

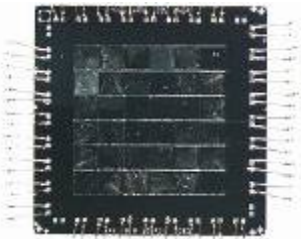
# Readout Electronics

the path of the signal  
from detection to acquisition



# Detector(s)

A large variety of detectors  
But similar modeling



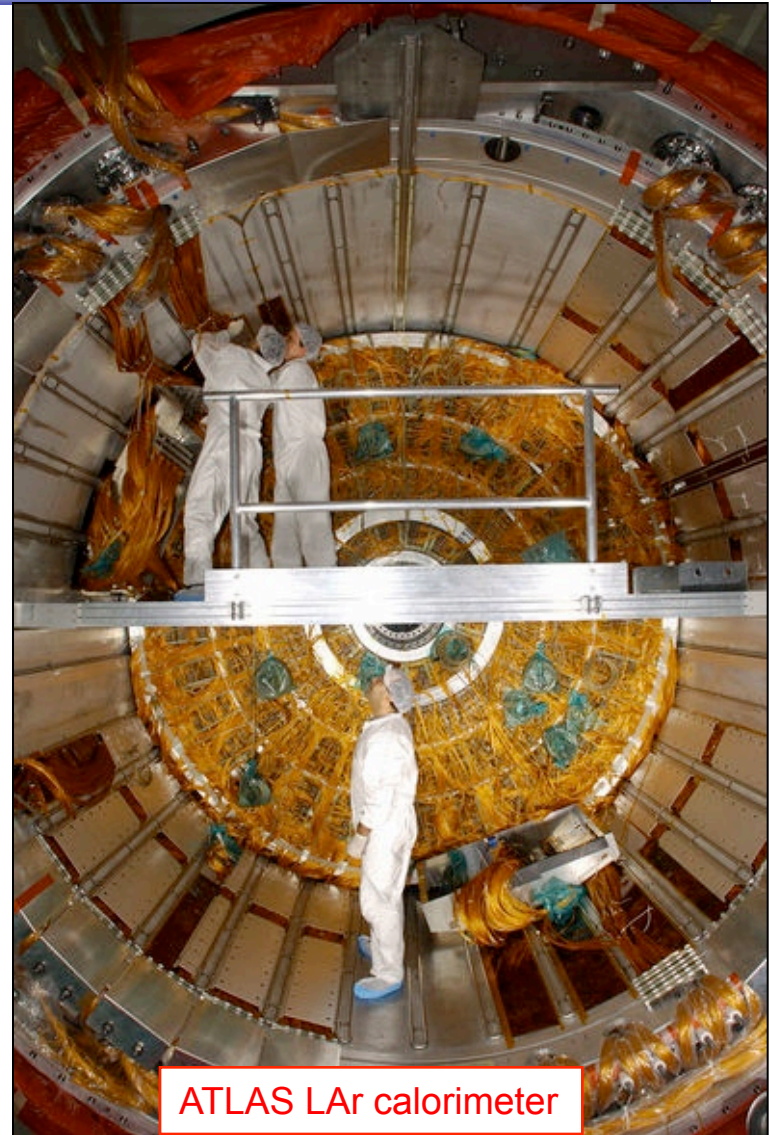
6x6 pixels, 4x4 mm<sup>2</sup>  
HgTe absorbers, 65 mK  
12 eV @ 6 keV



PMT in ANTARES



CMS pixel module



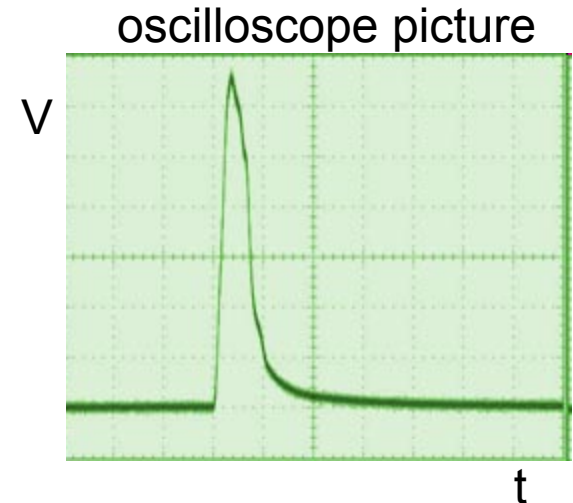
ATLAS LAr calorimeter

# Detector Signal

- Detector signal generally a short current pulse:

$$i = V/R \quad (R = 50\Omega, \text{ oscilloscope termination})$$

- thin silicon detector (10 –300  $\mu\text{m}$ ): 100 ps–30 ns
- thick ( $\sim\text{cm}$ ) Si or Ge detector: 1 –10  $\mu\text{s}$
- proportional chamber: 10 ns –10  $\mu\text{s}$
- Microstrip Gas Chamber: 10 –50 ns
- Scintillator+ PMT/APD: 100 ps–10  $\mu\text{s}$



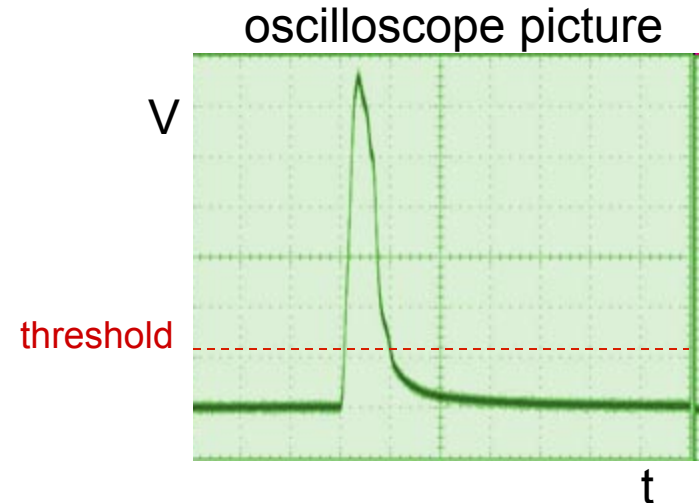
$$E \propto Q_s = \int i_s(t) dt$$

# Signal measurements

Various measurements of this signal are possible  
Depending on information required:

- Signal above threshold  
digital response / event count
- Integral of current = charge  
→ energy deposited
- Time of leading edge  
→ time of arrival (ToA) or time of flight (ToF)
- Time of signal above threshold  
→ energy deposited by TOT

and many more ...





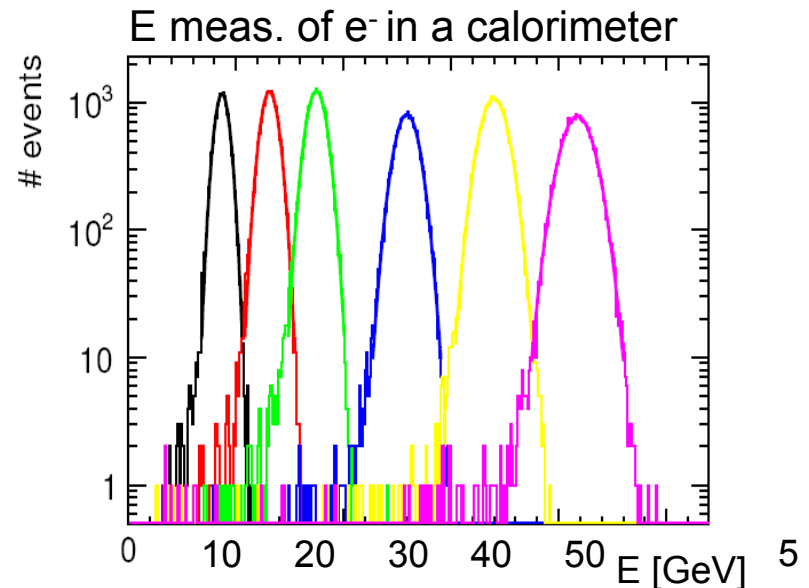
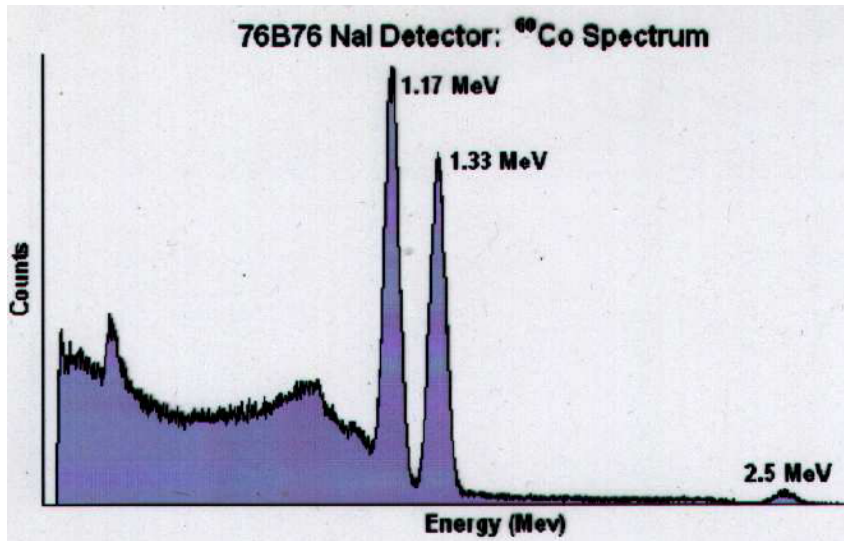
# Energy measurement

Determine energy deposited in a detector

- Necessary to integrate detector signal current:
  - integrate charge on input capacitance
  - use integrating (“charge sensitive”) preamplifier
  - amplify current pulse and use integrating ADC (analog to digital converter)

$$E \propto Q_s = \int i_s(t) dt$$

Examples:



# Electronics requirements for E meas.

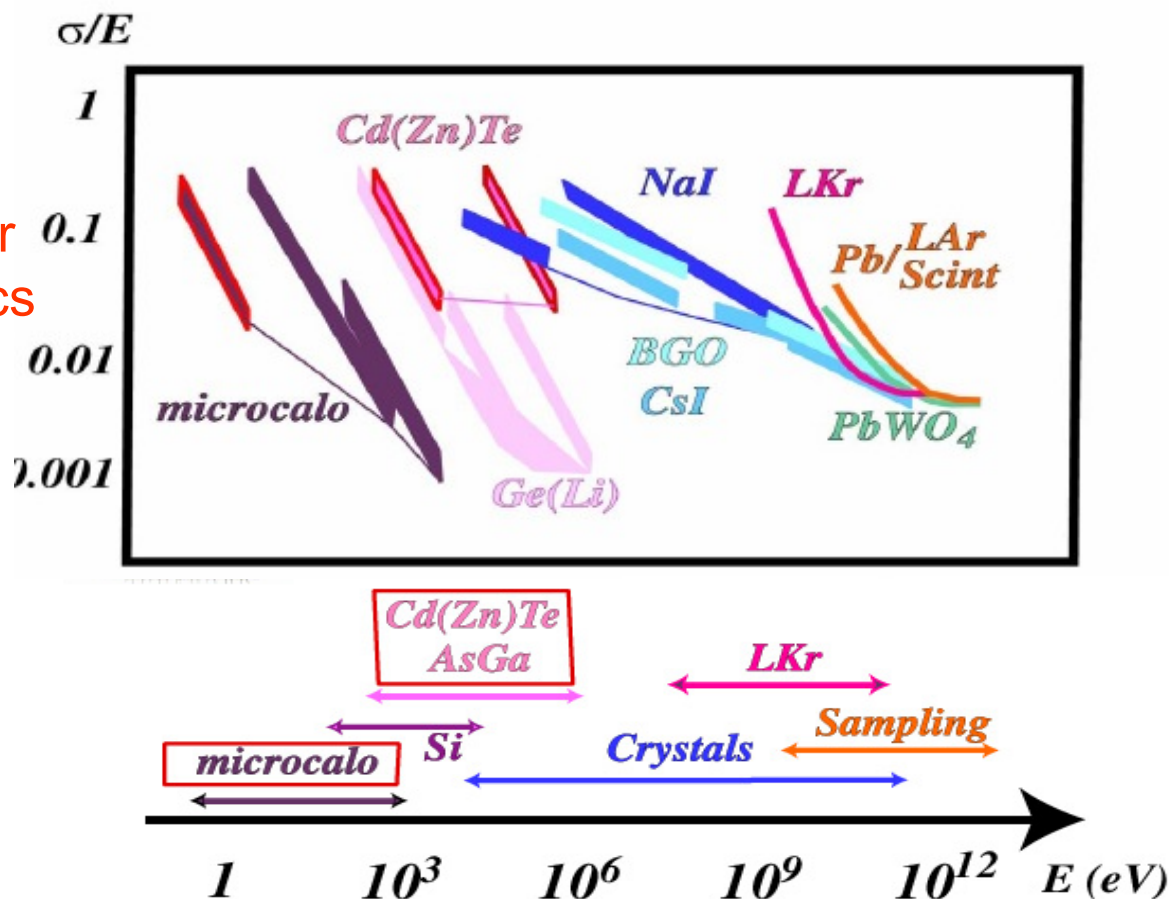
Dynamic range:

maximum signal/minimum signal (or noise) typically:  $10^3$ – $10^5$

often specified in dB  $(=20\log V_{\max}/V_{\min}) = 60 - 100$  dB

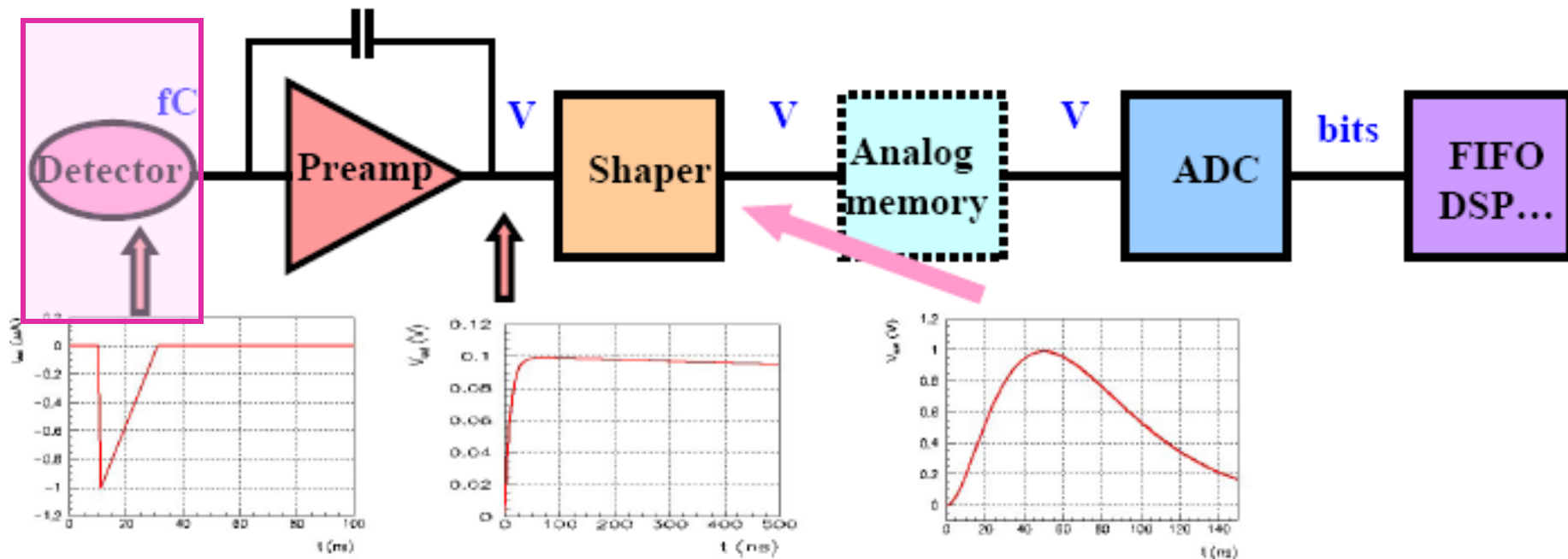
also in bits:  $2^n = V_{\max}/V_{\min} = 10 - 18$  bits

