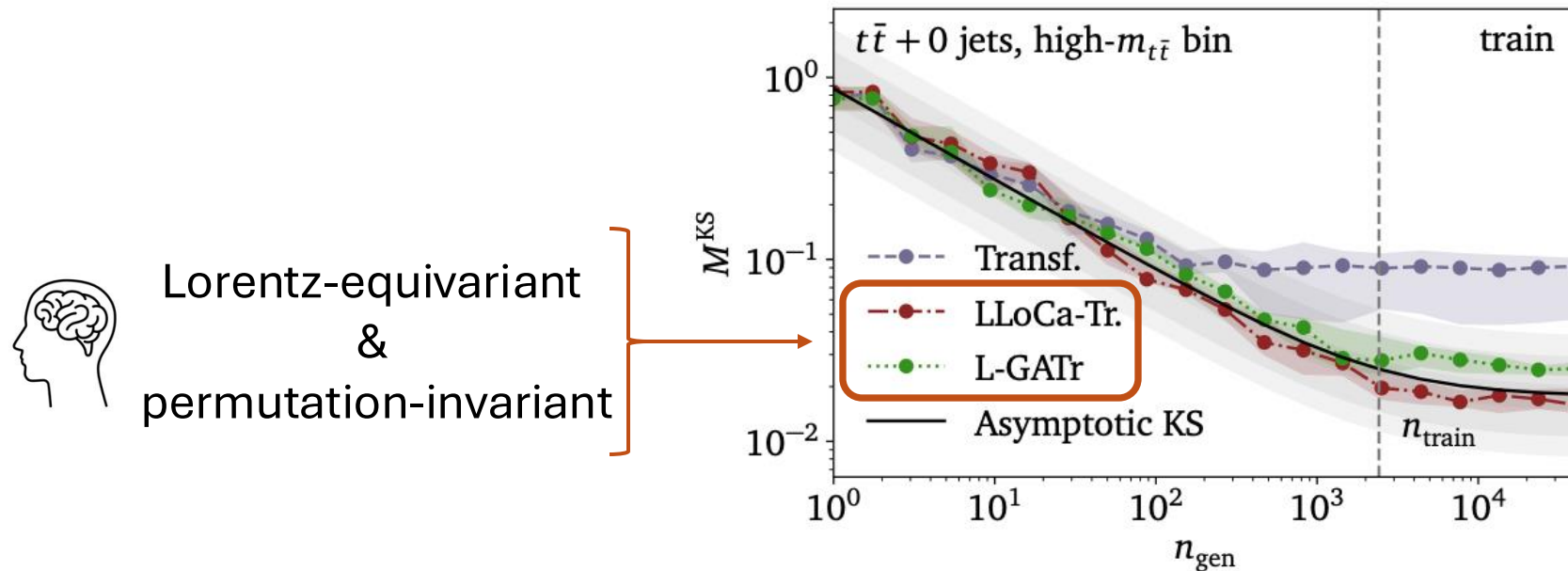
one option for M : Kolmogorov-Smirnov test comparing D_{train} and D_{gen}



➡ systematic approach to assess quality of generative NNs

Controlling generative ML

one option for M : Kolmogorov-Smirnov test comparing D_{train} and D_{gen}



➡ systematic approach to assess quality of generative NNs

Interpretable ML

looking under the hood



Back to the formula – symbolic regression

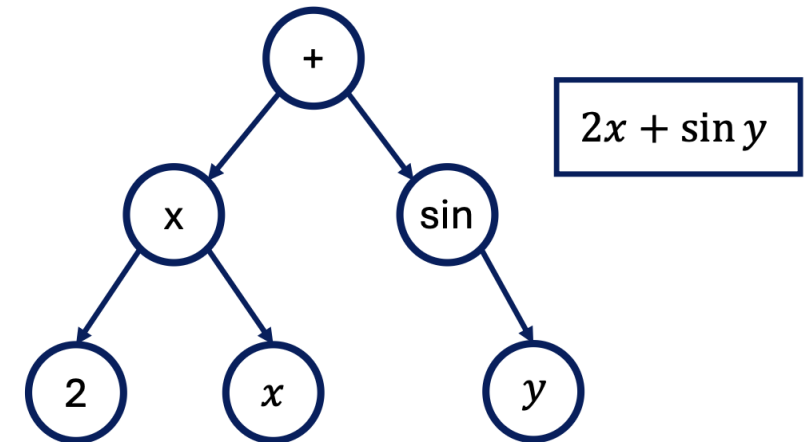
- many ways to make ML interpretable
- goal: find most relevant representation/observables describing the data

→ maximal interpretability: analytic equation!

- construct them dynamically using symbolic regression

[Schmidt&Lipson`09, Udrescu&Tegmark`19, Cranmer et al.`19,`20,`23]

- build upon genetic algorithm successively forming equation
- interplay between goodness-of-fit and complexity of equation



