

INDEPENDENT OPERATION OF ELECTRON/POSITRON WINGS OF ILC

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Abstract

We represent a concept of fast feedback system allowing independent operation of electron-positron wings of ILC.

INTRODUCTION

The Future Linear Collider ILC, if build, will be equipped with undulator conversion system. This system allows polarized electron/positron collisions and makes problems for target less critical [1], [2]. The level of positron/electron polarization can reach 85% with a 200-m long undulator [1].

Independence of electron and positron wings of linear collider is very suitable property of LC. First, there is no necessity for transport channel traversing IP. Second, as the collider will be filled by structures from one side until it is completed, the possibility to make a choice which one it is –electron or positron –is much appreciated.

Similar to asymmetric B-factory, no doubt, Linear Collider (LC) will be used with the beams having *different* energy. This allows intermediate particle to move some distance out from the point of creation. This might be especially important is search of Higgs and short-lived resonances.

In this publication we consider some details of the scheme with independent electron/positron operation, allowed by fast feedback system. Technical details of Starter electron source, which serves for initial accumulation of particles (see below), when they are lost, will be described in other place.

LINEAR COLLIDER

Scheme which allows independent operation of positrons and electrons in ILC in comparison with baseline one is represented in Fig.1 [1].

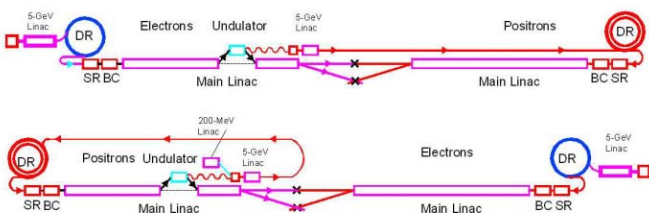


Figure 1: Base-line scheme for positron production, upper sketch. Scheme which allows independent electron and positron sections of the linac, below. SR stands for spin rotator, BC –for bunch compressor.

Here basically ~ 150 GeV positrons deflected from the accelerator line into undulator, generate there gammas, which are directed to the conversion target. Meanwhile these primary positrons are returned to the acceleration line and are going further to IP. So the new positrons just generated from radiation emitted by these primary ones.

Generally speaking the positrons generated from electricity. Additional 200-MeV linac required for restoration of positrons, when the beam is lost. This considered as rare event. Two targets located in target area. Collection from each target is going independently and combining damping ring is going in longitudinal phase space [3], [4].

A debuncher is required if the lengthening of the bunch after conversion is not enough, so injected bunch can develop instability if it's length much shorter, than equilibrium. Remember that the bunch is short in linac; normally there is few stage buncher after the ring.

To restore the positron population after occasional lost, the electrons are used here. Electron linac having energy ~ 200 MeV serves for these purposes. High Voltage ceramic vacuum tube immersed into pressurized SF_6 serves as injector. So *the electrons* after acceleration in a linac (to 0.2 GeV as mentioned above, fraction of main linac can be appointed for this purpose) directed onto the same positron target, which serves for polarized positron production. For better accumulation thin positron target ($\sim 0.5X_0$) used for positron generation from gammas, can be replaced quickly to a more thick one suitable to 0.2 GeV electrons, what is $\sim 2X_0$.

In this primary operation *electrons* are generating positrons, which are collected by the same optics used in undulator production. After the necessary amount of positrons is accumulated (stacked) in the damping ring, the beam from the damping ring goes into main linac in a usual way. After few cycles, the polarized positron beam becomes restored.

The point of concern here is in stability of the scheme. If positron bunch, for some reason, fluctuated in intensity, then next round it will generate more/less positrons in a bunch, next round even more and so on. The bunch can acquire this variation in intensity in a damping ring as well, due to imperfection in injection, for example. So this will randomize the bunch population and might bring the losses as a sequence. At first look there is no way to make this scheme stable. That is why, the similar scheme, proposed in times of VLEPP [4], remains undeveloped until today.

We have mentioned that with appropriately designed feedback system, this scheme can be brought into stability. Let us consider some possible scenario for such a feedback system.

First, the positron conversion scheme for polarized positron production deals with selection of \sim half of the positrons created in a target. So there is a mechanism of energy selection, leaving the only energetic ones.

Even without polarization the secondary beam is going through some electro-optical elements naturally having controllable dispersion, see Fig. 1 at target area. Namely here it was suggested to make scrapping the particles with low energy, see [5] and references there. The additional

controllable selection of particles can be done with *fast kicker* by perturbation of dispersion at some point with low envelop function and scrapping particles at this point in accordance with the bunch population. Scrapping is made by adjustable collimator.

Let us consider one of such schemes.

SCHEME FOR PARTICLES SELECTION

Namely, let us scale the target area view in Fig.1 [5].

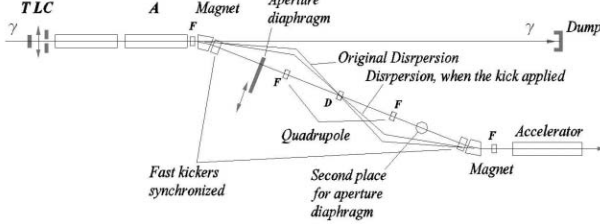


Figure 2: Achromatic bend with aperture diaphragm. T —is a target, L —is a short focusing lens, C —stands for collimator. F and D stand for focusing and defocusing lenses respectively. A stands for RF accelerator structure.