The large dynamic range is a **key parameter** for calorimeter electronics



# Readout architecture for E meas.

Most front-ends follow a similar architecture



- Very small signals (fC) -> need **amplification**
- Measurement of **amplitude** (ADCs)
- Thousands to millions of channels

# Detector modeling (approximation)

Detector = capacitance  $C_d$

- Pixels : 0.1-10 pF
- PMs : 3-30 pF
- Ionization chambers: 10-1000 pF
- Sometimes effect of transmission line

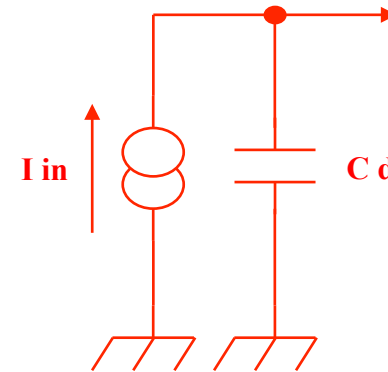
Signal : current source

- Pixels :  $\sim 100 \text{ e}^-/\mu\text{m}$
- PMs : 1 photoelectron  $\rightarrow 10^5\text{-}10^7 \text{ e}^-$
- Modeled as an impulse (Dirac) :

$$i(t) = Q_0 \delta(t)$$

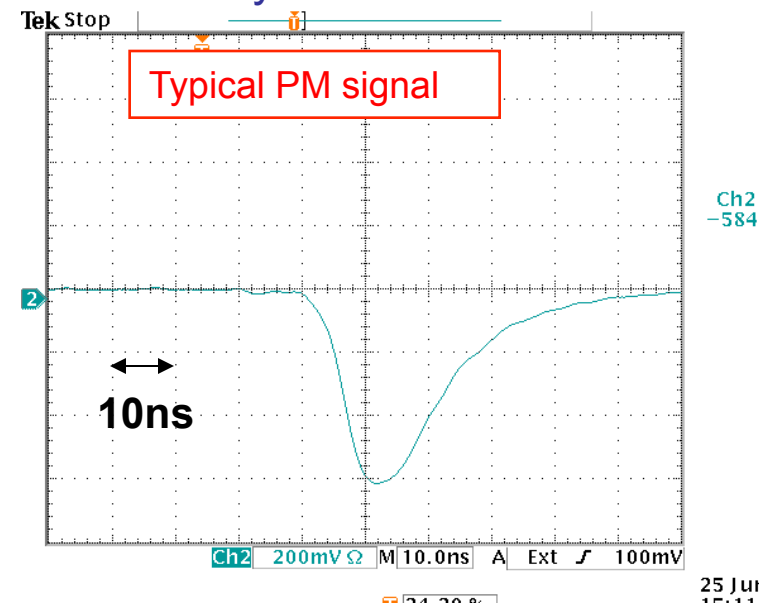
Missing :

- High Voltage, bias
- Connections, grounding
- Neighbors
- Calibration...



Detector model

Reality is different





# Ionization chamber signal shape

derive signal for single ionizing particle [ $R = \infty$ ]

$$U = U_0 + \Delta U$$

$$\begin{aligned}\Delta U &= -\frac{N_+ q_+}{C d} (d - z_0) + \frac{N_- q_-}{C d} (0 - z_0) = \Delta U_- + \Delta U_+ \\ &= -\frac{N}{C d} [e(d - z_0) - e(0 - z_0)] = -\frac{N e}{C}\end{aligned}$$

Final signal independent of ionization position and of detector dimension ...  
[see also Geiger counter]

Time evolution of pulse height:

$$z(t) = v_D \cdot t$$

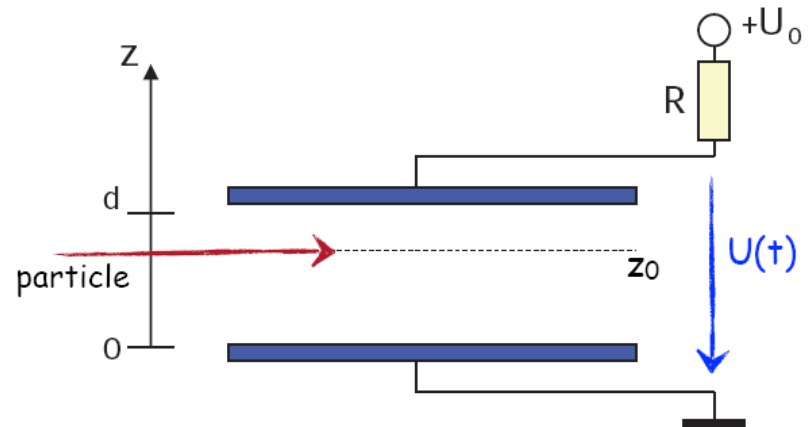
$$\Delta U = -\frac{N e}{C d} (v_D^e + v_D^{\text{ion}}) t$$

with:  
 $v_D^e \approx 1000 \cdot v_D^{\text{ion}}$

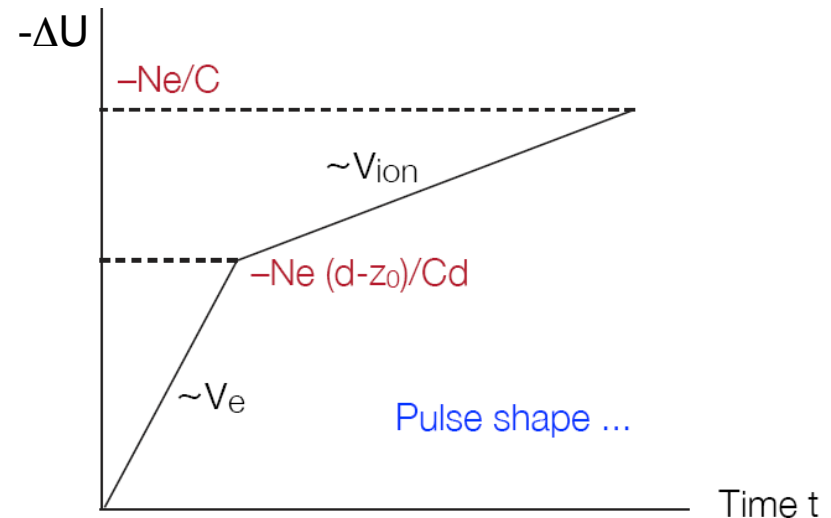
Typical:

$$v_{D,e} = 4 \text{ cm}/\mu\text{s}$$

$$v_{D,\text{ion}} = 4 \text{ cm}/\text{ms}$$



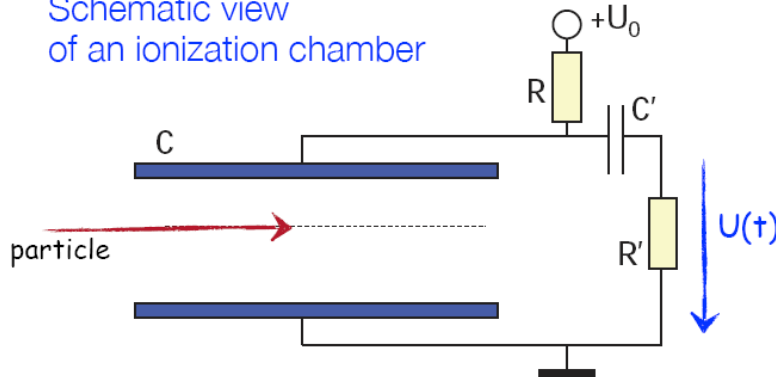
Schematic view of an ionization chamber



Pulse shape ...

# Ionization chamber signal shape

Schematic view  
of an ionization chamber



Pulse mode operation  
[Use RC circuit; R finite]

Response time of chamber:  $\tau = RC$

Must be sufficiently large with respect to  $t_{\text{signal}}$

Example:  $2 \times 2 \times 10 \text{ cm}^3$  chamber

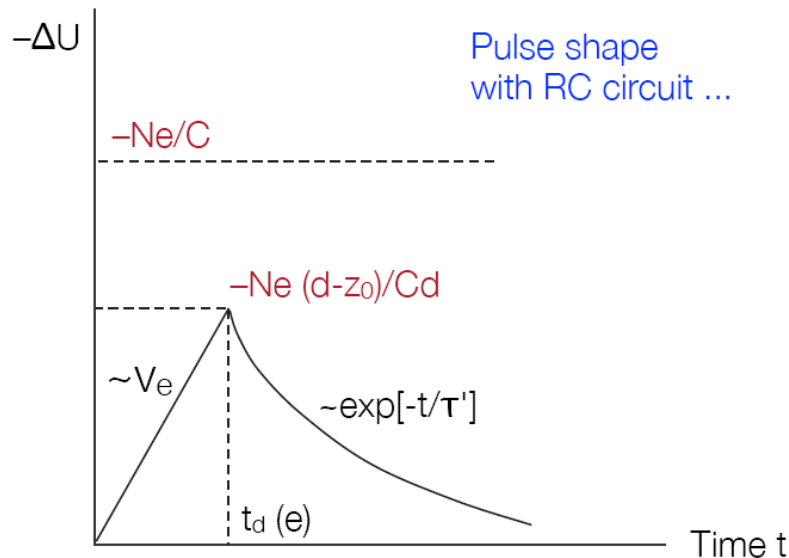
Electron drift time:  $t_{\text{max}}^- = d/v_{d,e} = 2\text{cm}/4\text{cm}/\mu\text{s} = 500 \text{ ns}$

Ion drift time:  $t_{\text{max}}^+ = d/v_{d,\text{ion}} = 500 \mu\text{s}$

Suppress ion signal by  $C'R'$  high pass filter  
with time constant  $\tau' = R'C'$

Chose:  $t_{\text{max}}^- < \tau' < t_{\text{max}}^+$

Ex.:  $\tau' = 1 \mu\text{s}$   
 $C = 1 \text{ pF}, R = 10 \text{ M}\Omega$   
 $C' = 1 \text{ pF}, C_{\text{tot}} = CC'/(C+C') = 0.5 \text{ pF}$   
 $R' = \tau'/C = 1 \mu\text{s}/0.5 \text{ pF} = 2 \text{ M}\Omega$



Features:

linear rise; exponential fall

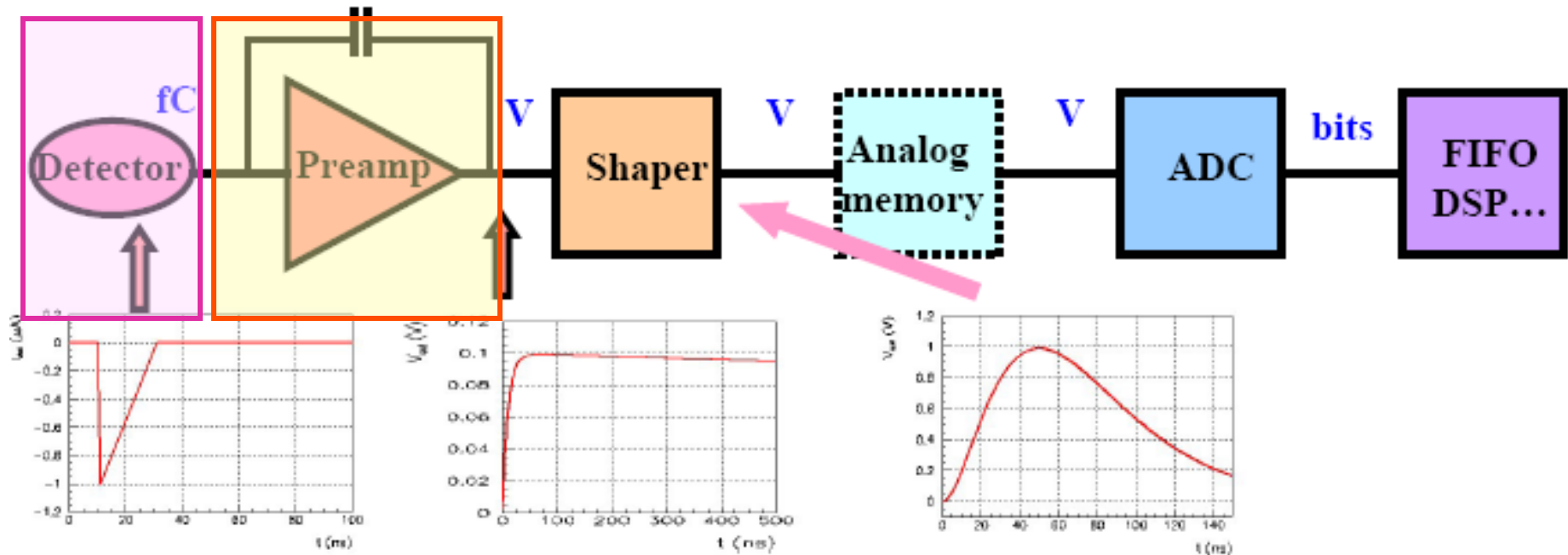
dead time  $T_{\text{dead}} \approx \tau'$

position dependent pulse height

position dependent resolution

# Readout architecture for E meas.

Most front-ends follow a similar architecture

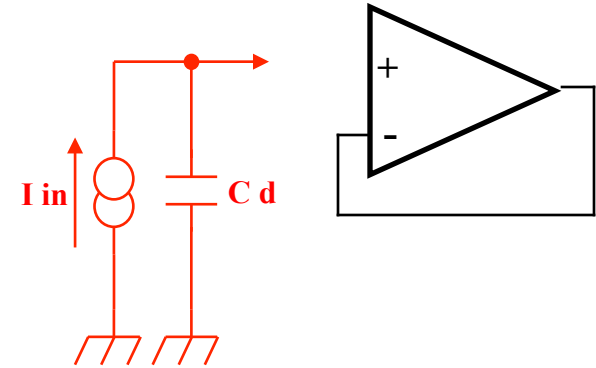


- Very small signals (fC) -> need **amplification**
- Measurement of **amplitude** (ADCs)
- Thousands to millions of channels

# Reading the signal

## Signal

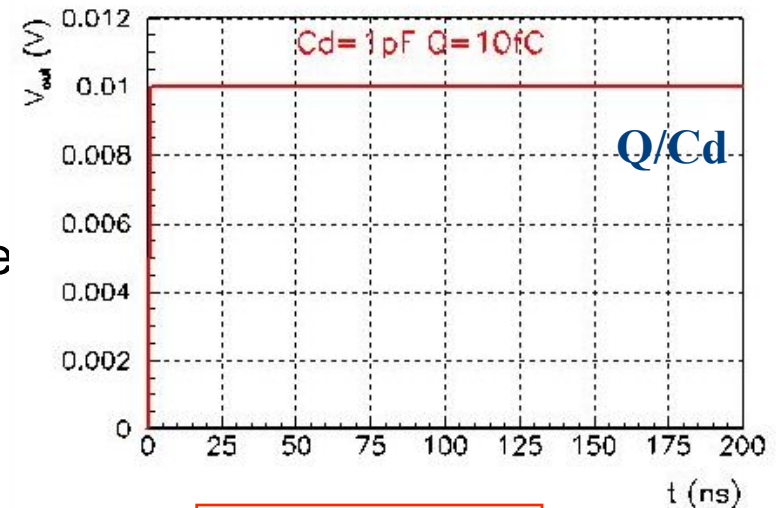
- Signal = current source
- Detector = capacitance  $C_d$
- Quantity to measure
  - Charge  $\rightarrow$  integrator needed
  - Time  $\rightarrow$  discriminator + TDC



Voltage readout

## Integrating on $C_d$

- Simple :  $V = Q/C_d$
- « Gain » :  $1/C_d$  : 1 pF  $\rightarrow$  1 mV/fC
- Need a follower to buffer the voltage  $\rightarrow$  parasitic capacitance
- Gain loss, possible non-linearity
- crosstalk
- Need to empty  $C_d$ ...