Example: Higgs CP test for VBF

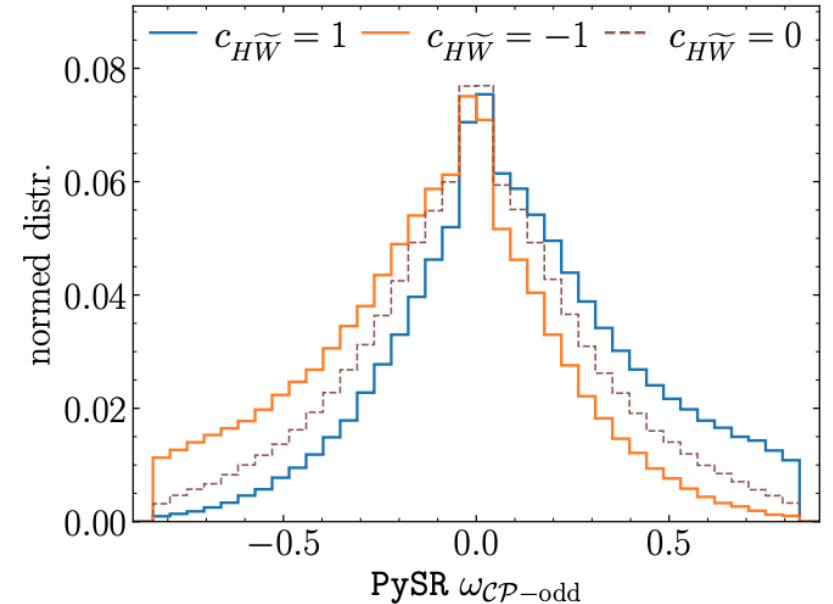
[HB et al., 2507.05858]

- consider dim-6 operator $\frac{c_{H\widetilde{W}}}{\Lambda^2} \Phi^\dagger \Phi \widetilde{W}_{\mu\nu}^a W^{a\mu\nu}$
- unambiguous CP test \rightarrow CP-odd observables
- construct optimal reco-level CP-odd obs. by training a classifier on $c_{H\widetilde{W}} = \pm 1$ samples
- analytic equation \rightarrow ensure learned observable is indeed CP-odd



$$d^{\text{PySR}} = \frac{1.8566 \sin \Delta \phi_{jj}}{\left| \frac{0.3080 x_{j_1} \log \Delta \eta_{jj} + \log \Delta \eta_{jj} \sinh(x_{j_2} - 2.5977) + 0.3080 \sinh x_h}{x_{j_1} \log \Delta \eta_{jj} + \sinh x_h} \right| + 0.6047}$$

with $x = p_T/m_h$



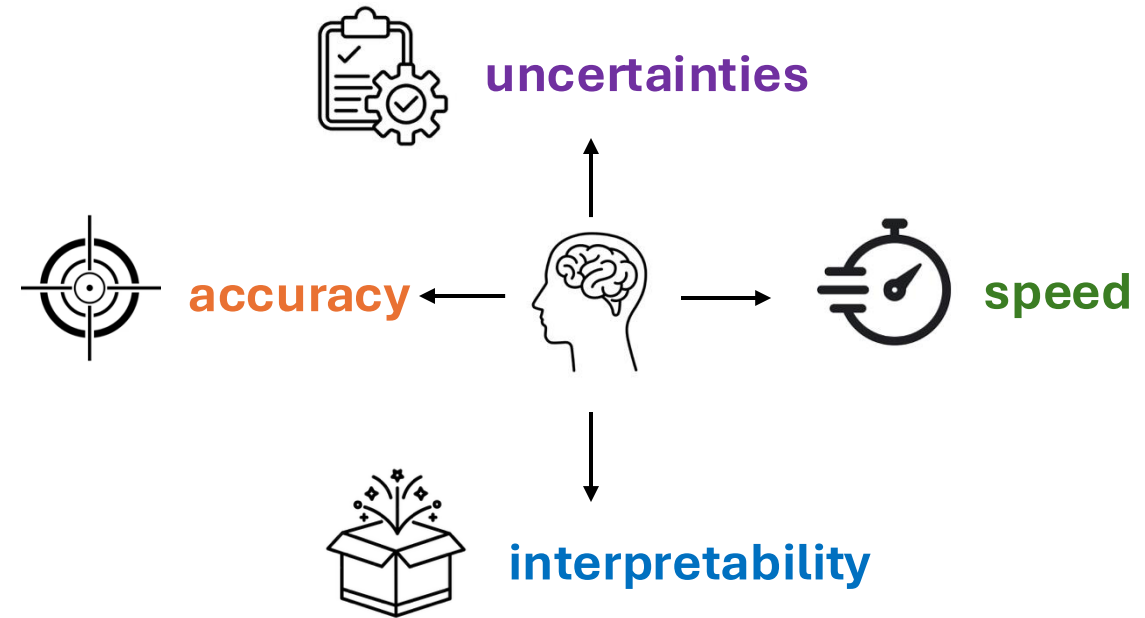
	$ \sigma(c_{H\widetilde{W}} = 1 \text{ vs. SM}) $
$p_{T,j_1} p_{T,j_2} \sin \Delta \phi_{jj}$	6.76
trained on $c_{H\widetilde{W}} = \pm 1$	
PySR	6.98
SymbolNet	7.07
BDT	6.71

Conclusions



Conclusions

- particle physics is in the precision era
→ large amounts of multidimensional data
- ML methods excel in such an environment
- important requirements: uncertainties and interpretability
- key ingredient: representation learning based on particle theory



ML is an essential tool for the future of particle physics

Appendix

The goal of particle physics

→ Answer the big fundamental questions!

Nature of EWSB

Neutrino masses

.....