Achromatic bend arranged with the help of two bending magnets and two radially focusing quadrupoles located in between and marked F in Fig 2. This scheme was proposed in [6]. The same achromatic bends used in main beam transport to the undulator axis, as is seen in Fig.1.

Let us make some analytical estimation first. At the end of the magnet M the dispersion goes to be proportional to the bending radius and is rather simple function of angle

$$D \cong \rho \cdot (1 - \cos\varphi), \quad D'(s) = \sin\varphi, \quad \varphi = s / \rho, \quad (1)$$

where $\rho = (HR) / H_m$ stands for the bending radius, $(HR) = pc[eV] / 300 [G \cdot cm]$ is a magnetic rigidity, H_m magnetic field in a bending magnet, s is a path length along equilibrium trajectory. At the location of lens F , in the middle of it, the dispersion goes to be

$$D|_l \cong \rho \cdot (1 - \cos\varphi) + L \cdot \sin\varphi, \quad (2)$$

where L is a distance between the magnet and lens. Let $\varphi = \pi / 12$ (15°), $L = 300 \text{ cm}$, $\rho = 100 \text{ cm}$, then $\sin(\pi / 12) \cong 0.26$, $\cos(\pi / 12) \cong 0.96$ and $D|_l \cong 82 \text{ cm}$.

If the energy delivered by accelerator structure $E_{10} = 200 \text{ MeV}$, $E_{\gamma \text{ max}} \cong 20 \text{ MeV}$ and we collect half of this interval, i.e. $15 \pm 5 \text{ MeV}$, then the energy at the out of accelerating structure goes to be $E_l = 215 \pm 5 \text{ MeV}$ and full radial displacement at the lens location will be

$$\Delta r \cong D|_l \cdot \frac{\Delta E}{E} = 82 \cdot \frac{10}{215} \cong 3.8 \text{ cm} \approx (\pm 2 \text{ cm}) \quad (3)$$

For reduction of systematic energy spread introduced by RF roll-off, one can consider acceleration of positron bunch in first section A at one side of RF, and the last half of section at another side. Anyway as the cut in intensity done by scraper any way, linearity is not important, generally (see below).

Focal distance of the lens is $L = (HR) / (GI)$, and l stands for the length of the lens. Supposing that the length of the lens is $l = 10 \text{ cm}$, then gradient must be

$$G = \frac{(HR)}{L \cdot l} = \frac{600 \text{ kG} \cdot \text{cm}}{200 \text{ cm} \cdot 10 \text{ cm}} = 0.3 \text{ kGs/cm}. \quad (4)$$

Magnetic rigidity $(HR) = 600 \text{ kG} \cdot \text{cm}$ for $\sim 200 \text{ MeV}$ beam. So the lens is rather weak. Result of calculation of channel just described with computer program is represented in Fig. 3. One can see that this is absolutely symmetric channel with respect to the central lens.

Let the scraper to be located \sim at the middle between lens and the magnet, the radial displacement will be here as big as $\Delta r \cong \pm 1 \text{ cm}$. Within this aperture spread all particles will be located. Here, between two radially focusing lenses, the minimum of envelope function can be arranged. Typical value of envelop function in minimum comes to be $\sim 4 \text{ cm}$ or even less. With emittance of the beam $\sim \gamma \mathcal{E}_{x,y} \cong 2 \text{ cm} \cdot \text{rad}$, the transverse betatron size is going to be $x_\beta \cong y_\beta \cong \sqrt{\gamma \mathcal{E} \cdot \beta / \gamma} \cong \sqrt{2 \cdot 4 / 400} \cong 0.14 \text{ cm}$, while the beam size arising due to the energy spread according to (1) is $x_D \cong y_D \cong \pm 2 \text{ cm}$, so the energy resolution is high enough.

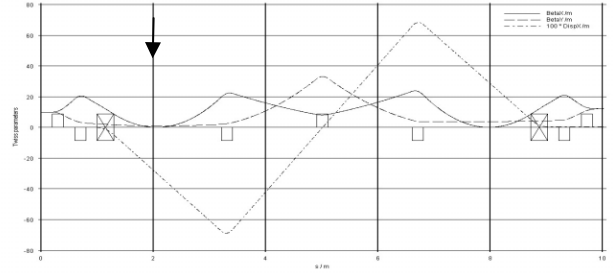


Figure 3: Example of more detailed design of channel. Envelope functions and dispersion are given in meters. Scraper location indicated by arrow. Radial beta-function in minimum is $\sim 4 \text{ cm}$.

So the aperture scraper in first place will cut all positrons with low energy. It also allows controllable change of energy pass interval by installation of two fast kickers, located at the edge of each of bending magnets, see Fig. 2.