Impulse response

# Reading the signal (II)

If the input time constant of the amplifier,  $\tau = C_i R_i$  is large compared to the duration of the current pulse of the detector,  $t_c$  the current pulse will be integrated on the capacitance  $C_i$ .

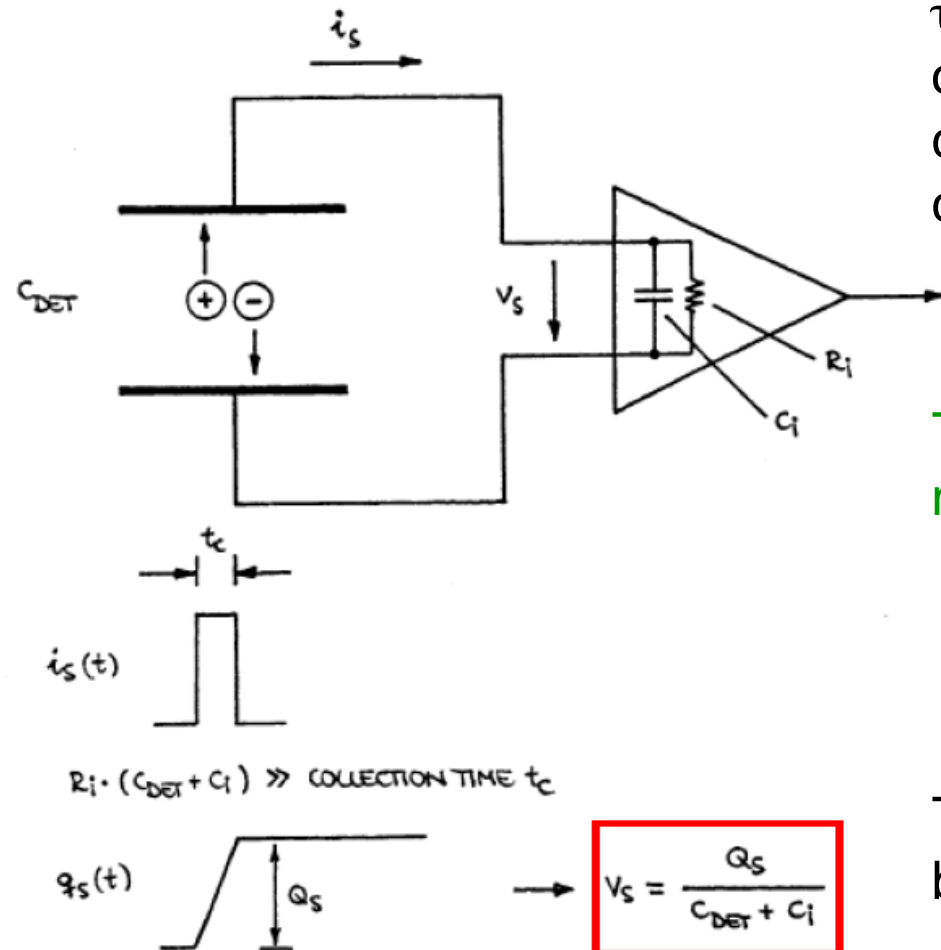
The resulting voltage at  $C_i$  and  $R_i$  is  

$$v_i = v_s = Q_s / (C_{\text{det}} + C_i)$$

The fraction of the signal charge measured is:

$$\frac{Q_i}{Q_s} = \frac{C_i v_i}{v_i (C_i + C_{\text{det}})} = \boxed{\frac{1}{1 + C_{\text{det}} / C_i}}$$

The dynamic input capacitance  $C_i$  should be  $\gg C_{\text{det}}$  to get a good ratio close to 1

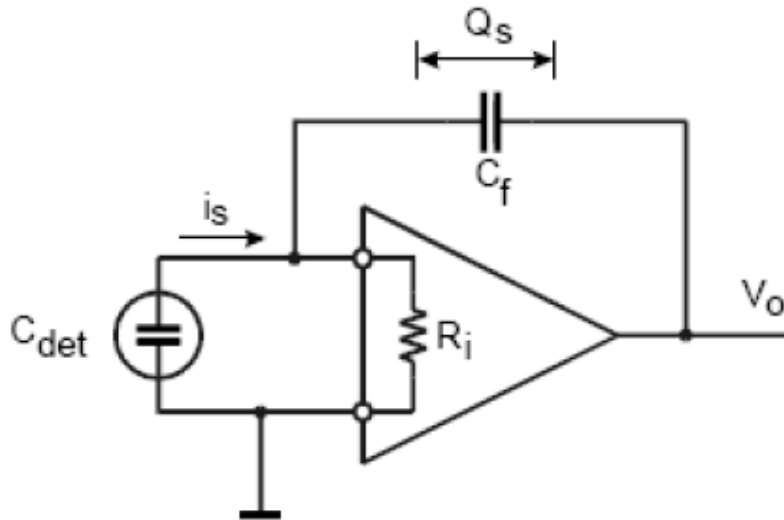


Depends on the detector capacitance



# Charge sensitive amplifier

Add feedback capacitor  $C_f$ :



Voltage gain  $dV_o/dV_i = -A \rightarrow v_o = -Av_i$   
 Input impedance =  $\infty$  (no signal current flows into amplifier input)

Voltage diff. across  $C_f$ :  $v_f = (A+1)v_i$   
 $\rightarrow$  Charge deposited on  $C_f$ :  $Q_f = C_f v_f$   
 $Q_i = Q_f$  (since  $Z_i = \infty$ )  
 $\rightarrow$  Effective input capacitance

$$C_i = Q_i/v_i = C_f(A+1)$$

*“dynamic input capacitance”*

Amplifier gain:

$$A_Q = \frac{dV_o}{dQ_i} = \frac{A \cdot v_i}{C_i \cdot v_i} = \frac{A}{C_i} = \frac{A}{A+1} \frac{1}{C_f} \approx \frac{1}{C_f} \quad (A \gg 1)$$

# Charge sensitive amplifier (II)

So finally the fraction of charge signal measured by the amplifier is:

$$\frac{Q_i}{Q_s} = \frac{C_i v_i}{v_i (C_i + C_{\text{det}})} = \frac{1}{1 + C_{\text{det}} / C_i} \quad C_f \approx \frac{A}{C_i} \quad (A \gg 1)$$

Example:

$$A = 10^3$$

$$C_f = 1 \text{ pF}$$



$$C_i = 1 \text{ nF}$$

$$C_{\text{det}} = 10 \text{ pF}$$



$$Q_i/Q_s = 0.99 \quad (C_i \gg C_{\text{det}})$$

$$C_{\text{det}} = 500 \text{ pF}$$

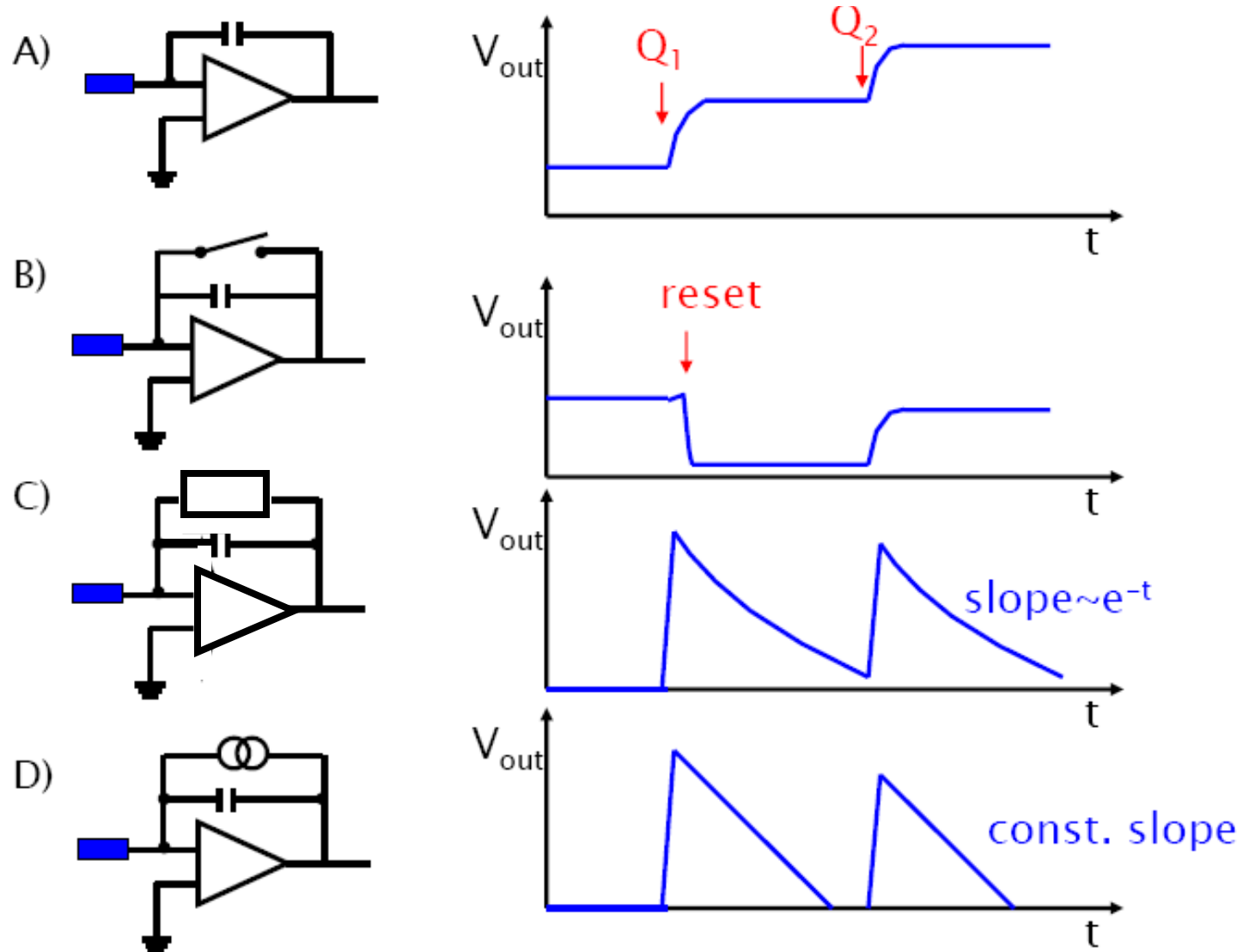


$$Q_i/Q_s = 0.67 \quad (C_i \sim C_{\text{det}})$$



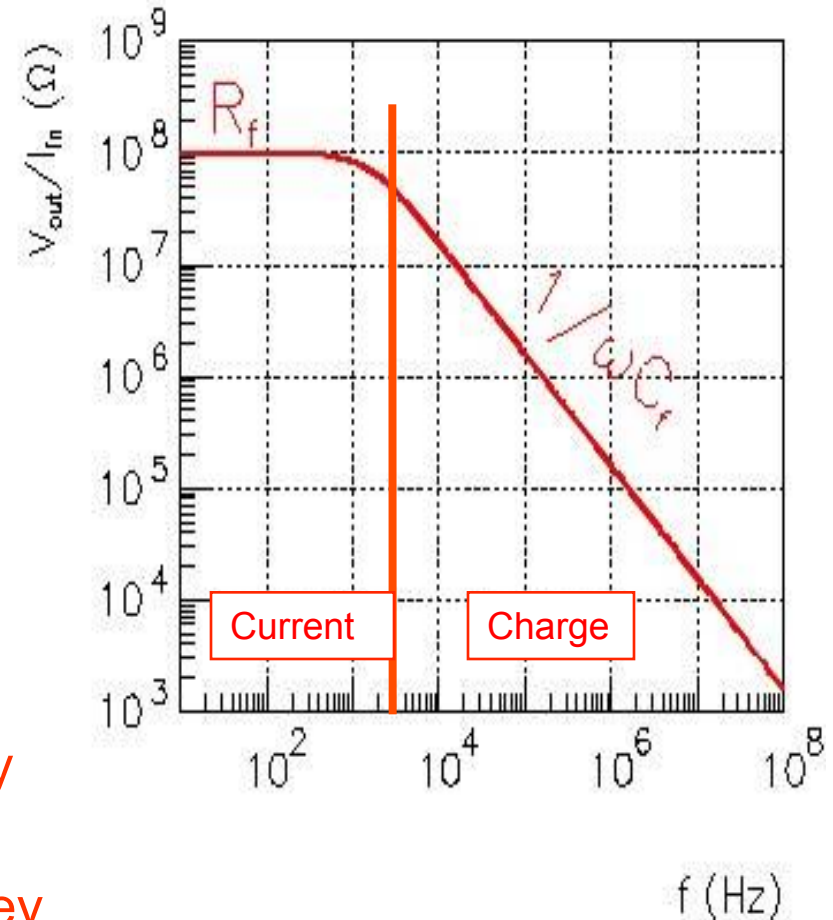
Si det: 50um thick, 500mm<sup>2</sup> area

# Charge sensitive (pre)-amplifier



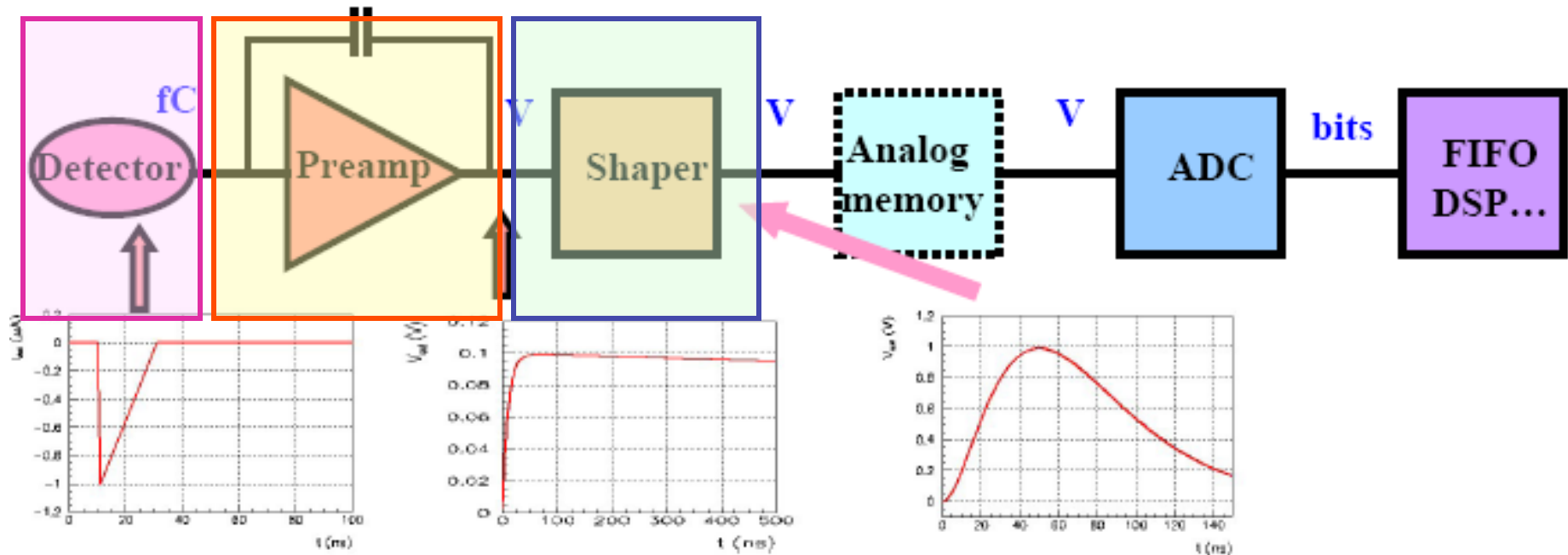
# Charge vs Current preamps

- Charge preamps
  - Best noise performance
  - Best with short signals
  - Best with small capacitance
- Current preamps
  - Best for long signals
  - Best for high counting rate
  - Significant parallel noise
- Charge preamps are not slow, they are long
- Current preamps are not faster, they are shorter (but easily unstable)