Dark matter

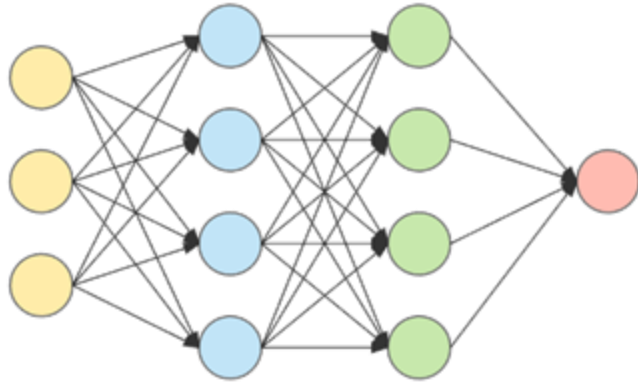
Baryon asymmetry

Naturalness

Can ML find answer these questions for us? **No!**

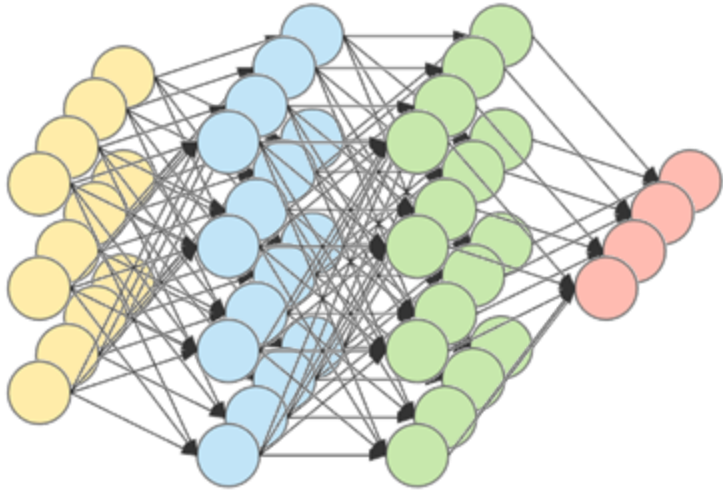
Can it help us with it? **Yes!**

Modelling the statistical uncertainty

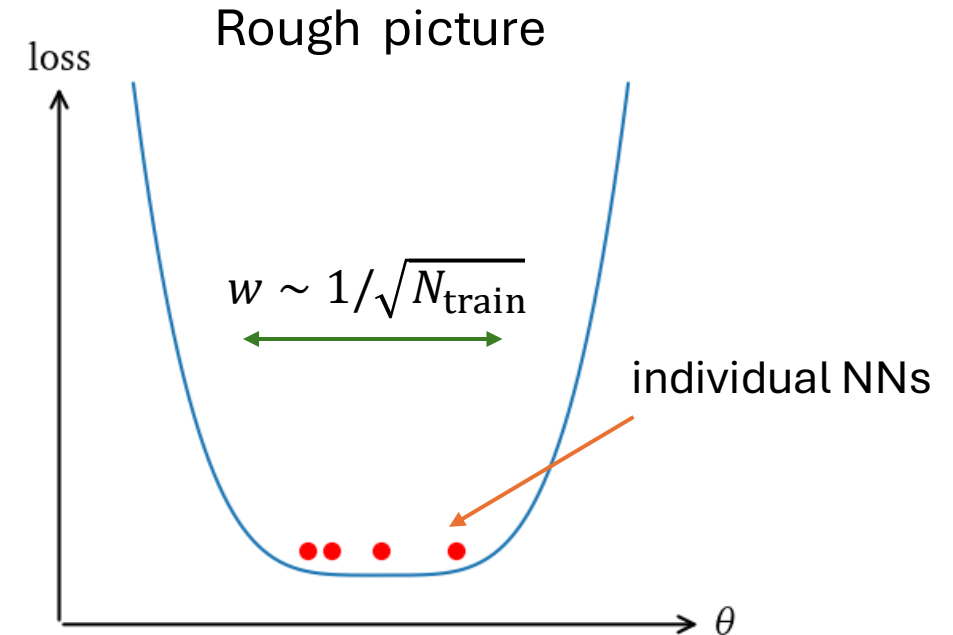


- train ensemble of networks
- each networks leads to slightly different result
- spread of network predictions \sim statistical uncertainty
- less data \rightarrow higher spread

