# Dispersion Measurements at the VUV-FEL 

Accelerator Studies - Week 142006
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## Overview

INTERMEDIATE GOAL
Obtain a dispersion in the undulator smaller than 1 cm in both planes

GOAL of WEEKS 14\&16

- Measurement of orbit and dispersion response for all the steerers and quads
- Measure and correct dispersion

DIFFICULTIES (week 14)

- Charge instability
- Losses in the undulator

ACHIEVEMENTS (week 14)

- Successful test of on-crest phase measurement (ACC1)
- Measured orbit \& dispersion response for 18 steerers (up to ACC2)


## Beam jitter too high during part of the shift...



## On-crest phase measurement

- The idea is to make a phase scan and look at the orbit response in the BPM's
- For each BPM a $2^{\text {nd }}$ order fit is done, and maximum/minimum is derived.
- Maximum/minimum corresponds to the on-crest phase.
- This method is very reliable since all BPM's in the machine can be used.


## On-crest phase measurement (ACC1)



## On-crest phase measurement (ACC1)



## On-crest phase measurement (ACC1)



## Orbit and dispersion response measurements


$\Delta x_{i} / \Delta D_{i}$---------> change of the orbit / dispersion at the BPM $i$ $\Delta \theta_{j} \quad$---------> change of the kick angle of the steerer $j$

## We measured the response for the following correctors:

H1OACC1 - H1UBC2 - H1DBC2 - H2DBC2 - H4DBC2 - H5DBC2 - H8DBC2 - H9DBC2 - H11DBC2
V10ACC1 - V1UBC2 - V1DBC2 - V2DBC2 - V4DBC2 - V6DBC2 - V8DBC2 - V10DBC2 - V11DBC2

## Orbit and dispersion response measurements example: H10ACC1



Dispersion Response for H10ACC1


## Orbit and dispersion response measurements example: H4DBC2



## Orbit and dispersion response measurements example: V10ACC1




## Difference between measurements and simulations (horizontal case)



## Difference between measurements and simulations (vertical case)



## Summary \& next measurements

- Successful test of on-crest phase measurement using the orbit response in the BPMs
- Measured orbit \& dispersion response for 18 steerers. Still remaining about 40 steerers and 20 quad movers.
- Next steps:

Analyze obtained data (J. Keil)
Measure response for the rest of steerers and quads ( $\sim 1.5$ shifts) Measure and correct dispersion along the machine ( $3 \times \frac{1}{2}$ shifts)

## Thank you!