# Readout architecture for E meas.

Most front-ends follow a similar architecture



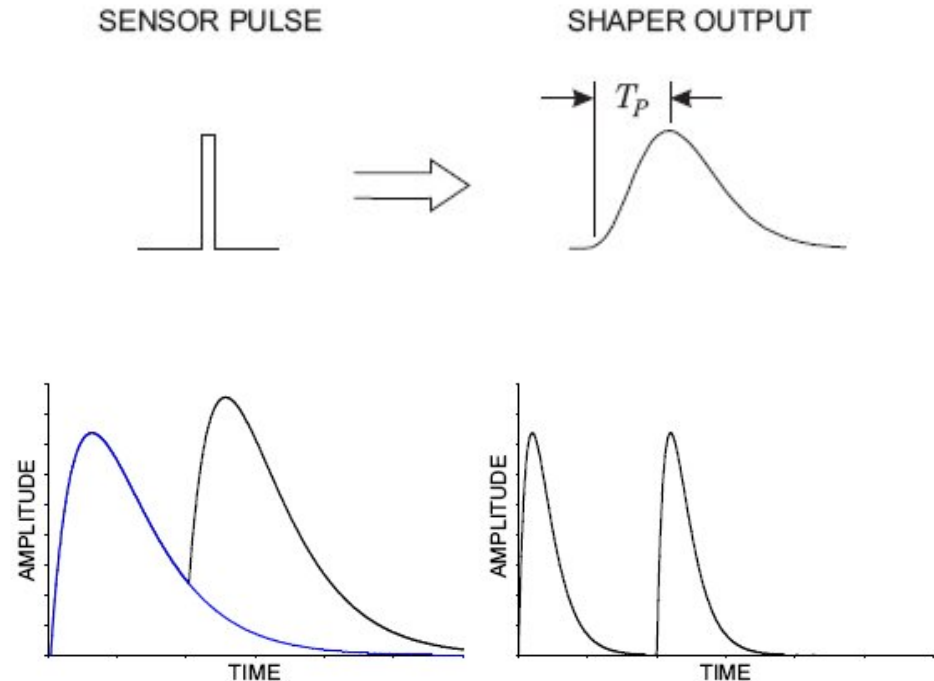
- Very small signals (fC) -> need **amplification**
- Measurement of **amplitude** (ADCs)
- Thousands to millions of channels



# Pulse shaping

Two conflicting objectives:

- 1) Limit the bandwidth to match the measurement time.  
→ too large bandwidth increases the noise
- 2) Contain the pulse width so that successive signal pulses can be measured without overlap (pile-up)  
→ Short pulse duration increases the allowed signal rate but also noise

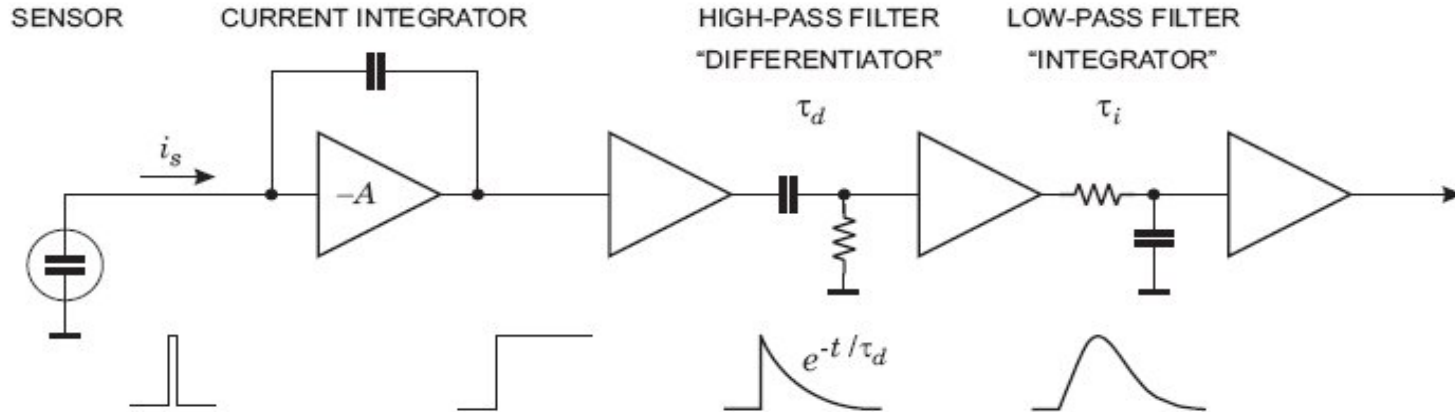


# CR-RC shaper

Example of a simple shaper: CR-RC

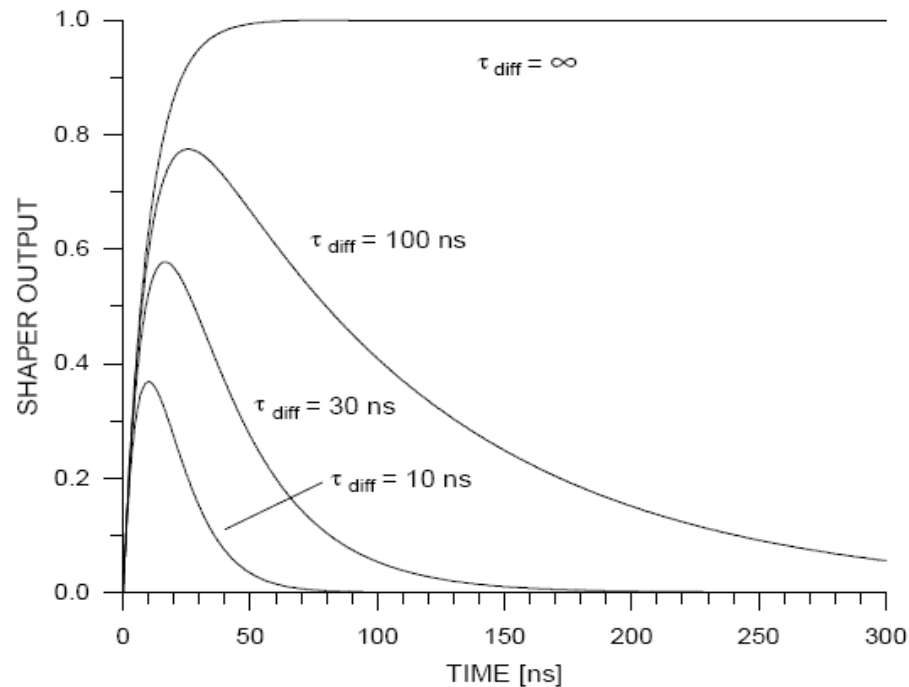
- the **high-pass filter** sets the duration of the pulse to have a decay time  $\tau_d$
- the **low-pass filter** increases the rise time to limit the noise bandwidth

**key design parameter: peaking time** → it dominates the noise bandwidth



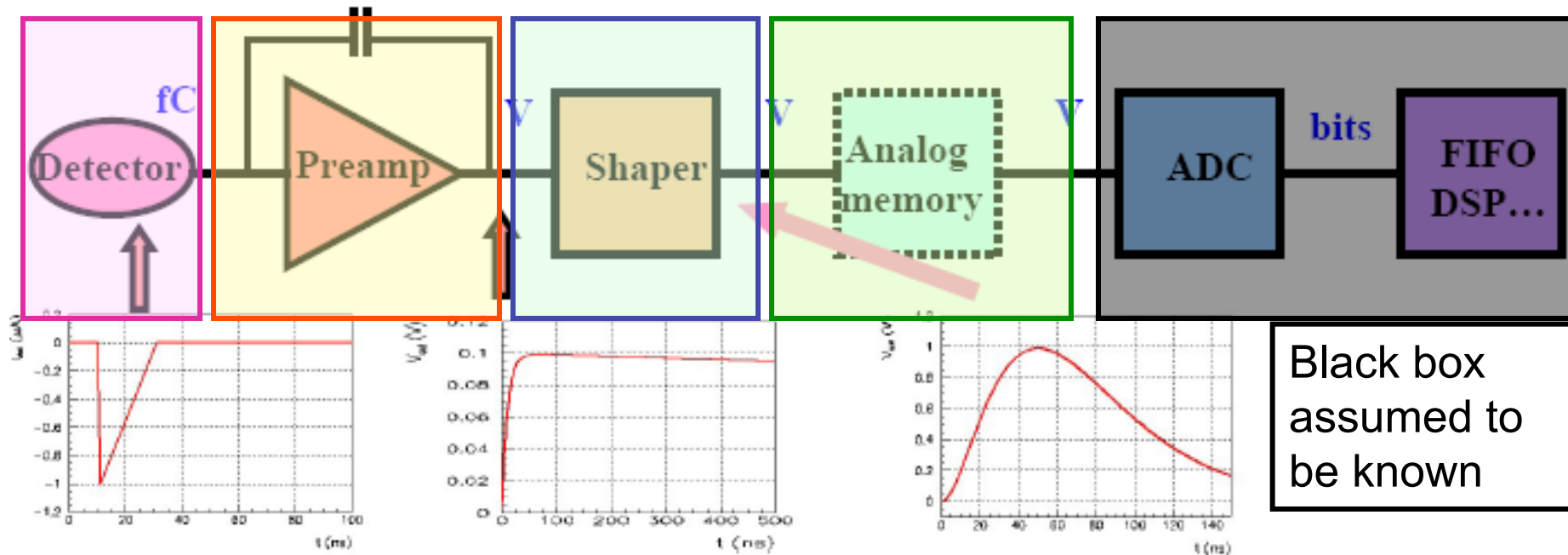
# CR-RC shaper (II)

Effect of a CR-RC shaper with  
fix integrator time constant = 10ns  
and variable differentiator time constant



# readout architecture for E meas.

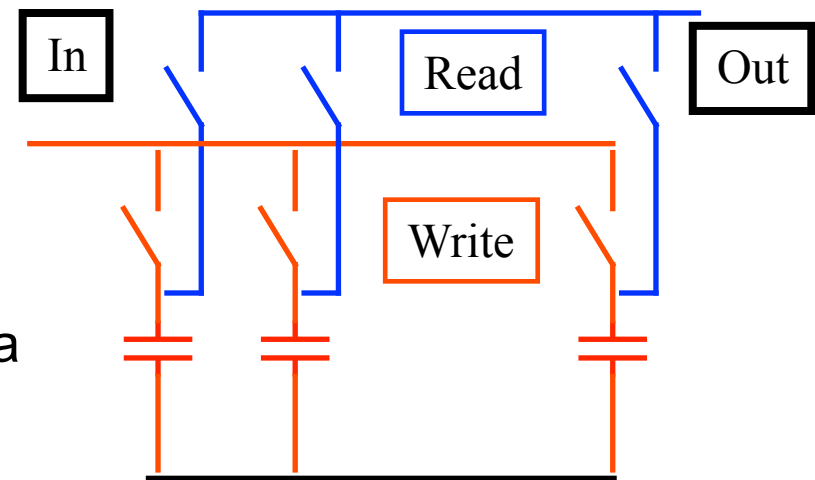
Most front-ends follow a similar architecture



- Very small signals (fC) -> need amplification
- Measurement of amplitude (ADC)
- Thousands to millions of channels

# Analog memories

- Switched Capacitor Arrays (SCAs)
  - Store signal on capacitors ( $\sim \text{pF}$ )
  - Fast write ( $\sim \text{GHz}$ )
  - Slower read ( $\sim 10\text{MHz}$ )
  - Dynamic range : 10-13 bits
  - depth : 100-2000 capacitors
  - Insensitive to absolute value of capa (voltage write, voltage read)
  - Low power
  - Possible loss in signal integrity (droop, leakage current)
- The base of 90% of digital oscilloscopes !