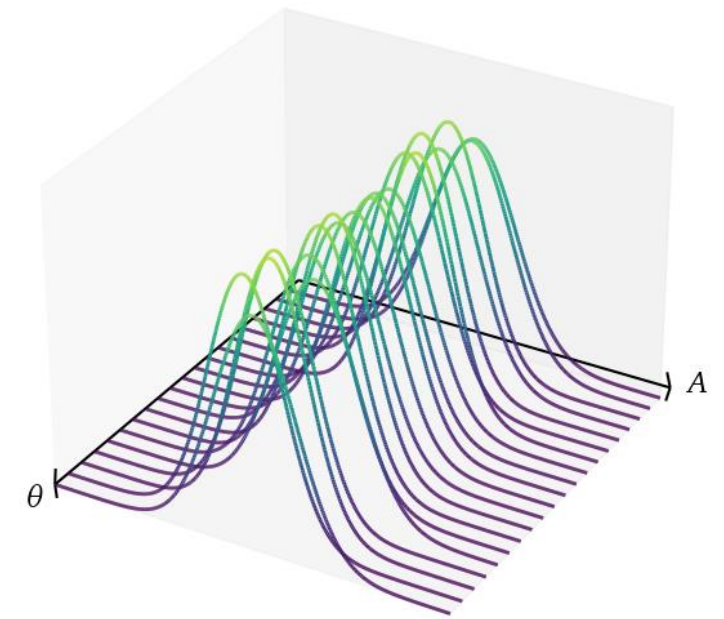
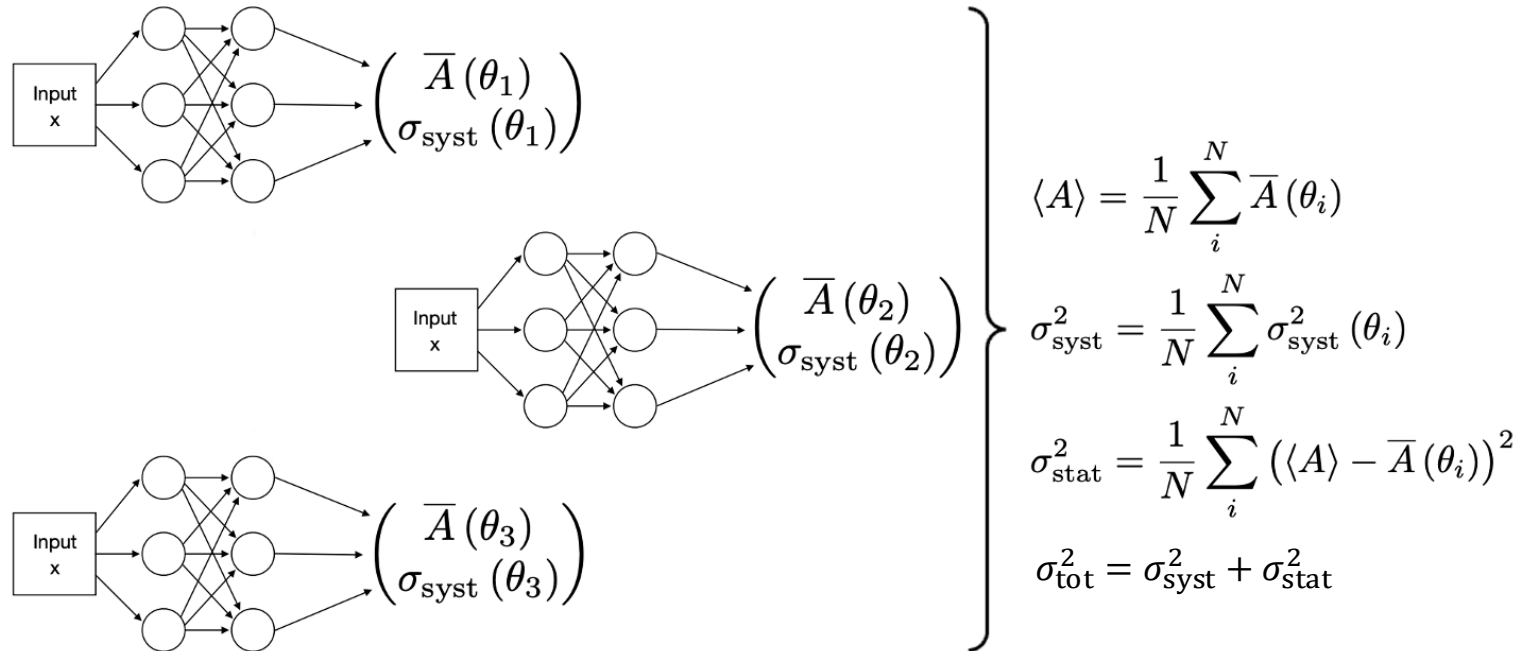
Modelling the statistical uncertainty



- train ensemble of networks
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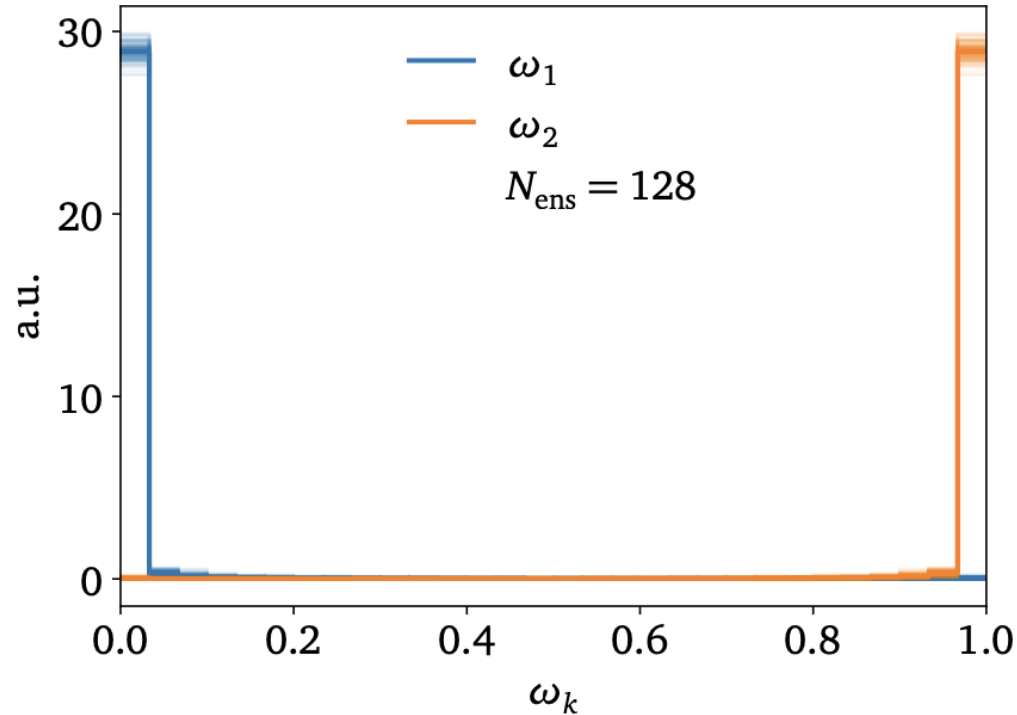
Bringing it all together



➡ Combined learnable modelling of systematic and statistical uncertainties!