KICKER AND AMPLIFIER

These fast kickers feed from a powerful amplifier. We would like to underline one more time, that this is namely powerful *amplifier*, not pulser. In its turn it gets the signal from pickup, located in the dumping ring. Signal from this pickup processed, so the zero level can be controlled in a way desired. Spacing between bunches $\sim 20 \text{ ns}$ allows easy resolution the individual bunch population. As we mentioned, the bunches after target are following with 300 ns spacing one after another, giving a lot of time for rise and down. The spacing in 300 nsec between bunches corresponds to the frequency $\sim 3.3 \text{ MHz}$ only.

Let us estimate the power required. If we suggest 10% of variation of dispersion at the scraper location and,

hence, 10% of $\Delta r \cong \pm 1\text{cm}$, then fast kicker must deliver $\sim 10\%$ of D' . This angle is $D' \times 0.1 = \text{Sin}(\pi/12) \times 0.1 \cong 0.026$, so the kicker field integral must be as big as $\int H dl_{\text{kicker}} \cong (HR) \cdot D' \times 0.1 \cong 15.6 \text{ kG}\cdot\text{cm}$. If we suggest, that the effective length of this kicker is $l_k \cong 10 \text{ cm}$, then the field in it goes to be $H = 1.56 \text{ kG}$. For aperture of this fast kicker $a = 4 \text{ cm}$, the feeding current will be $I \cong 5.20 \text{ kA}\cdot\text{turns}$ which comes to $\sim 520 \text{ A}$ for ten turn coil. If the impedance of the cable feeding kicker is $Z \sim 25 \Omega$, then the pulsed power running through it becomes as big as $P_{\text{peak}} = I^2 Z \cong 6.8 \text{ MW}$, with the voltage $V = I \times Z \cong 13 \text{ kV}$. Total length of conductor comes to $l \sim 3 \text{ m}$. So the pass-time corresponding to this length does to be $\tau \cong l/c \cong 10 \text{ nsec}$. Thus, the pulse duration is $\sim 17 \text{ ns}$, bringing the maximal average power $P \cong 880 \text{ W}$. Inductance L of the kicker's coil can be found from the following equation (in MKSA units)

$$LI^2 \cong \mu_0 H^2 l_k a b, \quad (6)$$

where b stands for the width of aperture, $\mu_0 = 4\pi 10^{-7} \text{ H/m}$ is magnetic permeability of vacuum. For parameters under discussion, $n=10$, $a=0.04 \text{ m}$, $b=0.1 \text{ m}$, $l_k=0.1 \text{ m}$ one can obtain from (7) $L \cong 30 \mu\text{H}$. The cables even with lower impedance can be used here. This impedance defined by the kicker design.

Fast kickers having rise time $\sim 2 \text{ ns}$ described in [7], [8]. One of these has ferrite core, but another has laminated iron core. Here in [9] it was shown, that magnetic field in c-shape magnets comes to equilibrium extremely fast, practically with nsec level. That was explained by specific mechanism of magnetic field establishment.

Mostly adequate solution for the controllable power supply is in usage of tetrodes designed for SW transmitters. Tetrode(s) enveloped into appropriate holders. So basically we are talking about the last (end) cascade of RF transmitter. One possible scheme for such amplifier is represented in Fig. 4.

Solid state pre-amplifiers for these vacuum tubes are available on the market and are in use for fast feedback in damping/storage rings. Even for these solid-state pre-amplifiers typical average power is 2 kW . Thus, the scheme can be realized without doubts.

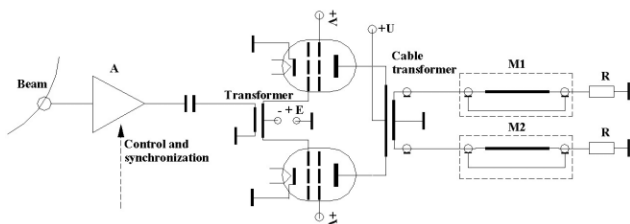


Figure 4: Tetrode amplifier. $M1$ and $M2$ stands for the kickers. A – controlled pre-amplifier. Voltages E , V , U applied for proper operation of tubes. $M1$, $M2$ stand for the kicker magnets, R stand for the loads.

We considered the simplest scheme of this kind. More complicated schemes can be made so that RF buckets having carrier frequency $\sim 3 \text{ MHz}$ applied to the kickers during the bunch train duration, but with amplitude modulation in accordance with bunch population. The best point of application of such amplitude modulation is modulation of displacement grid voltage E in Fig.4. So in this case we are talking basically about amplitude modulation of carrier signal with 3.3 MHz and having duration about 1 msec and repetition rate 5 Hz . So this regime is pretty easy for amplifier. Phase modulations (numerous types) can be used here as well too.

We considered the scheme in bending channel. This principle can be realized with fast kickers installed in other parts of transport channel as well

CONCLUSION

So coming to a conclusion, the scheme in Fig.1 can be technically realized and delivers flexibility, economy and ability to work for electron and positron part of collider independently. The scheme allows equalizing the bunch population also.

A detailed design of fast kicker will be done in separate publication. There is no apparent limitation in construction of such fast kicker however.

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