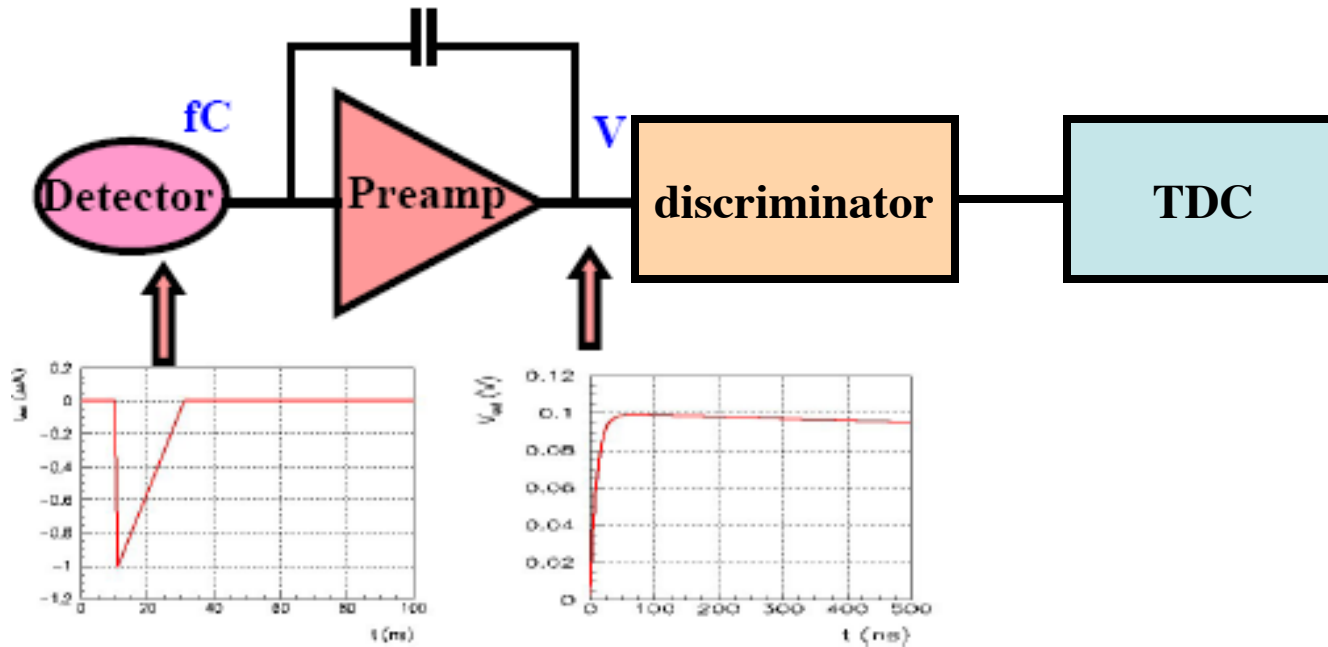


Principle of a « voltage-write, voltage-read » analog memory



# Readout architecture for t meas.

Most front-ends follow a similar architecture

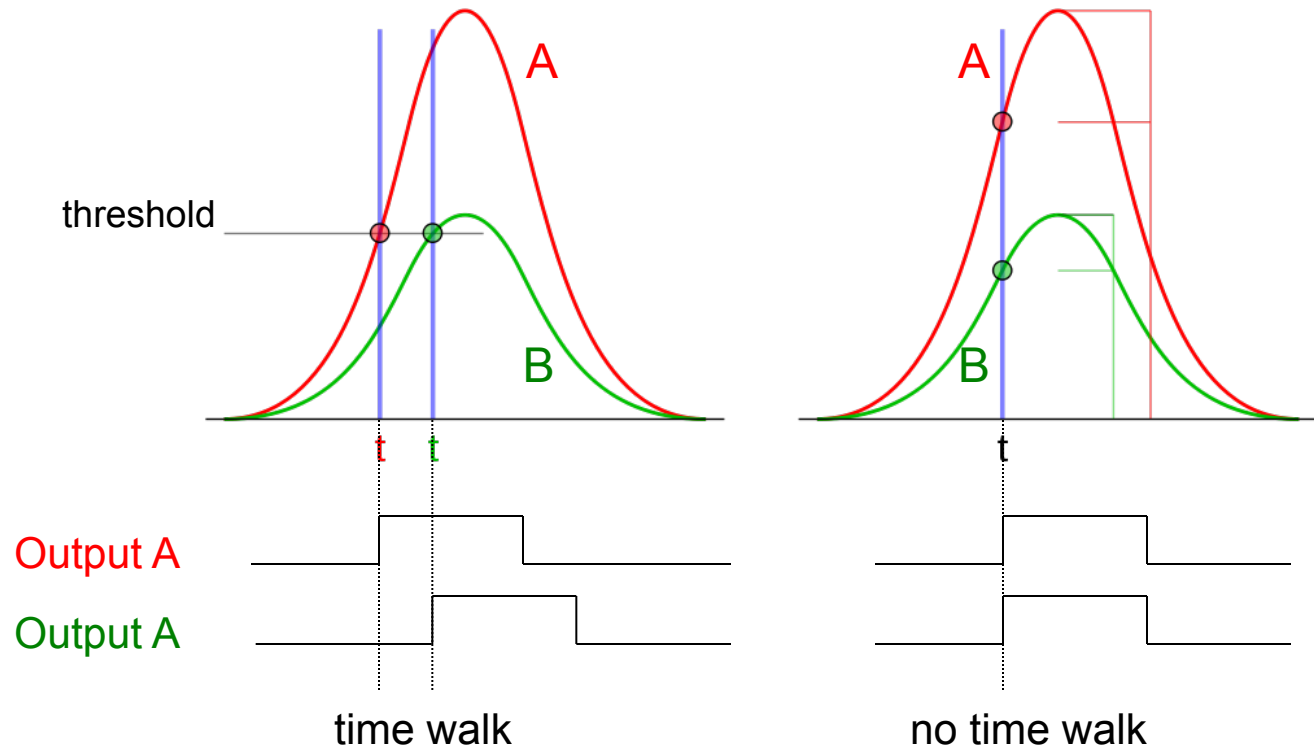


- Very small signals (fC) -> need amplification
- Measurement time (discriminator, TDCs)
- Thousands to millions of channels

# Discriminator

**Working principle:** compare voltage level of signal with fixed voltage level (threshold)  
if the signal level exceeds the threshold a standard logic signal is generated

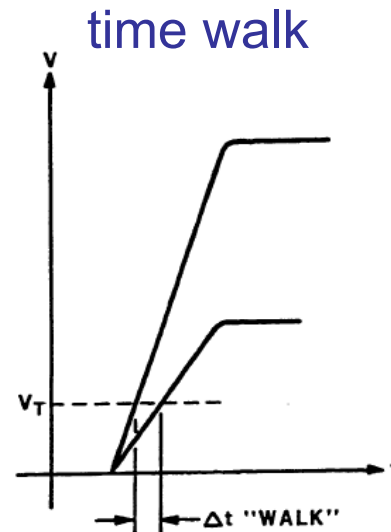
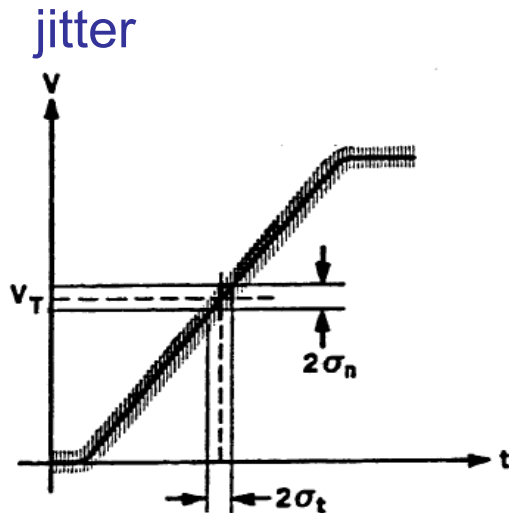
**Discriminator techniques:** leading edge triggering and constant fraction triggering



# Time measurements

Time measurements are characterized by their **slope-to-noise ratio**

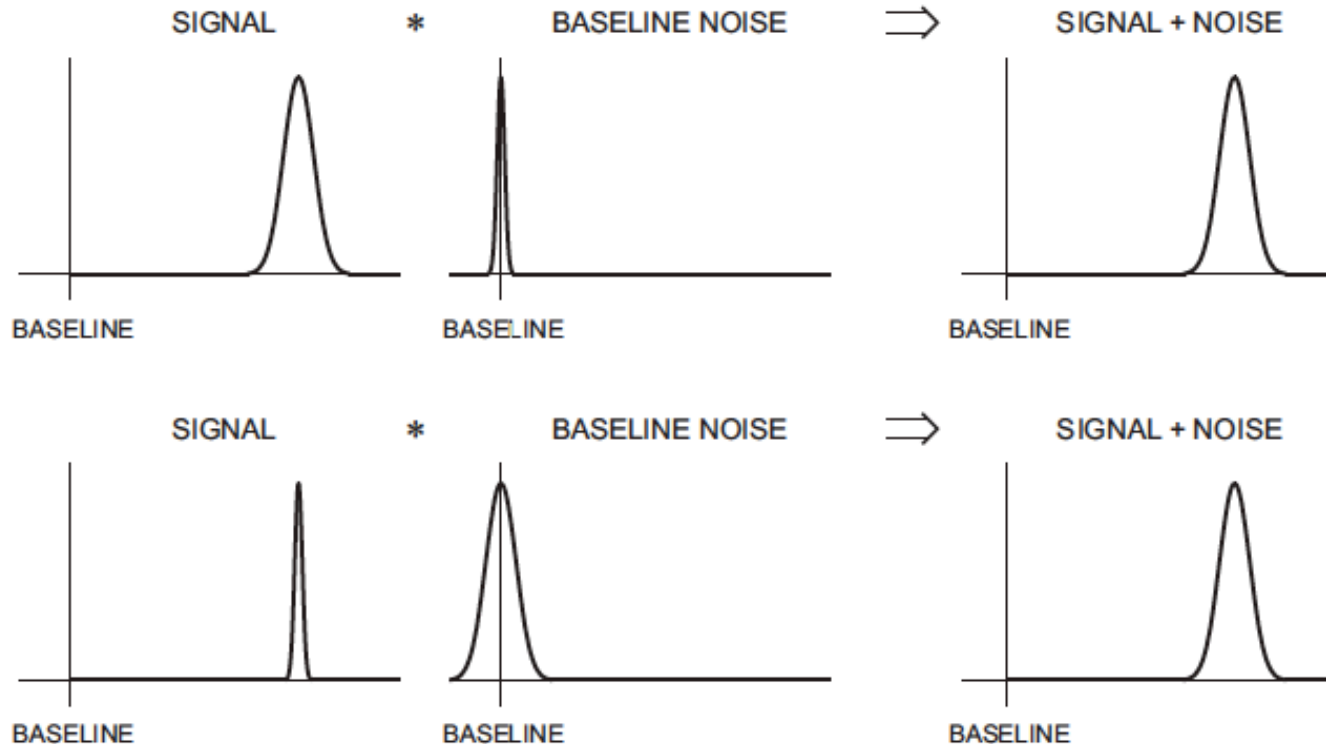
Two main effects contribute to the deterioration of a time measurement  
i.e. time of threshold crossing fluctuates due to:



Often driven by the time constant of the shaper which determines rise time & amplifier bandwidth

# From theory to reality

Every signal comes together with noise ...



Noise is a quite complex topic (see backup), we do not have time to discuss it. But always remember:

➔ what matters in a detector is S/N

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## Examples of readout electronics



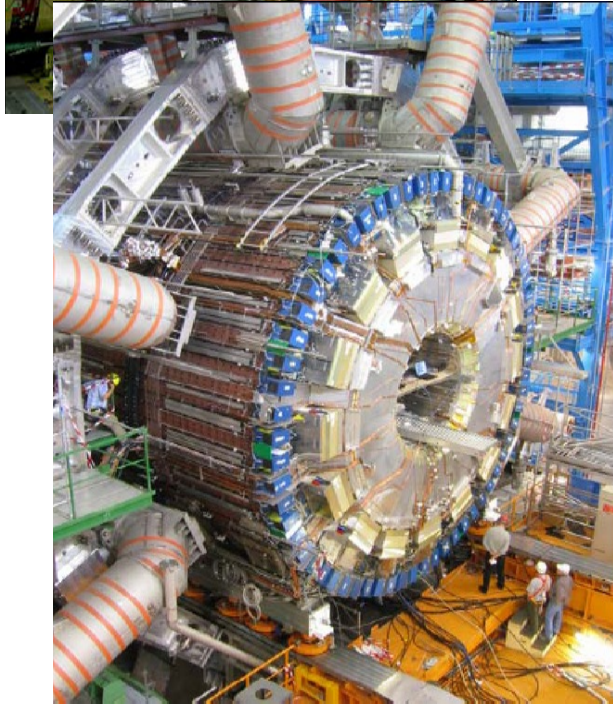
# Ionization calorimeters



Examples:  
DØ(LAr)  
NA48 (LKr)  
ATLAS (LAr)  
H1



Stable, Linear  
Easy to calibrate (!)  
Moderate resolution



# ATLAS LAr: Front End boards

**Amplify, shape, store and digitize Lar signals** 

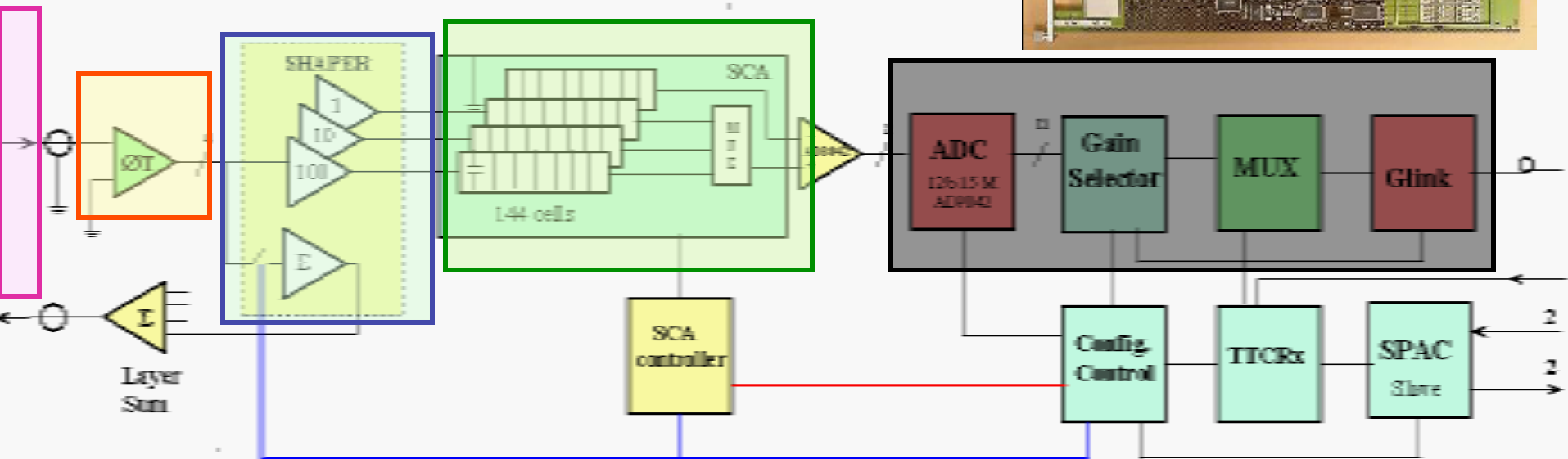
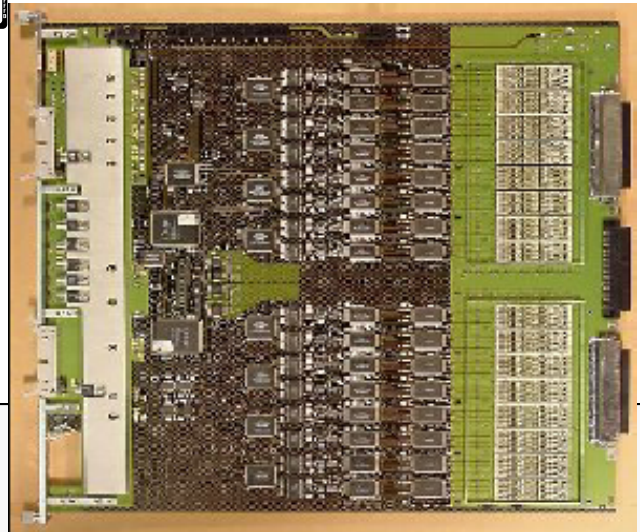
128 warm preamps

128 tri-gain shapers

128 quad pipelines

32 ADCs (12bits 5 MHz)

1 optical output (Glink)