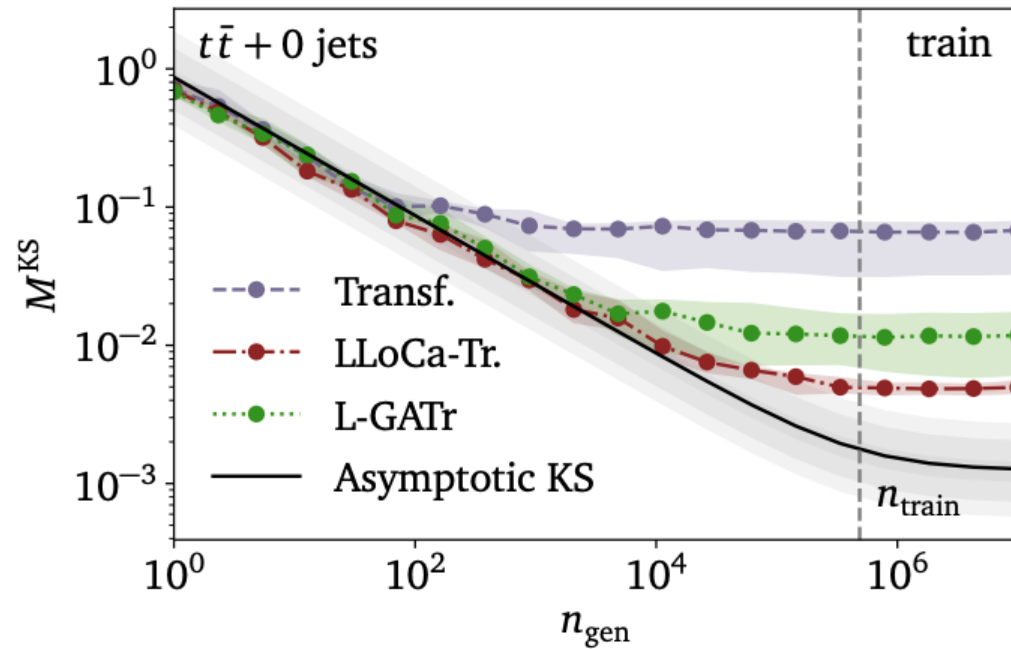
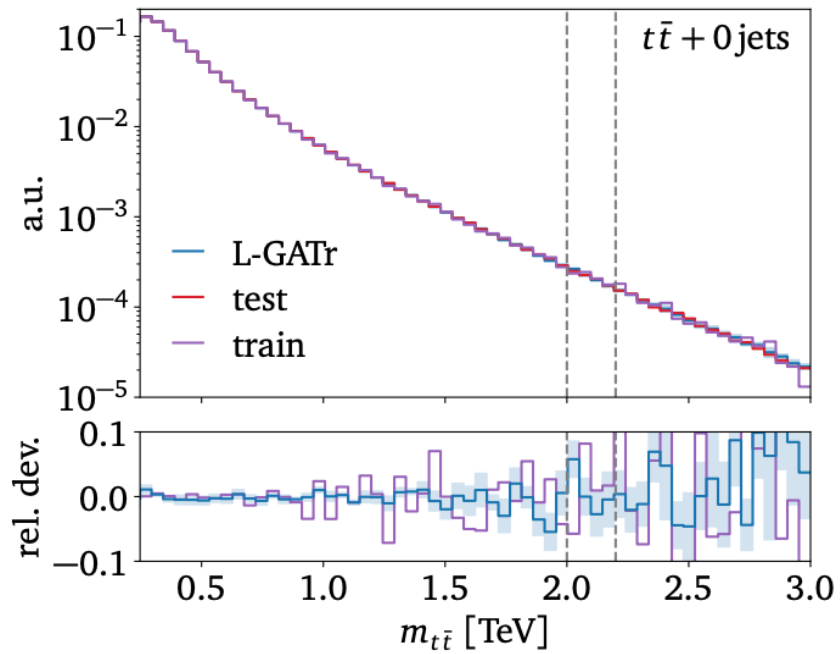
Alternative approaches: Bayesian neural networks, evidential regression

Gaussian mixture model



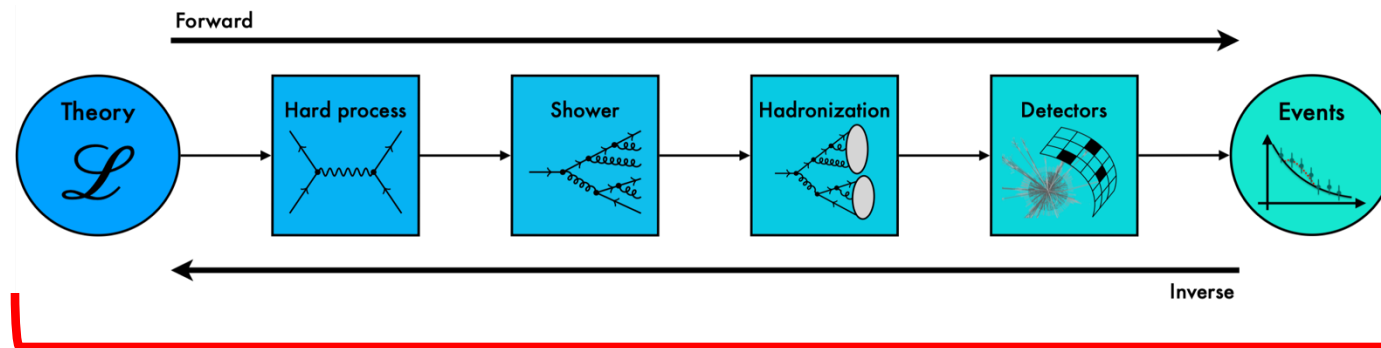
$$p_{\text{GMM}}(A|x, \theta) = \sum_{k=1}^K \omega_k(x, \theta) \mathcal{N}(A | \bar{A}_k(x, \theta), \sigma_k^2(x, \theta)), \quad \text{with} \quad \sum_{k=1}^K \omega_k(x, \theta) = 1$$

