

Excercise Sheet 2 to General Relativity

Prof. Günter Sigl
II. Institut für Theoretische Physik der Universität Hamburg
Luruper Chaussee 149
D-22761 Hamburg
Germany
email: sigl@mail.desy.de
tel: 040-8998-2224

Discussion on 2.11.2012 in the exercise classes

1. Contravariant and Covariant Vectors

The components a^μ of a contravariant vector transform as

$$a'^\mu = \Lambda^\mu{}_\nu a^\nu$$

under a Lorentz transformation $\Lambda^\mu{}_\nu$.

(a) Show that the components

$$a_\mu \equiv \eta_{\mu\nu} a^\nu$$

of the corresponding covariant vector (often also called *dual vector*) transforms as

$$a'_\mu = \Lambda_\mu{}^\nu a_\nu,$$

where we introduced the notation

$$\Lambda_\mu{}^\nu \equiv \left(\Lambda^{-1}\right)^\nu{}_\mu.$$

(b) By introducing a set of *basis vectors* $e_{(\mu)}$ a (contravariant) vector can also be defined in an abstract way as a quantity

$$a \equiv a^\mu e_{(\mu)}$$

which is independent of the coordinate system. Show that the set of basis vectors then transforms as

$$e'_{(\mu)} = \Lambda_\mu{}^\nu e_{(\nu)}.$$

please turn over

2. Commutators of Vector Fields

For two smooth vector fields v and w the *commutator* is defined by

$$[v, w](f) \equiv v[w(f)] - w[v(f)], \quad (1)$$

for all smooth (C^∞) functions $f : M \rightarrow \mathbb{R}$.

(a) Show that the definition Eq. (1) satisfies the linearity and Leibnitz properties and thus defines a vector field.

(b) Show that the components of the commutator of two smooth vector fields v and w are given by

$$[v, w]^\mu = v^\nu \frac{\partial w^\mu}{\partial x^\nu} - w^\nu \frac{\partial v^\mu}{\partial x^\nu} \quad (2)$$

in any coordinate system.

(c) Show that any three smooth vector fields X, Y, Z satisfy the *Jacobi identity*,

$$[[X, Y], Z] + [[Y, Z], X] + [[Z, X], Y] = 0. \quad (3)$$

3. Coordinate Transformations of the Metric Tensor

The metric of special relativity is given by the Lorentz metric

$$ds^2 = dt^2 - dx^2 - dy^2 - dz^2 \quad (4)$$

Derive the components of the metric $g_{\mu\nu}$ and the inverse metric $g^{\mu\nu}$ in the rotating coordinate frame given by

$$\begin{aligned} t' &= t, \\ x' &= (x^2 + y^2)^{1/2} \cos(\phi - \omega t), \\ y' &= (x^2 + y^2)^{1/2} \sin(\phi - \omega t), \\ z' &= z, \end{aligned}$$

where $\phi = \arctan y/x$.