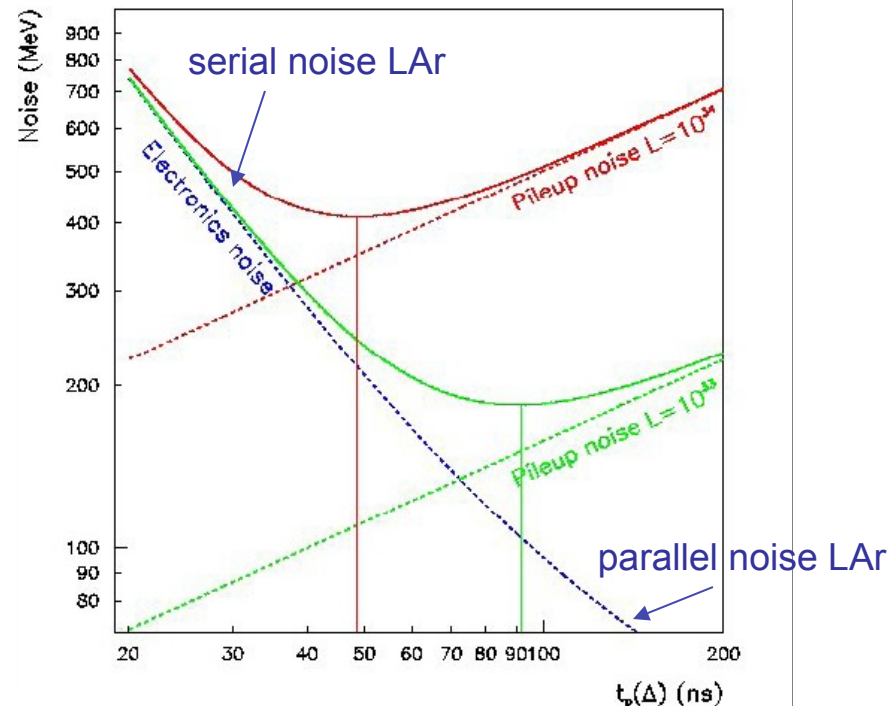
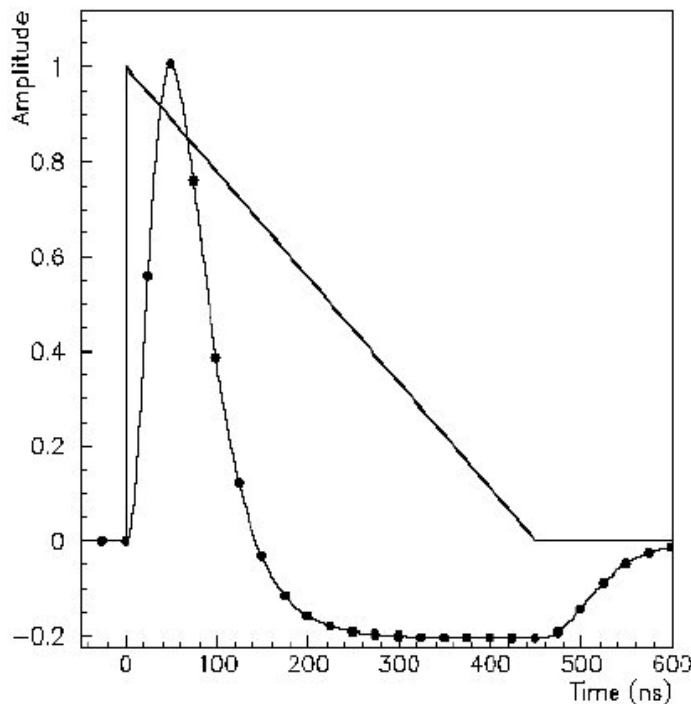
# ATLAS : LAr shaper

**Goal : optimize signal to noise ratio between electronics noise and pileup noise**

Ionization signal  $\sim 500\text{ns} = 20$  LHC bunch Xings

Reduced to 5 bunch Xings with fast shaper  $\rightarrow$  worse S/N due to loss of charge

Choice of peak time varies with luminosity  $\rightarrow 45\text{ns}$  at  $L=10^{34}\text{cm}^{-2}\text{s}^{-1}$

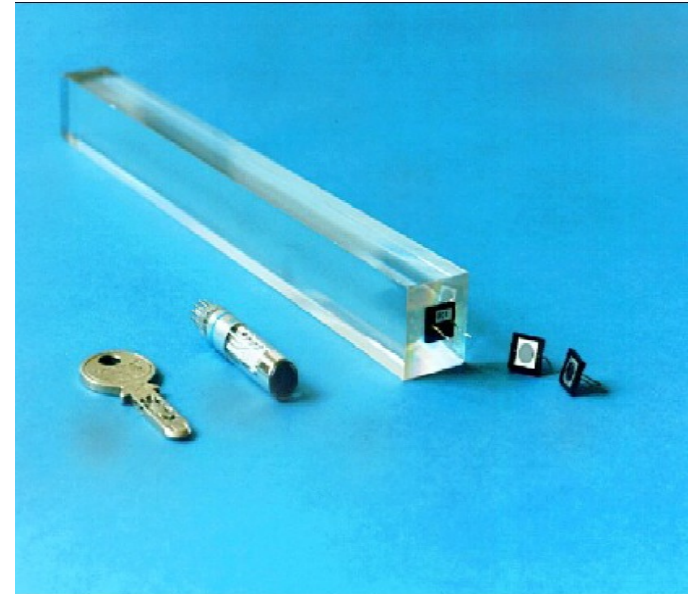




# Crystal calorimeters



Babar(Csl)  
Kloe(Csl)  
CMS (PbWO<sub>4</sub>)  
L3, CLEO, Belle,  
ALICE



Fast  
Best resolution  
Difficult to calibrate  
expensive

# CMS: ECAL Electronics

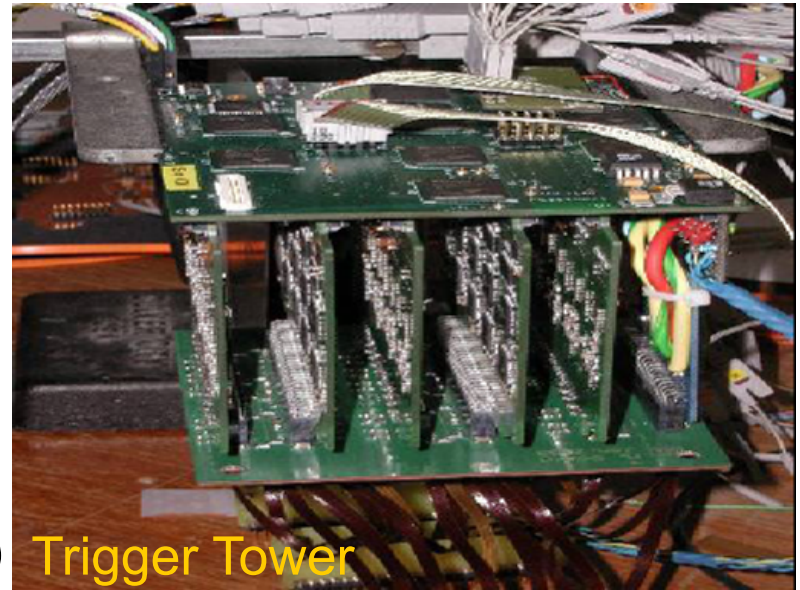
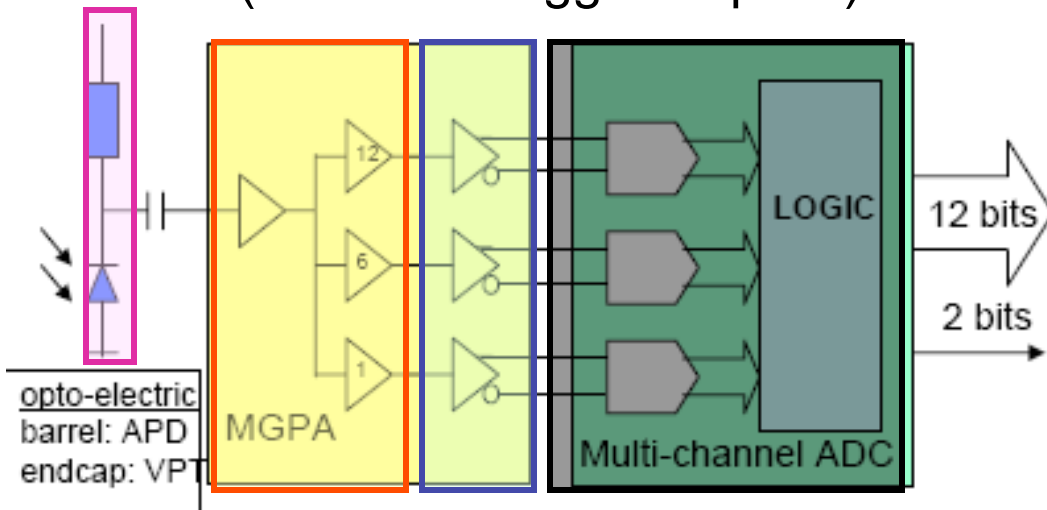
building block :

## Trigger Tower (25 channels)

- 1 mother board
- 1 LV regulator board
- 5 VFE boards (5 channels each)
- 1 FE board

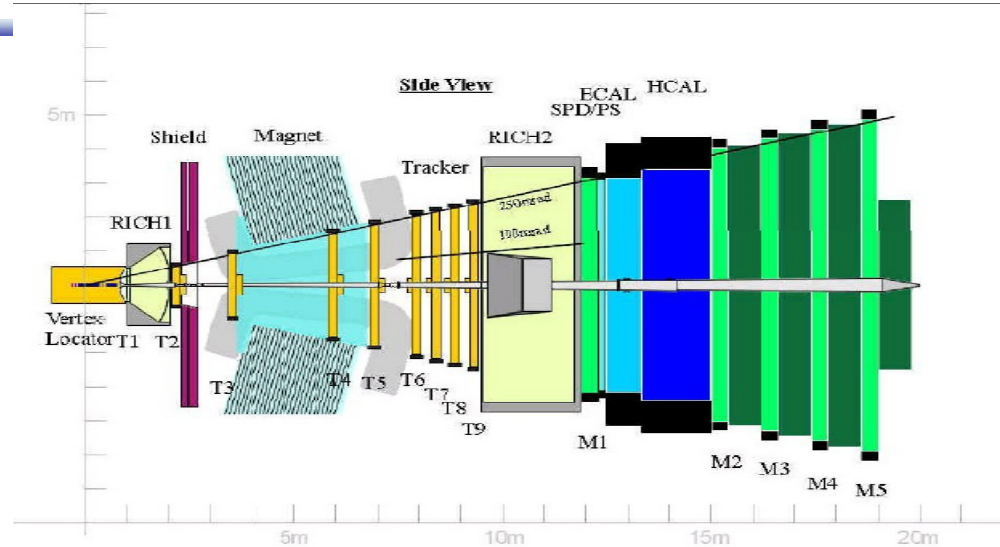
2 fibres per TT sending

- trigger primitives (every beam crossing)
- data (on level 1 trigger request)



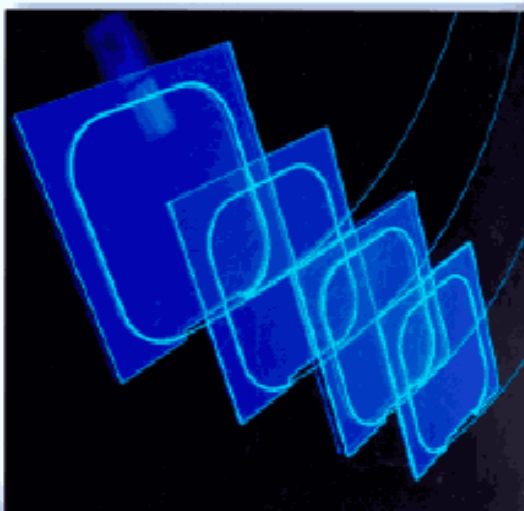


# Scintillating calorimeters



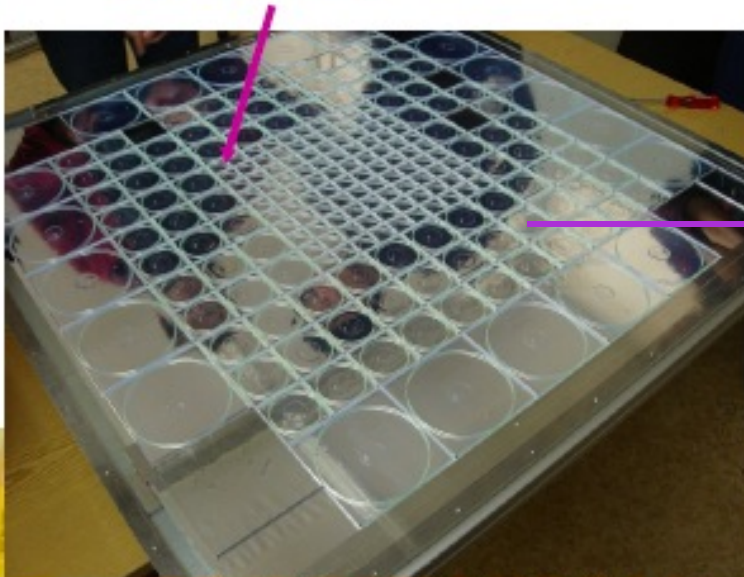
CMS hadronic  
LHCb  
OPERA  
ILC hadronic  
ILC em  
ATLAS hadronic

Fast  
Cheap  
Moderate resolution  
Difficult to calibrate

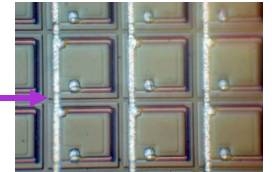
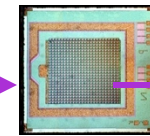
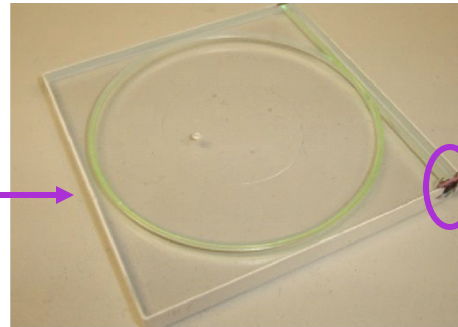


# ILC: hadronic calorimeter (CALICE)

Iron/**plastic(tiles)** sandwich



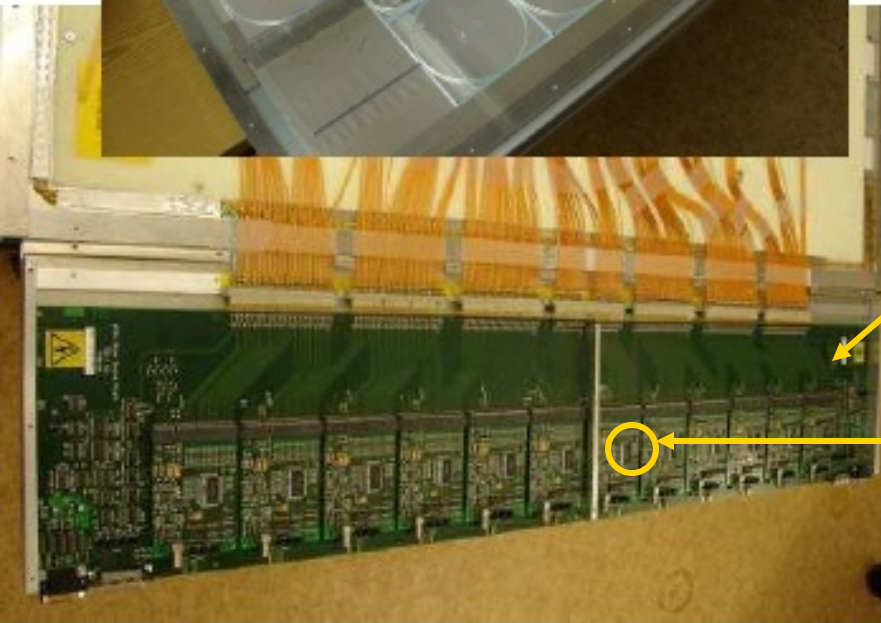
Single tile readout with WLS fiber + SiPM:  
pixel device operated  
in Geiger mode



Read out 216 tiles/module  
38 sampling layers  
~8000 channels

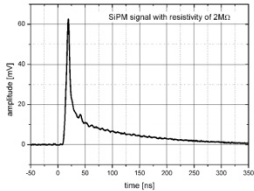
VFE: control board for 12 ASICs / layer  
connect to SiPMs

ASIC: amplification + shaping +  
multiplexing (18 ch.)