Controlling generative ML



Simulation-Based Inference

fully exploiting high-dimensional data



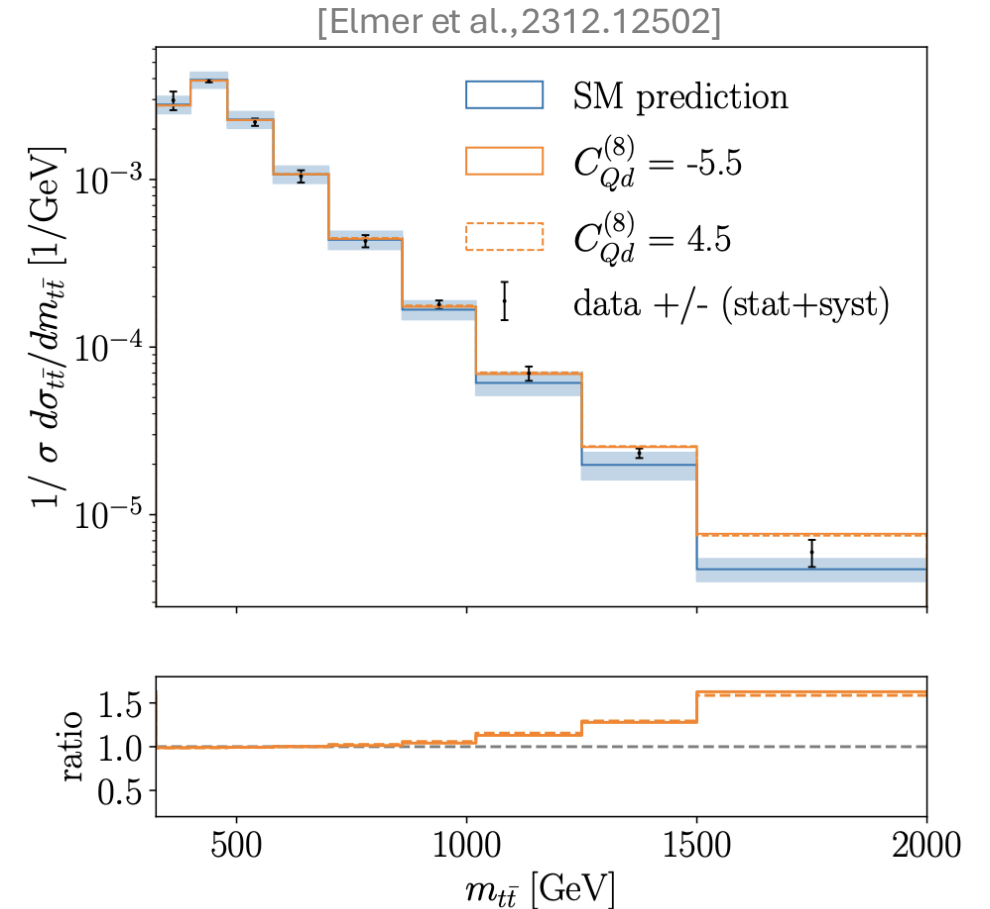
Classical parameter inference

- reduce dimension of phase space
summary statistics
- bin summary statistics
- compare resulting histogram to SM/BSM
predictions

Advantage: humanly digestible plots

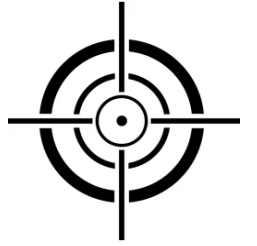
Disadvantage: loss of information

→



Full likelihood

phase space point theory parameters



- Monte-Carlo simulation chain allows us to sample full likelihood $p(x|\theta)$. But cannot directly compute it.
- Neyman-Pearson lemma: likelihood ratio $r(x|\theta, \theta_0) \equiv \frac{p(x|\theta)}{p(x|\theta_0)}$ is most powerful statistical test
- but we can regress to reco-level $r(x|\theta, \theta_0)$ using known parton-level $r(z_p|\theta, \theta_0)$:

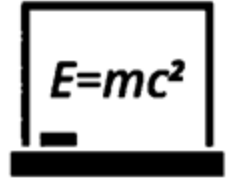
$$\mathcal{L} = \left\langle \left[r(z_p|\theta, \theta_0) - \underbrace{r_\varphi(x|\theta, \theta_0)}_{\text{NN}} \right]^2 \right\rangle_{\substack{x, z_p \sim p(x|z_p)p(z_p|\theta); \theta \sim q(\theta) \\ \text{average over event sample}}}$$



unbinned multi-dimensional inference without information loss

Encoding amplitude structure

[Schöfbeck et al., 2107.10859, 2205.12976]



Theory structure for e.g. SMEFT:

$$\mathcal{L}_{\text{SMEFT}} = \mathcal{L}_{\text{SM}} + \sum_i \frac{c_i}{\Lambda^2} O_i \equiv \mathcal{L}_{\text{SM}} + \sum_i \theta_i O_i$$

$$|\mathcal{M}(z_p|\theta)|^2 = |\mathcal{M}_{\text{SM}}(z_p)|^2 + \theta_i |\mathcal{M}_i(z_p)|^2 + \theta_i \theta_j |\mathcal{M}_{ij}(z_p)|^2$$



encode into likelihood

$$R(x|\theta, \theta_0) \equiv \frac{d\sigma(x|\theta)/dx}{d\sigma(x|\theta_0)/dx} = \frac{\sigma(\theta)p(x|\theta)}{\sigma(\theta_0)p(x|\theta_0)}$$

$$R(x|\theta, \theta_0) = 1 + (\theta - \theta_0)_i R_i(x) + (\theta - \theta_0)_i (\theta - \theta_0)_j R_{ij}(x)$$

$$R_i(z_p) \equiv \frac{\partial}{\partial \theta_i} \frac{d\sigma(z_p|\theta)/dz_p}{d\sigma(z_p|\theta_0)/dz_p} \Big|_{\theta=\theta_0} = \frac{\partial_{\theta_i} |\mathcal{M}(z_p|\theta)|^2}{|\mathcal{M}(z_p|\theta_0)|^2} \Big|_{\theta_0}$$