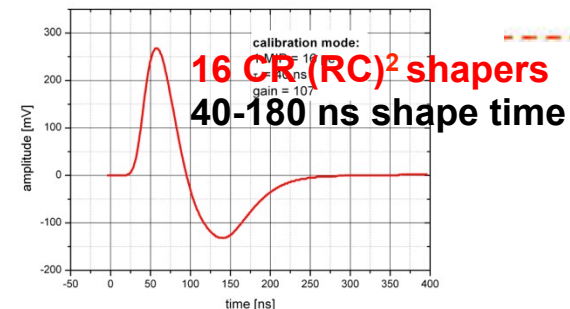
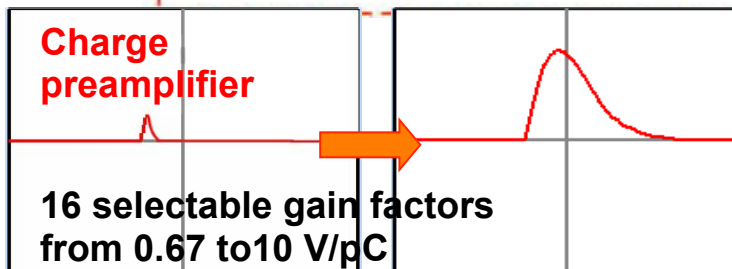
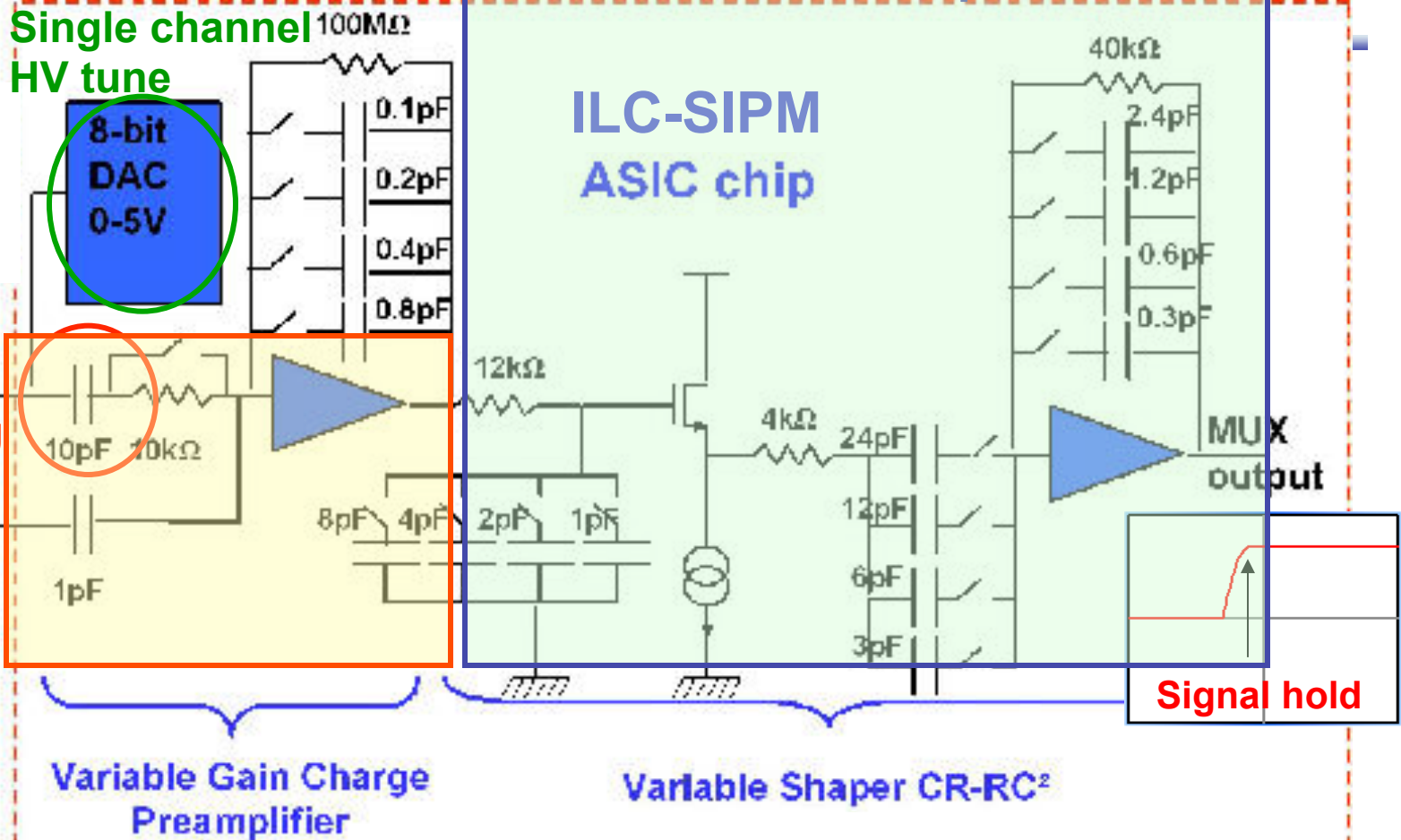
# ILC: HCAL readout chip

Single channel  
HV tune



SiPM input  
decoupling

test Input





# Trends & Future

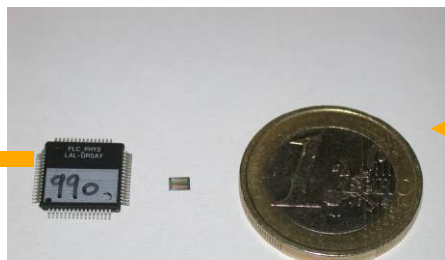
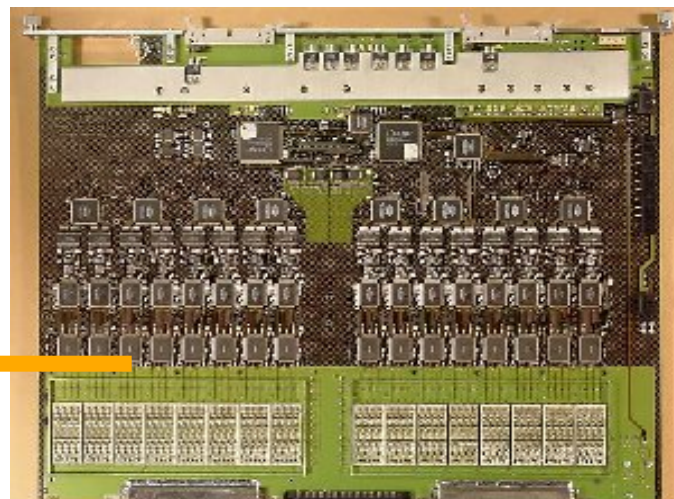
More channels / more functionality in the chip (analog+digital)

→ more integration

Detector imbedded electronics

→ reduce cable volume = dead volume

→ ultra-low power consumption

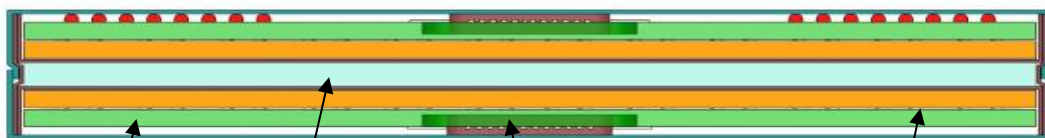
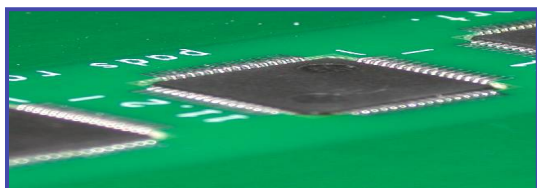


ILC : 100 $\mu$ W/ch

FLC\_PHY3 18ch 10\*10mm 5mW/ch

ATLAS LAr FEB 128ch 400\*500mm 1 W/ch

Readout chip integrated in active layer (Si-W ECAL for ILC)



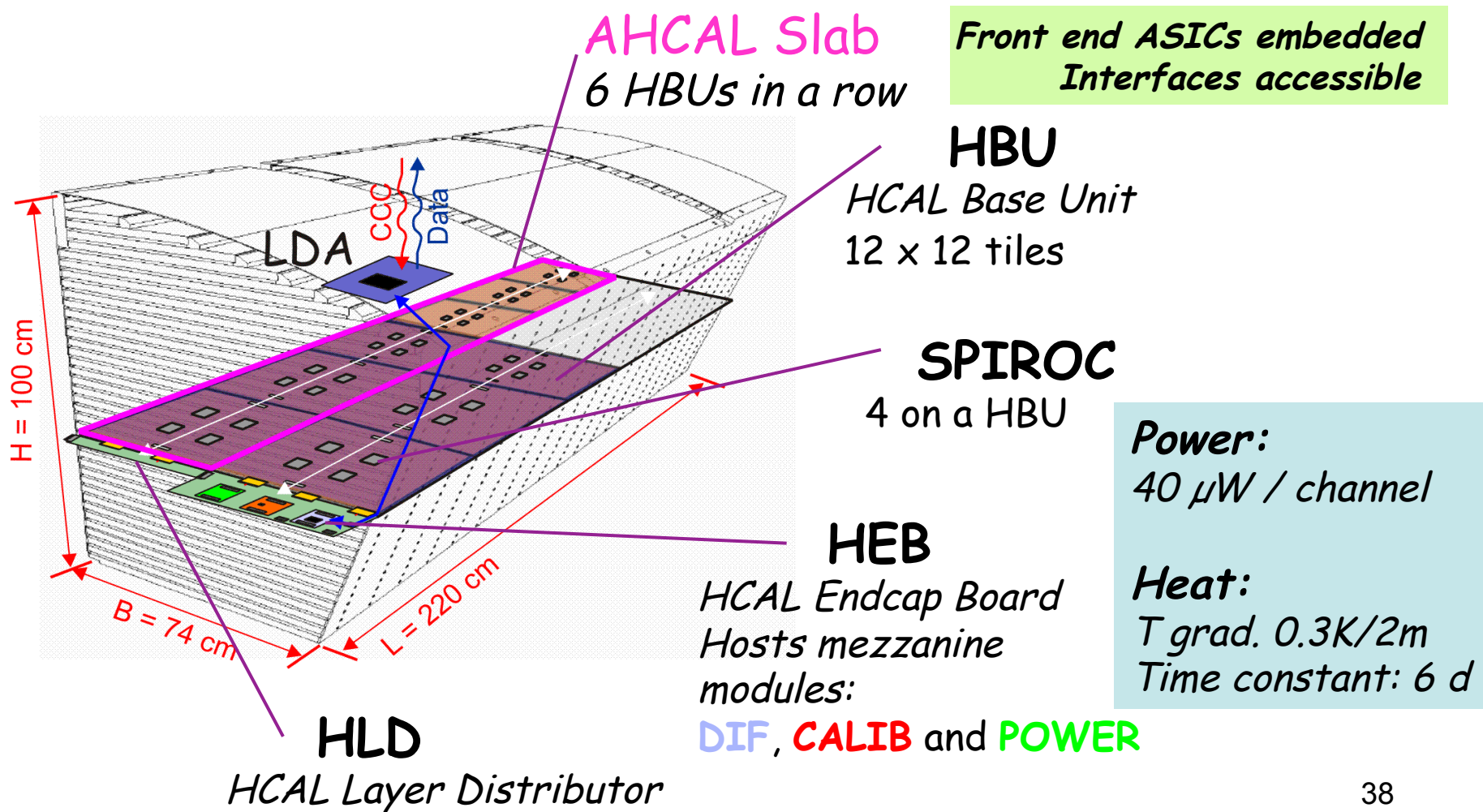
PCB (600 $\mu$ m)

Tungsten (1 mm)

FE chip (1mm)

Wafer (400 $\mu$ m)

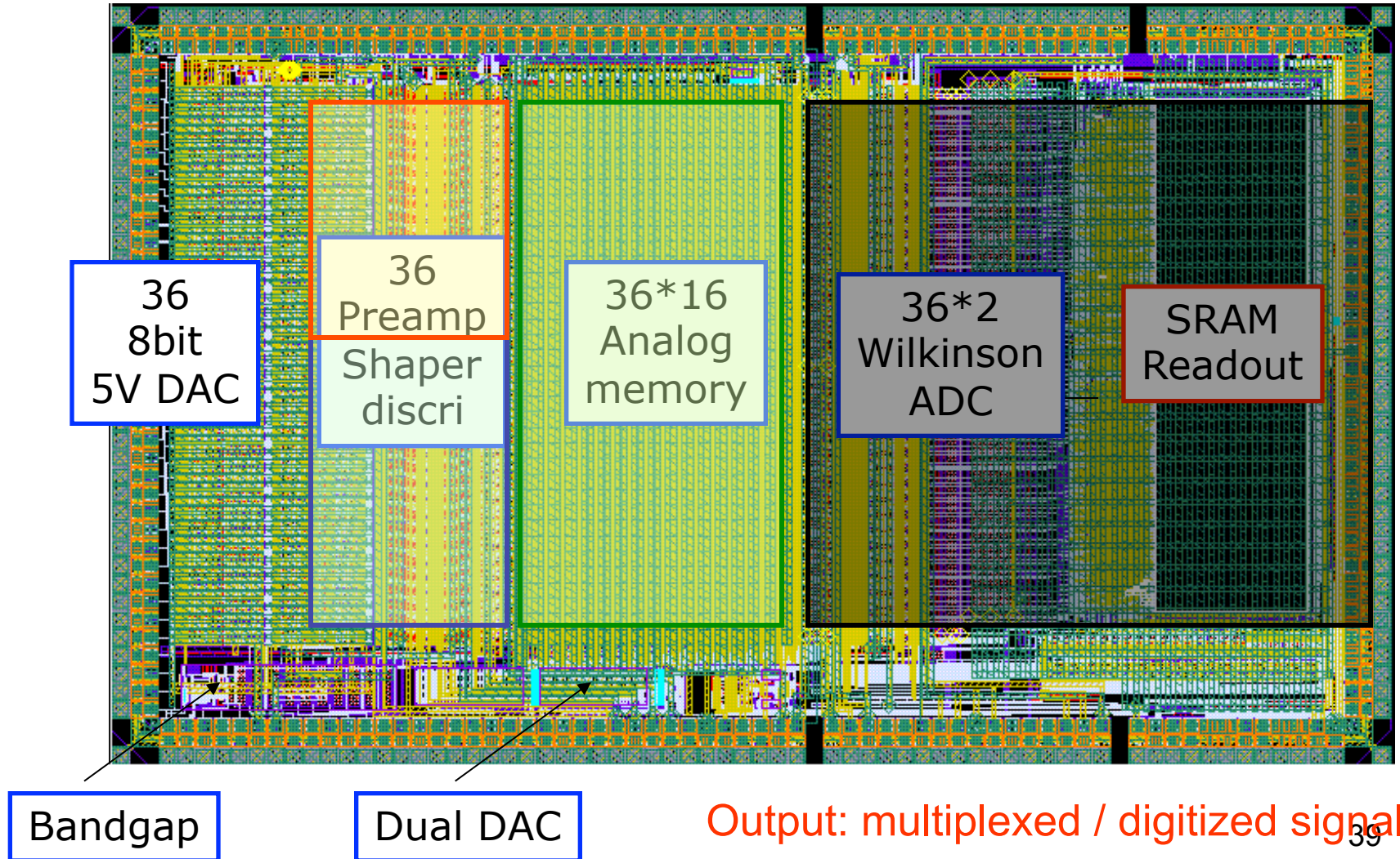
# Imbedded electronics (ILC HCAL)





# More pixels / more functionality

SPIROC layout (CALICE chip for Analog HCAL readout)

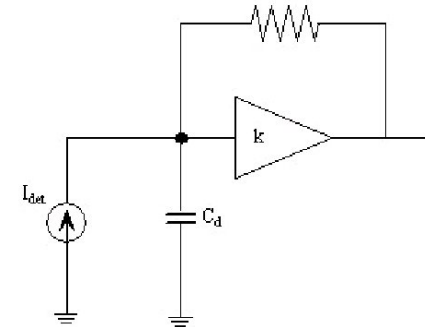


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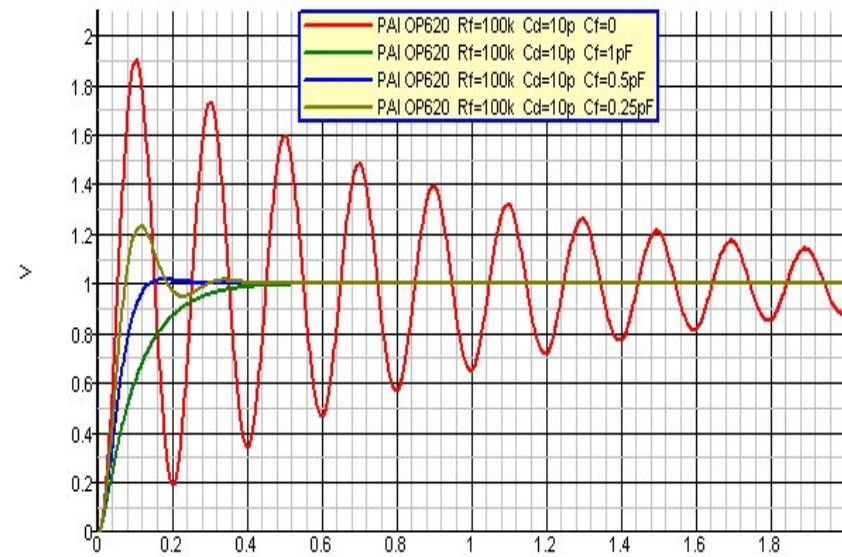
# Support material

# Current preamplifiers

- Transimpedance configuration
  - $V_{out}(\omega)/i_{in}(\omega) = -R_f / (1 + Z_f/GZ_d)$
  - Gain =  $R_f$
  - High counting rate
  - Typically optical link receivers
- Easily oscillatory
  - Unstable with capacitive detector
  - Inductive input impedance
 
$$L_{eq} = R_f / \omega_C$$
  - Resonance at :  $f_{res} = 1/2\pi \sqrt{L_{eq}C_d}$
  - Quality factor :  $Q = R / \sqrt{L_{eq}/C_d}$ 
    - $Q > 1/2 \rightarrow$  ringing
  - Damping with capacitance  $C_f$ 
    - $C_f = 2 \sqrt{(C_d/R_f G_0 \omega_0)}$
    - Easier with fast amplifiers



Current sensitive preamp

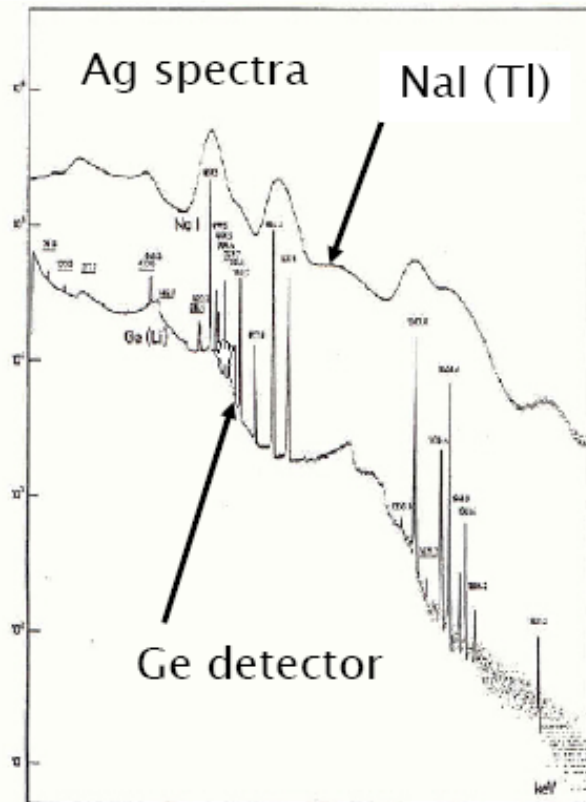


Step response of current sensitive preamp

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# Resolution and noise

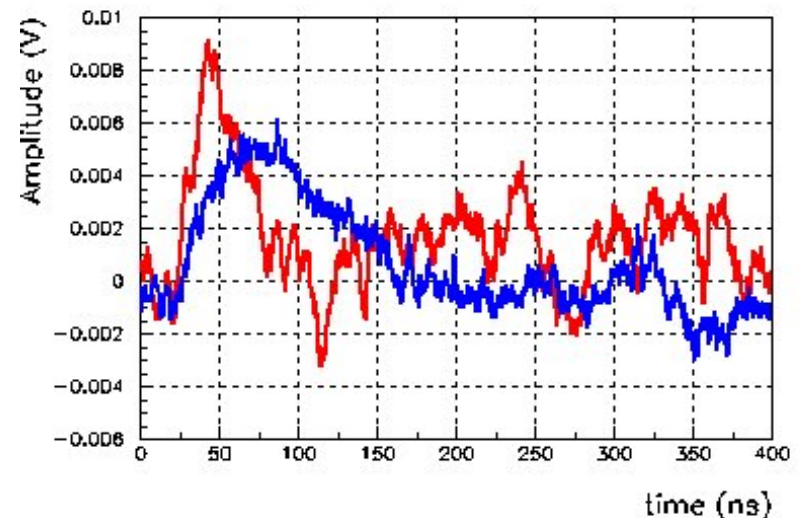
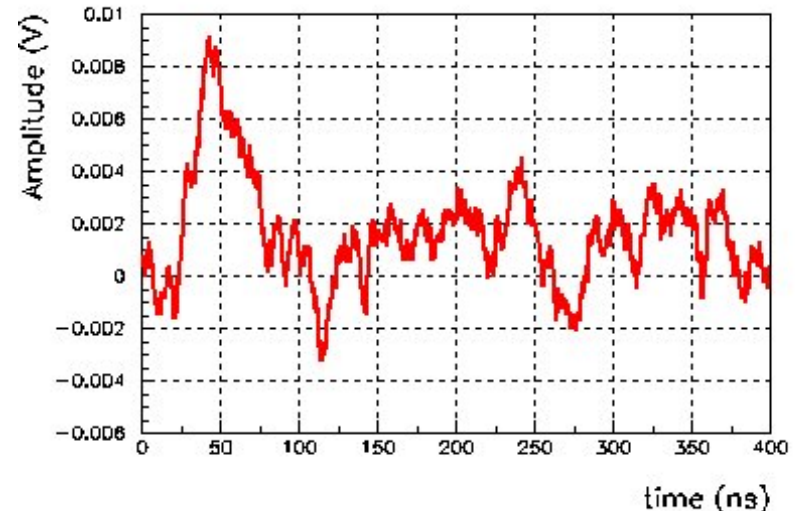
# Why bother about resolution and noise?





# Electronics noise

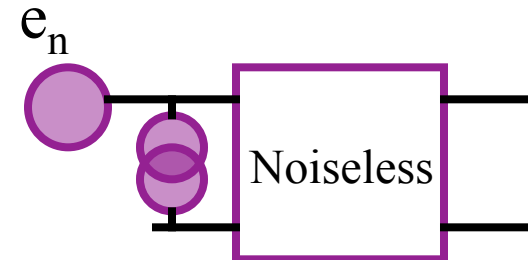
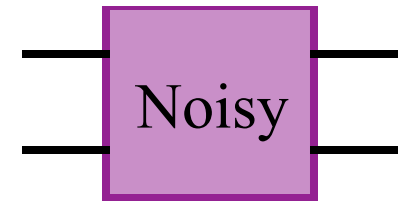
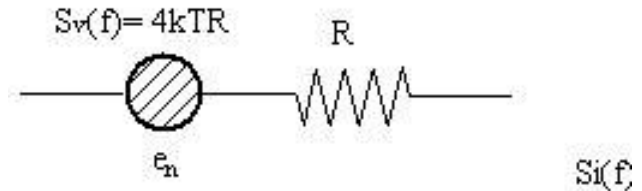
- Definition of Noise
  - Random fluctuation superimposed to interesting signal
  - Statistical treatment
- Three types of noise
  - Fundamental noise (Thermal noise, shot noise)
  - Excess noise ( $1/f$  ...)
  - Parasitic → EMC/EMI (pickup noise, ground loops...)





# Calculating electronics noise

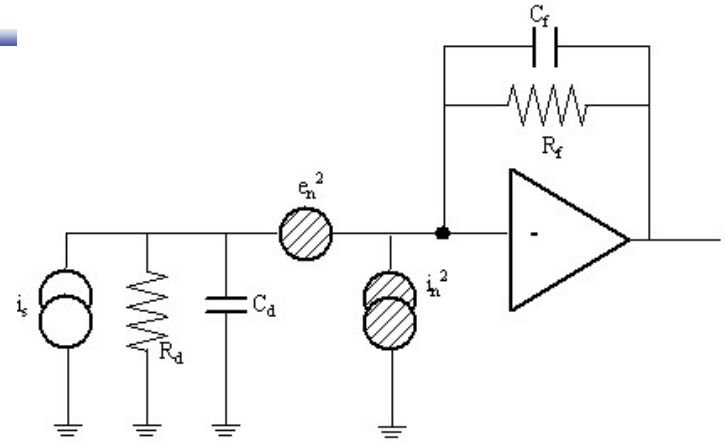
- Fundamental noise
    - Thermal noise (**resistors**) :  $S_v(f) = 4kTR$
    - Shot noise (**junctions**) :  $S_i(f) = 2qI$
  - Noise referred to the input
    - All noise generators can be referred to the input as **2** noise generators :
    - A voltage one  $e_n$  in series : **series noise**
    - A current one  $i_n$  in parallel : **parallel noise**
    - Two generators : no more, no less...
- **To take into account the Source impedance**
- **Golden rule**
- **Always calculate the signal before the noise**  
**what counts is the signal to noise ratio**



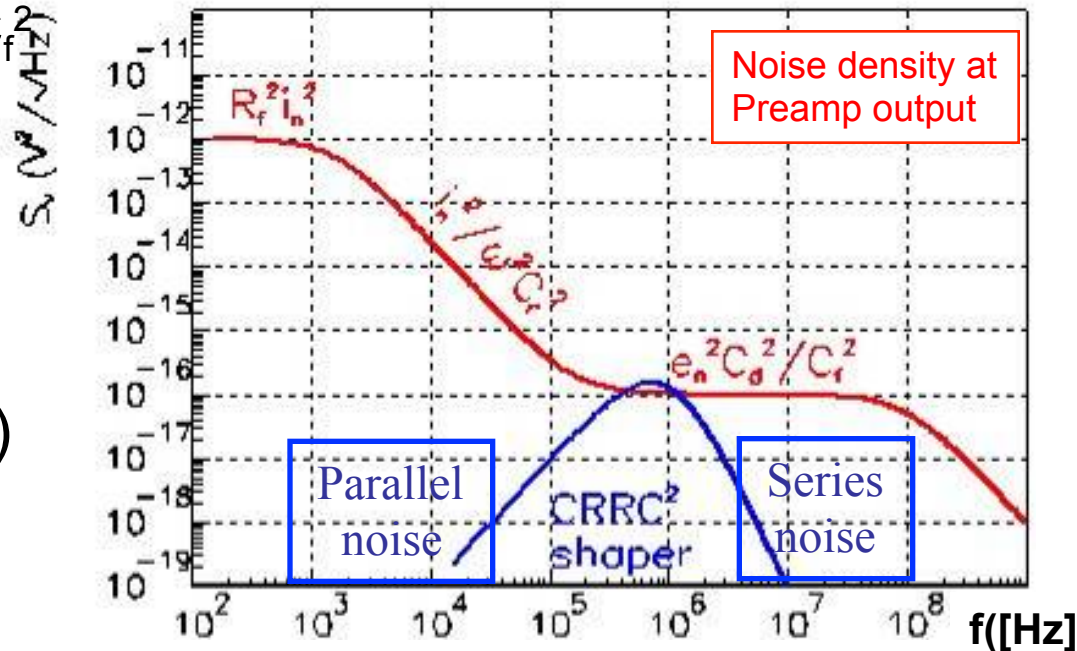
Noise generators  
referred to the input

# Noise in charge pre-amplifiers

- 2 noise generators at the input
  - Parallel noise : ( $i_n^2$ ) (leakage currents)
  - Series noise : ( $e_n^2$ ) (preamp)
- Output noise spectral density :
  - $S_v(\omega) = (i_n^2 + e_n^2/|Z_d|^2) / \omega^2 C_f^2$   
 $= i_n^2 / \omega^2 C_f^2 + e_n^2 C_d^2 / C_f^2$
  - Parallel noise in  $1/\omega^2$
  - Series noise is flat, with a « noise gain » of  $C_d/C_f$
- rms noise  $V_n$ 
  - $V_n^2 = \int S_v(\omega) d\omega / 2\pi \rightarrow \infty$  (!)
  - Benefit of shaping...



Noise generators in charge preamp

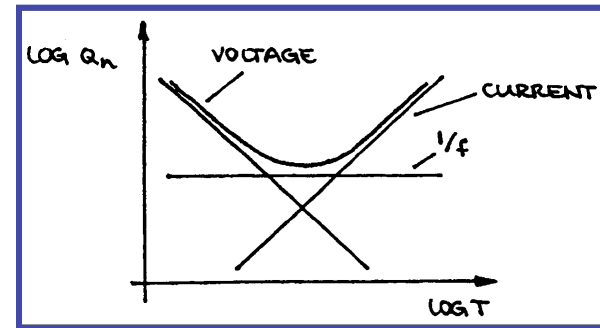


# Equivalent Noise Charge (ENC)

Two basic noise mechanisms: input noise current  $i_n$  [pA/ $\sqrt{\text{Hz}}$ ]  
input noise voltage  $e_n$  [nV/ $\sqrt{\text{Hz}}$ ]

Equivalent Noise Charge:

$$Q_n^2 = \underbrace{i_n^2}_{\text{from Front End}} \underbrace{T_s F_i}_{\text{from Shaper}} + \underbrace{C_i^2 v_n^2}_{\text{from Front End}} \underbrace{\left( \frac{F_v}{T_s} \right)}_{\text{from Shaper}}$$



where  $T_s$  = characteristic shaping time (e.g. peaking time)  
 $F_i, F_e$  "Form Factors" that are determined by the shape of the pulse (calculated in the frequency or time domain)  
 $C_i$  = total capacitance at the input node (detector capacitance + input capacitance of preamplifier + stray capacitance + ... )

➔ Current noise contribution increases with  $T$

➔ Voltage noise contribution decreases with increasing  $T$

only for "white" voltage & current noise sources + capacitive load

"1/f" voltage noise contribution constant in  $T$

# Coherent noise in a multi-channel system

Coherent noise problem :

Noise adds linearly instead of quadratically

Particularly sensitive in calorimetry as sums are performed to reconstruct jets or  $E_t^{\text{miss}}$

$$\sum a_i^2 = n \sigma_{\text{incoh}}^2 + n^2 \sigma_{\text{coh}}^2 \quad (i=\text{channels})$$

Coherent noise **estimation**

Perform **Direct** and **Alternate** sums to extract coherent noise

$$SD^2 = \sum a_i^2$$

$$SA^2 = \sum (-1)^i a_i^2$$

$$SA^2 = n \sigma_{\text{incoh}}^2$$

Incoherent & coherent noise :

$$\sigma_{\text{incoh}}^2 = SA^2/n$$

$$\sigma_{\text{coh}}^2 = (SD^2 - SA^2)/n^2$$

Usually  $\sigma_{\text{coh}} / \sigma_{\text{incoh}} < \sim 20 \%$

Chip 11 - RMS of direct and alternating sums