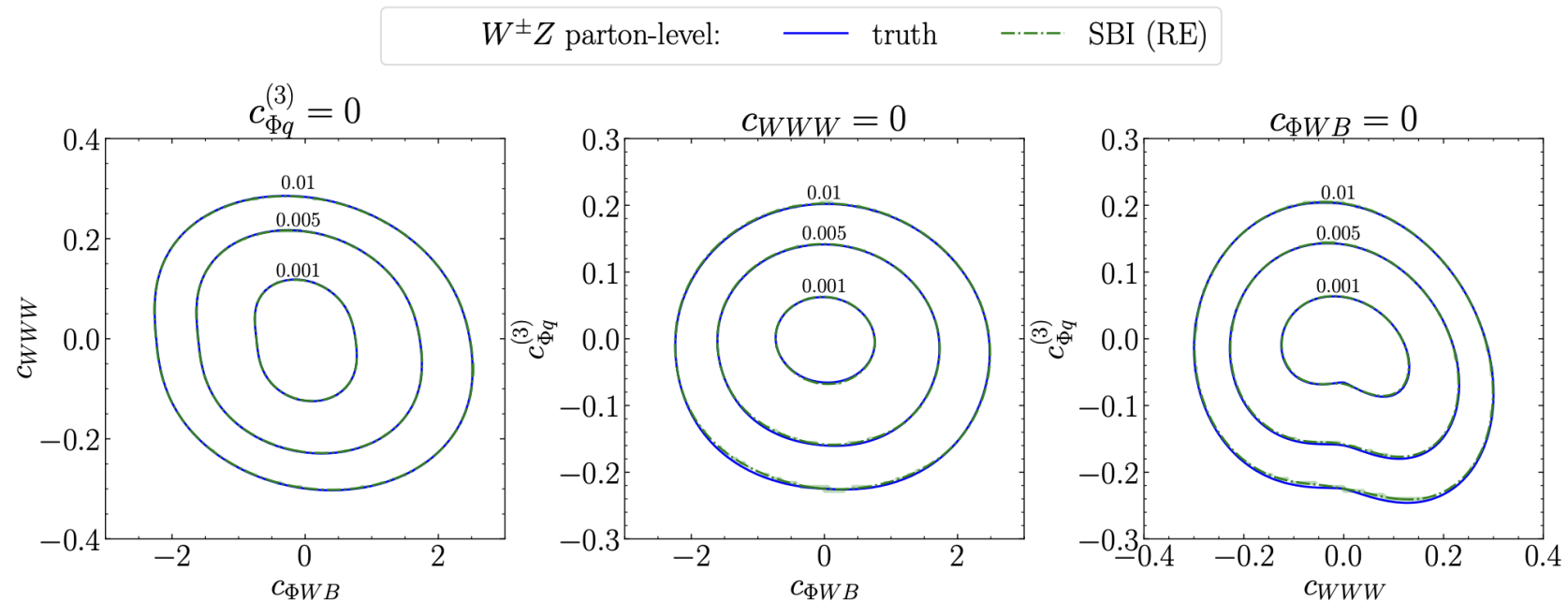
$$R_{ij}(z_p) \equiv \frac{\partial^2}{\partial \theta_i \partial \theta_j} \frac{d\sigma(z_p|\theta)/dz_p}{d\sigma(z_p|\theta_0)/dz_p} \Big|_{\theta=\theta_0} = \frac{\partial_{\theta_i} \partial_{\theta_j} |\mathcal{M}(z_p|\theta)|^2}{|\mathcal{M}(z_p|\theta_0)|^2} \Big|_{\theta_0}$$



learn coefficients $R_{i,j}$ separately \rightarrow theory parameter dependence fully factored out

Parton-level cross-check: $W^\pm Z$ production

- consider effects of three SMEFT operators



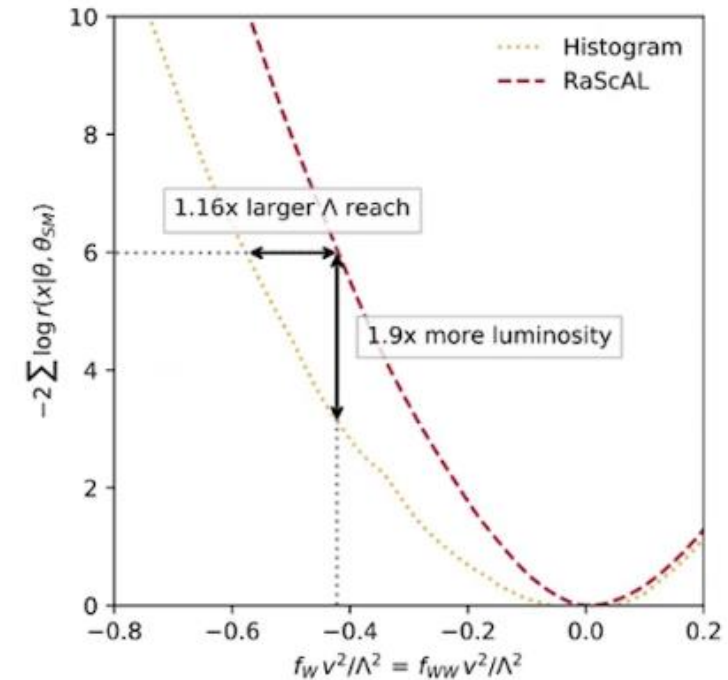
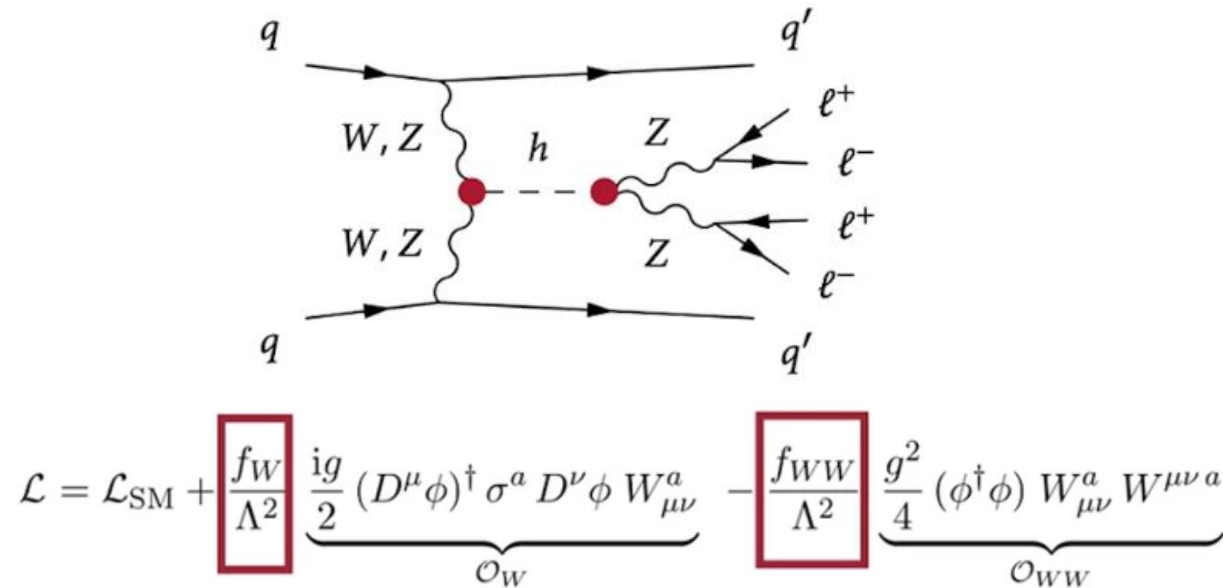
[HB et al., 2410.07315]



almost perfectly learns high-dimensional likelihood

Reco-level: VBF with $H \rightarrow 4\ell$

[Brehmer et al., 1805.00013]



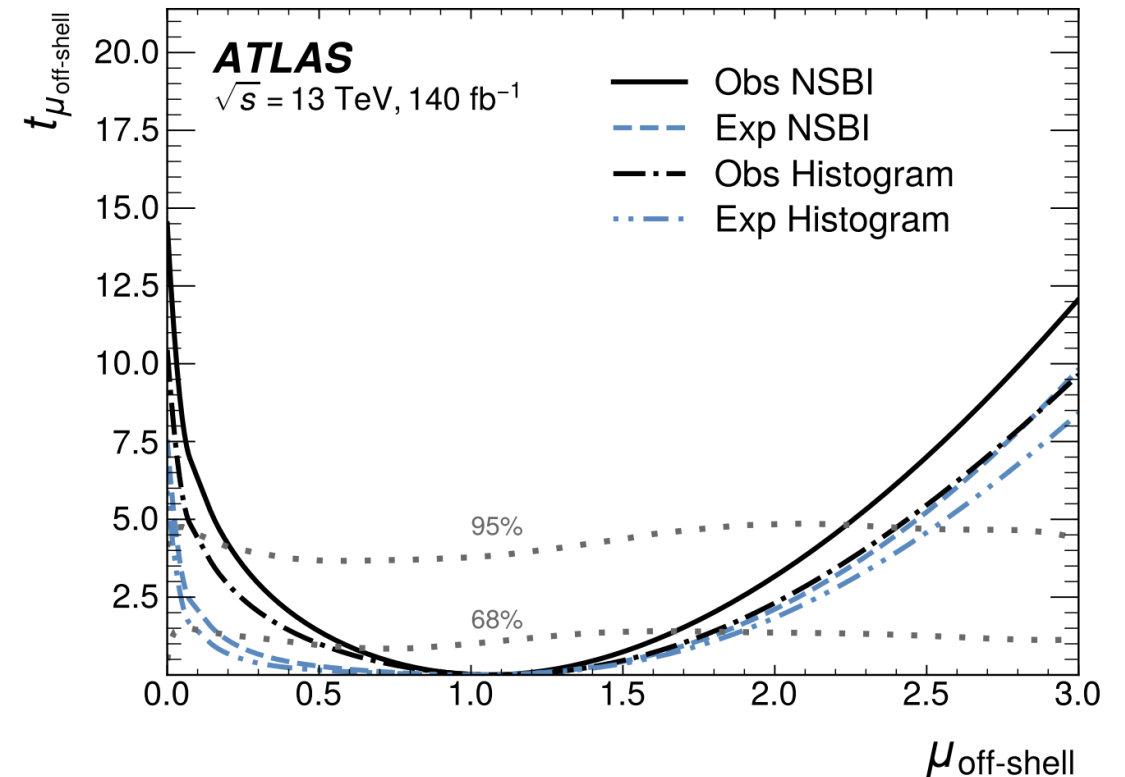
➡ Huge potential to improve sensitivity of a wide variety of measurements/searches

But is SBI also viable in a realistic analysis including uncertainties etc.?

1st experimental SBI analysis

[ATLAS-CONF-2024-016]

- goal: measure off-shell signal strength in $H \rightarrow ZZ$ channel
- full treatment of statistical and systematic uncertainties
- large sensitivity improvement for low $\mu_{\text{off-shell}}$



➡ proves potential of SBI for full experimental analysis